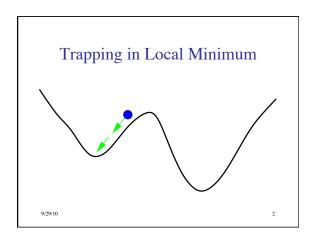
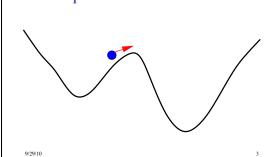
### B. Stochastic Neural Networks

(in particular, the stochastic Hopfield network)

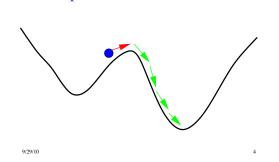
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#### Escape from Local Minimum



#### Escape from Local Minimum

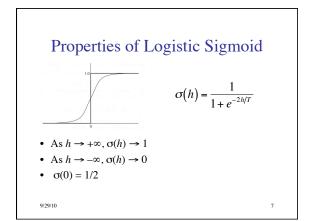


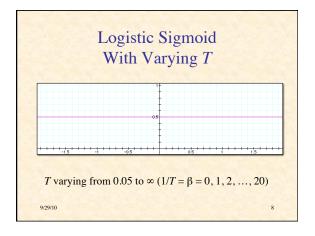
#### Motivation

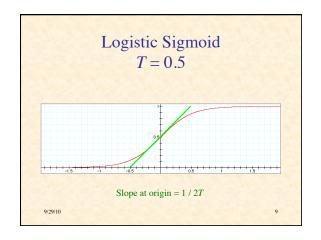
- Idea: with low probability, go against the local
  - move up the energy surface
  - make the "wrong" microdecision
- Potential value for optimization: escape from local optima
- Potential value for associative memory: escape from spurious states
  - because they have higher energy than imprinted states

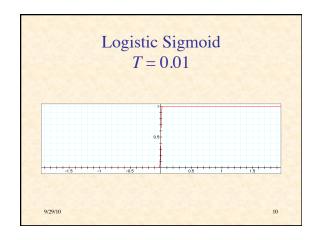
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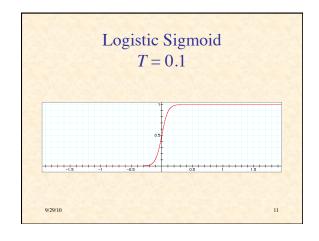
## The Stochastic Neuron Deterministic neuron: $s_i' = \operatorname{sgn}(h_i)$ $\Pr\{s_i' = +1\} = \Theta(h_i)$ $\Pr\{s_i' = -1\} = 1 - \Theta(h_i)$ Stochastic neuron: $\Pr\{s_i' = +1\} = \sigma(h_i)$ $\Pr\{s_i' = -1\} = 1 - \sigma(h_i)$ Logistic sigmoid: $\sigma(h) = \frac{1}{1 + \exp(-2h/T)}$

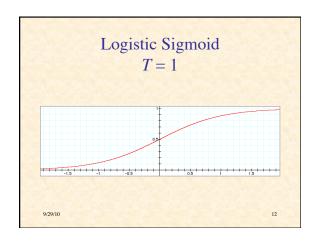


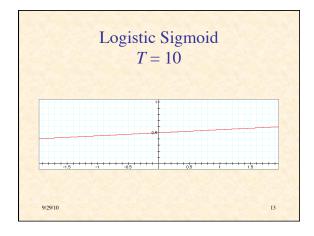


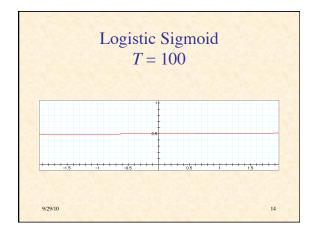












#### Pseudo-Temperature

- Temperature = measure of thermal energy (heat)
- Thermal energy = vibrational energy of molecules
- A source of random motion
- Pseudo-temperature = a measure of nondirected (random) change
- Logistic sigmoid gives same equilibrium probabilities as Boltzmann-Gibbs distribution

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#### **Transition Probability**

Recall, change in energy  $\Delta E = -\Delta s_k h_k$ = 2 s. h.

$$\Pr\{s_k' = \pm 1 | s_k = \mp 1\} = \sigma(\pm h_k) = \sigma(-s_k h_k)$$

$$\Pr\{s_k \to -s_k\} = \frac{1}{1 + \exp(2s_k h_k/T)}$$
$$= \frac{1}{1 + \exp(\Delta E/T)}$$

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#### Stability

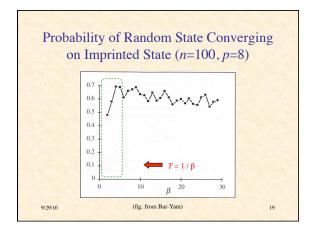
- Are stochastic Hopfield nets stable?
- Thermal noise prevents absolute stability
- But with symmetric weights: average values  $\langle s_i \rangle$  become time - invariant

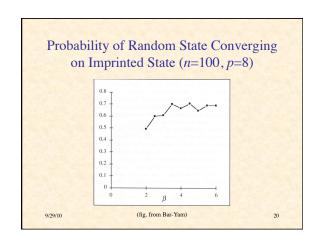
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## Does "Thermal Noise" Improve Memory Performance?

- Experiments by Bar-Yam (pp. 316-20):
  - *n* = 100
  - p = 8
- · Random initial state
- To allow convergence, after 20 cycles set T = 0
- How often does it converge to an imprinted pattern?

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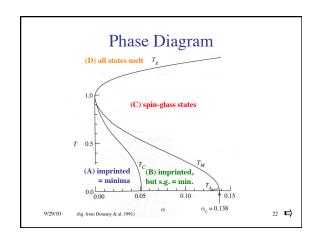


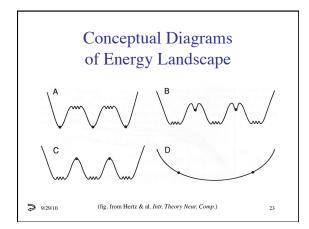


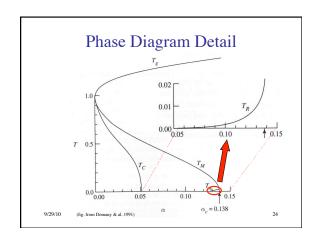
#### Analysis of Stochastic Hopfield Network

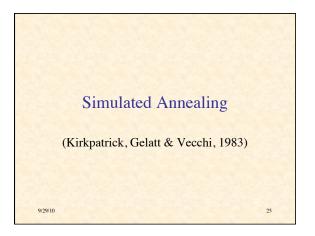
- Complete analysis by Daniel J. Amit & colleagues in mid-80s
- See D. J. Amit, *Modeling Brain Function:* The World of Attractor Neural Networks, Cambridge Univ. Press, 1989.
- The analysis is beyond the scope of this course

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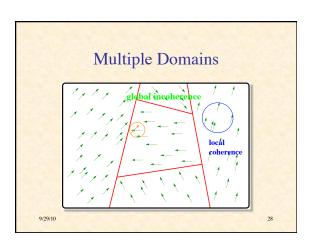


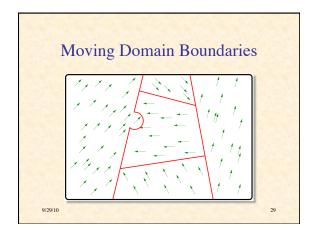


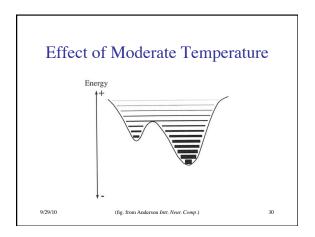
#### Dilemma

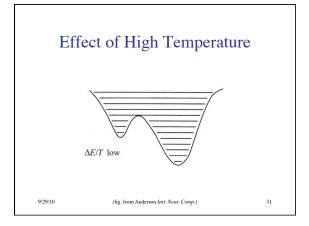
- In the early stages of search, we want a high temperature, so that we will explore the space and find the basins of the global minimum
- In the later stages we want a low temperature, so that we will relax into the global minimum and not wander away from it
- Solution: decrease the temperature gradually during search

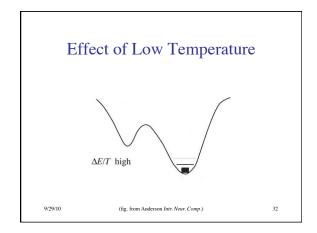
## Quenching vs. Annealing • Quenching: - rapid cooling of a hot material - may result in defects & brittleness - local order but global disorder - locally low-energy, globally frustrated • Annealing: - slow cooling (or alternate heating & cooling) - reaches equilibrium at each temperature - allows global order to emerge - achieves global low-energy state











#### **Annealing Schedule**

- Controlled decrease of temperature
- Should be sufficiently slow to allow equilibrium to be reached at each temperature
- With sufficiently slow annealing, the global minimum will be found with probability 1
- · Design of schedules is a topic of research

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### Typical Practical Annealing Schedule

- Initial temperature T<sub>0</sub> sufficiently high so all transitions allowed
- Exponential cooling:  $T_{k+1} = \alpha T_k$ 
  - typical  $0.8 < \alpha < 0.99$
  - at least 10 accepted transitions at each temp.
- Final temperature: three successive temperatures without required number of accepted transitions

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#### Summary

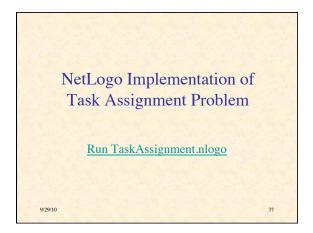
- Non-directed change (random motion) permits escape from local optima and spurious states
- Pseudo-temperature can be controlled to adjust relative degree of exploration and exploitation

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#### Hopfield Network for Task Assignment Problem

- Six tasks to be done (I, II, ..., VI)
- Six agents to do tasks (A, B, ..., F)
- They can do tasks at various rates
  - A (10, 5, 4, 6, 5, 1)
  - B (6, 4, 9, 7, 3, 2)
- eic
- What is the optimal assignment of tasks to agents?

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# Additional Bibliography 1. Anderson, J.A. An Introduction to Neural Networks, MIT, 1995. 2. Arbib, M. (ed.) Handbook of Brain Theory & Neural Networks, MIT, 1995. 3. Hertz, J., Krogh, A., & Palmer, R. G. Introduction to the Theory of Neural Computation, Addison-Wesley, 1991.