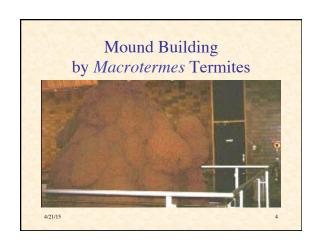
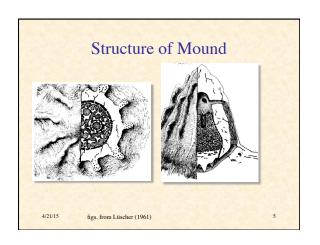
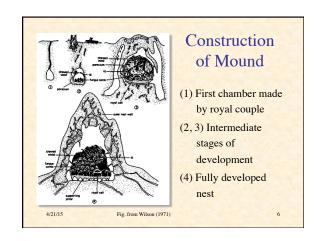
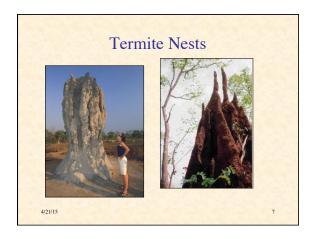


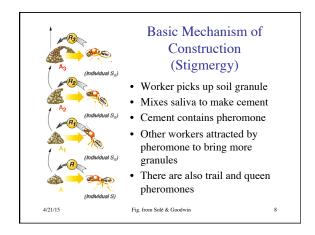
Nest Building by Termites
(Natural and Artificial)

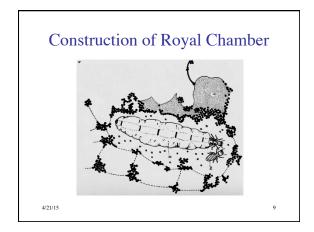


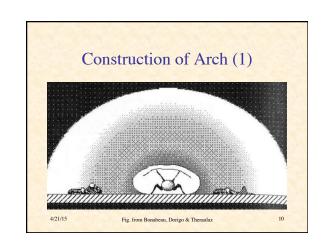


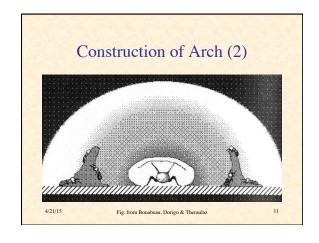


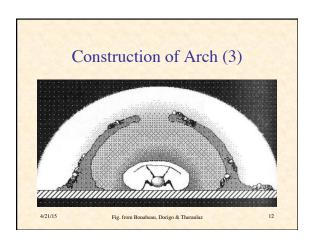












Basic Principles

- Continuous (quantitative) stigmergy
- · Positive feedback:
 - via pheromone deposition
- Negative feedback:
 - depletion of soil granules & competition between pillars
 - pheromone decay

13

Deneubourg Model

- H(r,t) = concentration of cement pheromone in air at location r & time t
- P(r, t) = amount of deposited cement with still active pheromone at r, t
- C(r, t) = density of laden termites at r, t
- Φ = constant flow of laden termites into system

/15

Equation for *P* (Deposited Cement with Pheromone)

 $\partial_t P$ (rate of change of active cement) = $k_1 C$ (rate of cement deposition by termites) $-k_2 P$ (rate of pheromone loss to air)

$$\partial_t P = k_1 C - k_2 P$$

4/21/15

Equation for *H* (Concentration of Pheromone)

 $\partial_t H$ (rate of change of concentration) = $k_2 P$ (pheromone from deposited material)

 $-k_4H$ (pheromone decay)

+ $D_H \nabla^2 H$ (pheromone diffusion)

$$\partial_t H = k_2 P - k_4 H + D_H \nabla^2 H$$

4/21/1

16

Equation for C (Density of Laden Termites)

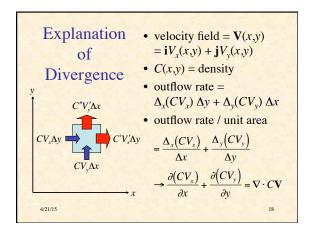
 $\partial_t C$ (rate of change of concentration) =

- Φ (flux of laden termites)
- $-k_1 C$ (unloading of termites)
- + $D_C \nabla^2 C$ (random walk)
- $-\gamma \nabla \cdot (C\nabla H)$ (chemotaxis: response to pheromone gradient)

$$\partial_t C = \Phi - k_1 C + D_C \nabla^2 C - \gamma \nabla \cdot (C \nabla H)$$

4/21/15

17



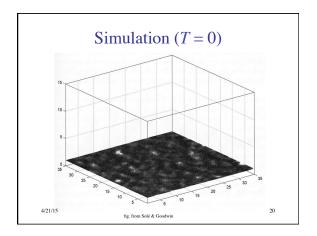
Part 6C: Nest Building

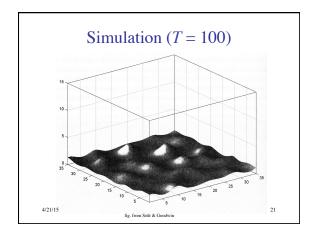
Explanation of Chemotaxis Term

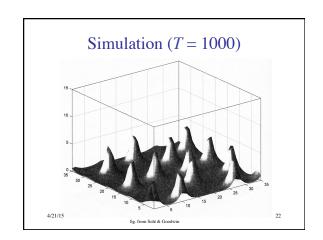
- The termite flow *into* a region is the *negative* divergence of the flux through it
 ∇ · J = -(∂J_x / ∂x + ∂J_y / ∂y)
- The flux velocity is proportional to the pheromone gradient
 - $\mathbf{J} \propto \nabla H$
- The flux density is proportional to the number of moving termites
 - $\mathbf{J} \propto C$
- Hence, $-\gamma \nabla \cdot \mathbf{J} = -\gamma \nabla \cdot (C \nabla H)$

4/21/15

19







Conditions for Self-Organized Pillars

- Will not produce regularly spaced pillars if:
 - density of termites is too low
 - rate of deposition is too low
- A homogeneous stable state results

$$C_0 = \frac{\Phi}{k_1}, \qquad H_0 = \frac{\Phi}{k_4}, \qquad P_0 = \frac{\Phi}{k_2}$$

4/21/15

NetLogo Simulation of Deneubourg Model

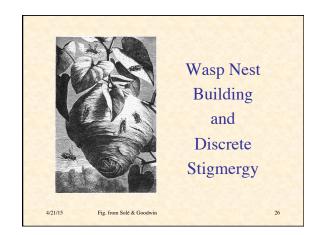
Run Pillars3D.nlogo

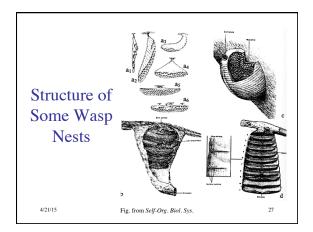
Interaction of Three Pheromones

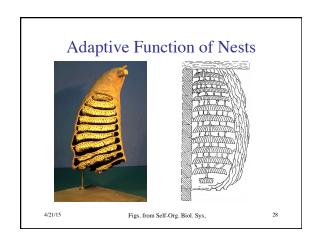
- Queen pheromone governs size and shape of queen chamber (template)
- Cement pheromone governs construction and spacing of pillars & arches (stigmergy)
- Trail pheromone:
 - attracts workers to construction sites (stigmergy)
 - encourages soil pickup (stigmergy)
 - governs sizes of galleries (template)

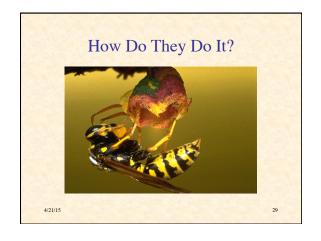
4/21/15

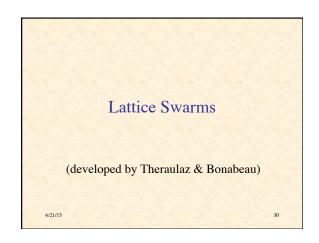
25







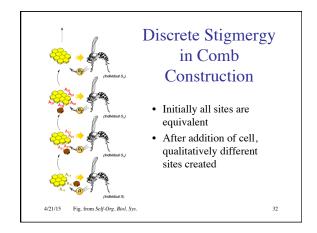


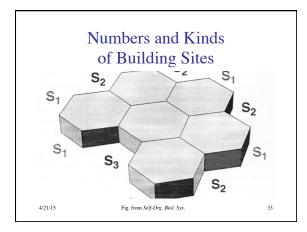


Discrete vs. Continuous Stigmergy

- Recall: stigmergy is the coordination of activities through the environment
- Continuous or quantitative stigmergy
- quantitatively different stimuli trigger quantitatively different behaviors
- Discrete or qualitative stigmergy
 - stimuli are classified into distinct classes, which trigger distinct behaviors

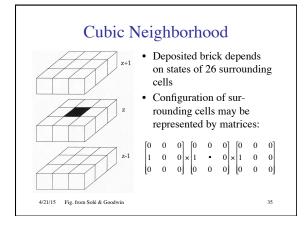
W21/15 3

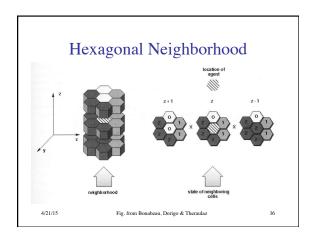


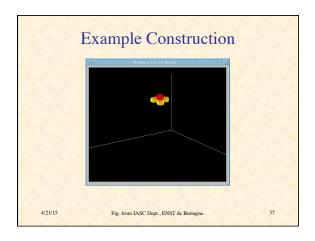


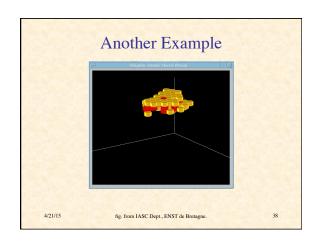
Lattice Swarm Model

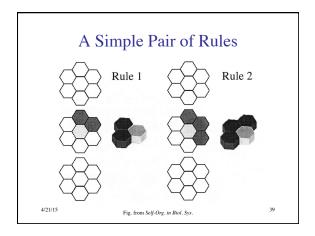
- Random movement by wasps in a 3D lattice
 cubic or hexagonal
- Wasps obey a 3D CA-like rule set
- Depending on configuration, wasp deposits one of several types of "bricks"
- Once deposited, it cannot be removed
- May be deterministic or probabilistic
- Start with a single brick

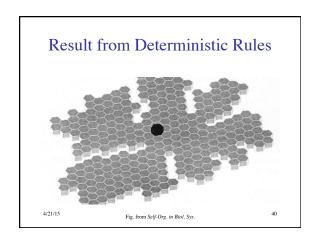


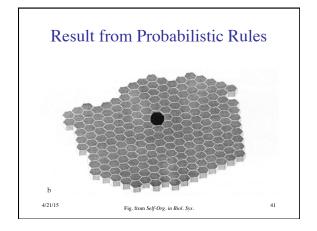


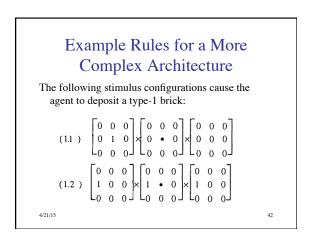


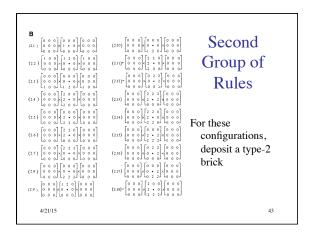


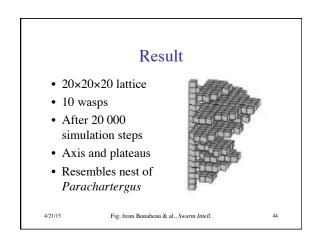


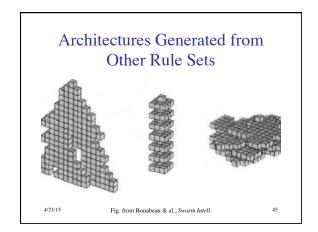


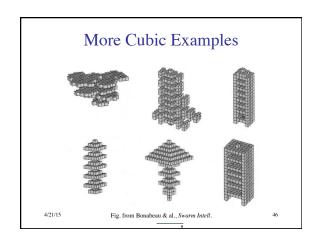


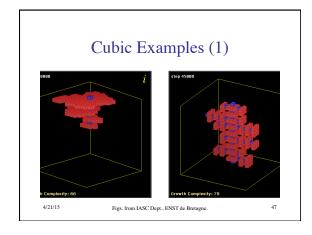


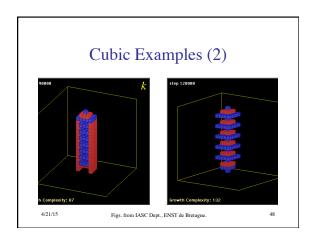


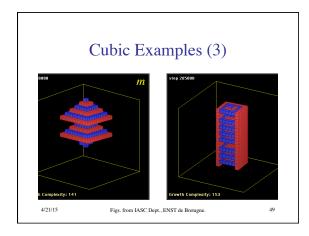


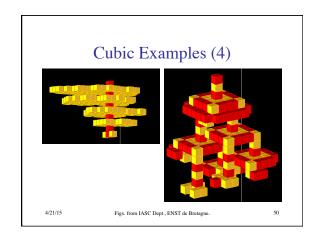


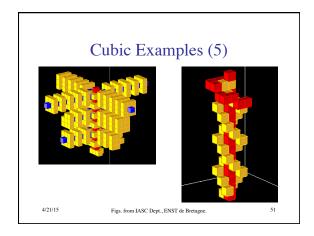


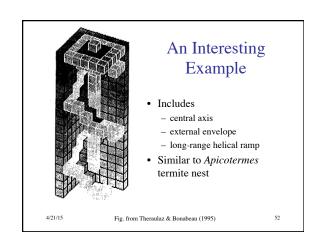


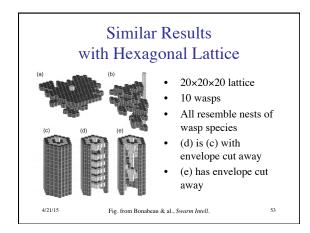


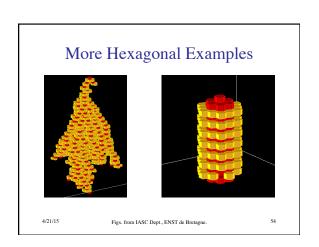


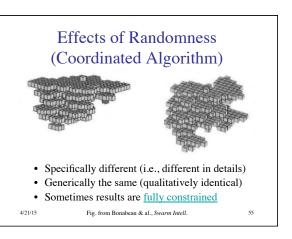


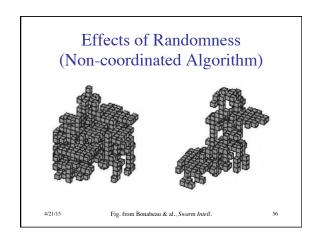












Non-coordinated Algorithms

- Stimulating configurations are not ordered in time and space
- Many of them overlap
- · Architecture grows without any coherence
- May be convergent, but are still unstructured

4/21/15 57

Coordinated Algorithm

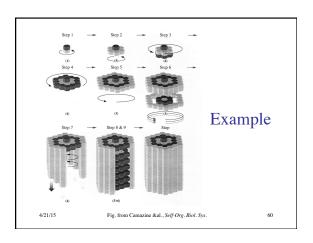
- Non-conflicting rules
 - can't prescribe two different actions for the same configuration
- Stimulating configurations for different building stages cannot overlap
- At each stage, "handshakes" and "interlocks" are required to prevent conflicts in parallel assembly

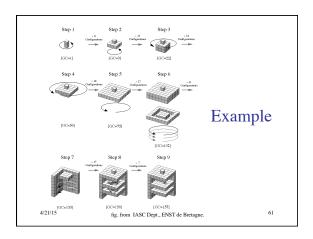
58

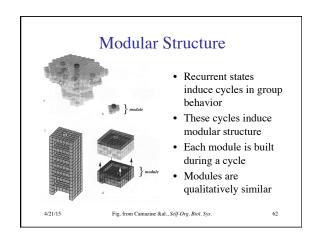
More Formally...

- Let $C = \{c_1, c_2, ..., c_n\}$ be the set of local stimulating configurations
- Let $(S_1, S_2, ..., S_m)$ be a sequence of assembly stages
- These stages partition C into mutually disjoint subsets C(S_n)
- Completion of S_p signaled by appearance of a configuration in C(S_{p+1})

21/15 59







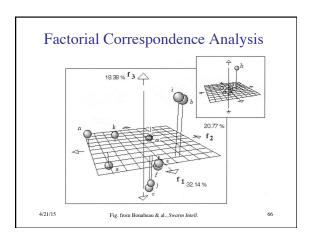
Possible Termination Mechanisms Qualitative - the assembly process leads to a configuration that is not · Quantitative

- a separate rule inhibiting building when nest a certain size relative to population
- "empty cells rule": make new cells only when no empties available
- growing nest may inhibit positive feedback mechanisms

Observations

- · Random algorithms tend to lead to uninteresting structures
 - random or space-filling shapes
- Similar structured architectures tend to be generated by similar coordinated algorithms
- · Algorithms that generate structured architectures seem to be confined to a small region of rule-space

Analysis • Define matrix M: • 12 columns for 12 sample structured architectures • 211 rows for stimulating configurations • $M_{ij} = 1$ if architecture j requires configuration i Fig. from Bonabeau & al., Swarm Intell.



Conclusions

- Simple rules that exploit discrete (qualitative) stigmergy can be used by autonomous agents to assemble complex, 3D structures
- The rules must be non-conflicting and coordinated according to stage of assembly
- The rules corresponding to interesting structures occupy a comparatively small region in rule-space

4/21/15



Additional Bibliography

- Camazine, S., Deneubourg, J.-L., Franks, N. R., Sneyd, J., Theraulaz, G., & Bonabeau, E. Self-Organization in Biological Systems. Princeton, 2001, chs. 11, 13, 18, 19.
- Bonabeau, E., Dorigo, M., & Theraulaz, G. Swarm Intelligence: From Natural to Artificial Systems. Oxford, 1999, chs. 2, 6.
- Solé, R., & Goodwin, B. Signs of Life: How Complexity Pervades Biology. Basic Books, 2000, ch. 6.
- Resnick, M. Turtles, Termites, and Traffic Jams: Explorations in Massively Parallel Microworlds. MIT Press, 1994, pp. 59-68, 75-81.
- Kennedy, J., & Eberhart, R. "Particle Swarm Optimization," Proc. IEEE Int'l. Conf. Neural Networks (Perth, Australia), 1995. http://www.engr.iupui.edu/~shi/pso.html.

1/21/15

