# VI Autonomous Agents & Self-Organization



# Nest Building

#### Autonomous Agent

- "a unit that interacts with its environment (which probably consists of other agents)
- but acts independently from all other agents in that it does not take commands from some seen or unseen leader,
- nor does an agent have some idea of a global plan that it should be following." —Flake (p. 261)

# Nest Building by Termites (Natural and Artificial)

Resnick's Termites ("Turmites")

## Basic procedure

- Wander randomly
- If you are not carrying anything and you bump into a wood chip, pick it up.
- If you are carrying a wood chip and you bump into another wood chip, put down the woodchip you are carrying

- Resnick, Turtles, Termites, and Traffic Jams

### Microbehavior of Turmites

- 1. Search for wood chip:
  - a) If at chip, pick it up
  - b) otherwise wiggle, and go back to (a)
- 2. Find a wood pile:
  - a) If at chip, it's found
  - b) otherwise wiggle, and go back to (a)
- 3. Find an empty spot and put chip down:
  - a) If at empty spot, put chip down & jump away
  - b) otherwise, turn, take a step, and go to (a)

## Demonstration

Run Termites.nlogo

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### Decrease in Number of Piles



# Why does the number of piles decrease?

- A pile can grow or shrink
- But once the last chip is taken from a pile, it can never restart
- Is there any way the number of piles can increase?
- Yes, and existing pile can be broken into two

# More Termites

Termites	2000 steps		10 000 steps		
	num. piles	avg. size	num. piles	avg. size	chips in piles
1000	102	15	47	30	
4000	10		3	80	240

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#### **Termite-Mediated Condensation**

- Number of chips is conserved
- Chips do not move on own; movement is mediated by termites
- Chips preferentially condense into piles
- Increasing termites, increases number of chips in fluid (randomly moving) state
- Like temperature

# An Experiment to Make the Number Decrease More Quickly

- Problem: piles may grow or shrink
- Idea: protect "investment" in large piles
- Termites will not take chips from piles greater than a certain size
- Result: number decreases more quickly
- Most chips are in piles
- But never got less than 82 piles

## Conclusion

- In the long run, the "dumber" strategy is better
- Although it's slower, it achieves a better result
- By not protecting large piles, there is a small probability of any pile evaporating
- So the smaller "large piles" can evaporate and contribute to the larger "large piles"
- Even though this strategy makes occasional backward steps, it outperforms the attempt to protect accomplishments

# Mound Building by *Macrotermes* Termites



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## Structure of Mound





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figs. from Lüscher (1961)



Construction of Mound

(1) First chamber made by royal couple
(2, 3) Intermediate
stages of
development
(4) Fully developed
nest

## **Termite Nests**





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## Alternatives to Self-Organization

- Leader
  - directs building activity of group
- Blueprint (image of completion)
  - compact representation of spatial/temporal relationships of parts
- Recipe (program)
  - sequential instructions specify spatial/temporal actions of individual
- Template
  - full-sized guide or mold that specifies final pattern



Basic Mechanism of Construction (Stigmergy)

- Worker picks up soil granule
- Mixes saliva to make cement
- Cement contains pheromone
- Other workers attracted by pheromone to bring more granules
- There are also trail and queen pheromones

## **Construction of Royal Chamber**



# Construction of Arch (1)



Fig. from Bonabeau, Dorigo & Theraulaz

# Construction of Arch (2)



Fig. from Bonabeau, Dorigo & Theraulaz

# Construction of Arch (3)



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Fig. from Bonabeau, Dorigo & Theraulaz

## **Basic Principles**

- Continuous (quantitative) stigmergy
- Positive feedback:
  - via pheromone deposition
- Negative feedback:
  - depletion of soil granules & competition between pillars
  - pheromone decay

#### Deneubourg Model

- *H*(*r*, *t*) = concentration of cement pheromone in air at location *r* & time *t*
- *P*(*r*, *t*) = amount of deposited cement with still active pheromone at *r*, *t*
- C(r, t) = density of laden termites at r, t
- $\Phi = \text{constant}$  flow of laden termites into system

#### Equation for *P* (Deposited Cement with Pheromone)

 $\partial_t P$  (rate of change of active cement) =  $k_1 C$  (rate of cement deposition by termites)  $-k_2 P$  (rate of pheromone loss to air)

$$\partial_t P = k_1 C - k_2 P$$

#### Equation for *H* (Concentration of Pheromone)

 $\partial_t H$  (rate of change of concentration) =  $k_2 P$  (pheromone from deposited material)  $- k_4 H$  (pheromone decay)  $+ D_H \nabla^2 H$  (pheromone diffusion)

 $\partial_t H = k_2 P - k_4 H + D_H \nabla^2 H$ 

# Equation for *C* (Density of Laden Termites)

- $\partial_t C$  (rate of change of concentration) =  $\Phi$  (flux of laden termites)  $-k_1 C$  (unloading of termites)  $+ D_C \nabla^2 C$  (random walk)
- $-\gamma \nabla \cdot (C \nabla H)$  (chemotaxis: response to pheromone gradient)

$$\partial_t C = \Phi - k_1 C + D_C \nabla^2 C - \gamma \nabla \cdot (C \nabla H)$$

Explanation of Divergence



- velocity field =  $\mathbf{V}(x,y)$ =  $\mathbf{i}V_x(x,y) + \mathbf{j}V_y(x,y)$
- C(x,y) =density
- outflow rate =  $\Delta_x(CV_x) \Delta y + \Delta_y(CV_y) \Delta x$
- outflow rate / unit area



y

## Explanation of Chemotaxis Term

• The termite flow *into* a region is the *negative* divergence of the flux through it

 $-\nabla \cdot \mathbf{J} = -\left(\frac{\partial J_x}{\partial x} + \frac{\partial J_y}{\partial y}\right)$ 

- The flux velocity is proportional to the pheromone gradient
   J ∝ ∇H
- The flux density is proportional to the number of moving termites
   J ∝ C
- Hence,  $-\gamma \nabla \cdot \mathbf{J} = -\gamma \nabla \cdot (C \nabla H)$

# Simulation (T = 0)



fig. from Solé & Goodwin

## Simulation (T = 100)



fig. from Solé & Goodwin

## Simulation (T = 1000)



fig. from Solé & Goodwin

# Conditions for Self-Organized Pillars

- Will not produce regularly spaced pillars if:
  - density of termites is too low
  - rate of deposition is too low
- A homogeneous stable state results

$$C_0 = \frac{\Phi}{k_1}, \qquad H_0 = \frac{\Phi}{k_4}, \qquad P_0 = \frac{\Phi}{k_2}$$

# NetLogo Simulation of Deneubourg Model

Run Pillars3D.nlogo

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#### Interaction of Three Pheromones

- Queen pheromone governs size and shape of queen chamber (template)
- Cement pheromone governs construction and spacing of pillars & arches (stigmergy)
- Trail pheromone:
  - attracts workers to construction sites (stigmergy)
  - encourages soil pickup (stigmergy)
  - governs sizes of galleries (template)



Wasp Nest Building and Discrete Stigmergy

Fig. from Solé & Goodwin

# Structure of Some Wasp Nests



Fig. from Self-Org. Biol. Sys.

#### Adaptive Function of Nests



Figs. from Self-Org. Biol. Sys,

### How Do They Do It?



#### Lattice Swarms

#### (developed by Theraulaz & Bonabeau)

# Discrete vs. Continuous Stigmergy

- Recall: *stigmergy* is the coordination of activities through the environment
- Continuous or quantitative stigmergy
  - quantitatively different stimuli trigger quantitatively different behaviors
- Discrete or qualitative stigmergy
  - stimuli are classified into distinct classes, which trigger distinct behaviors



Discrete Stigmergy in Comb Construction

- Initially all sites are equivalent
- After addition of cell, qualitatively different sites created

11/4/08 Fig. from *Self-Org. Biol. Sys.* 

# Numbers and Kinds of Building Sites



Fig. from Self-Org. Biol. Sys.

#### Lattice Swarm Model

- Random movement by wasps in a 3D lattice
  cubic or hexagonal
- Wasps obey a 3D CA-like rule set
- Depending on configuration, wasp deposits one of several types of "bricks"
- Once deposited, it cannot be removed
- May be deterministic or probabilistic
- Start with a single brick

#### Cubic Neighborhood



- Deposited brick depends on states of 26 surrounding cells
- Configuration of surrounding cells may be represented by matrices:

$$\begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 1 & \bullet & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

11/4/08 Fig. from Solé & Goodwin

#### Hexagonal Neighborhood



Fig. from Bonabeau, Dorigo & Theraulaz

### **Example Construction**



Fig. from IASC Dept., ENST de Bretagne.

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#### Another Example



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#### fig. from IASC Dept., ENST de Bretagne.

#### A Simple Pair of Rules



Fig. from Self-Org. in Biol. Sys.

### Result from Deterministic Rules



#### Result from Probabilistic Rules



Fig. from Self-Org. in Biol. Sys.

# Example Rules for a More Complex Architecture

The following stimulus configurations cause the agent to deposit a type-1 brick:

$$(1.1) \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

#### В

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 $(2.10) \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & \bullet & 0 \\ 1 & 2 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  $(2.11)^{*}\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 2 & 2 & 0 \\ 2 & \bullet & 0 \\ 2 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  $(2.12)^* \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 2 \\ 0 & \bullet & 2 \\ 0 & 0 & 2 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  $(2.13) \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 2 & 2 & 2 \\ 2 & \cdot & 2 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  $(2.14) \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 2 & 2 & 0 \\ 2 & \cdot & 0 \\ 2 & 2 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  $(2.15) \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 2 & \cdot & 2 \\ 2 & 2 & 2 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  $(2.16) \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 2 & 2 \\ 0 & \cdot & 2 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  $(2.17) \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & \cdot & 2 \\ 0 & 2 & 2 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  $(2.18)*\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 2 & 0 & 0 \\ 2 & \cdot & 0 \\ 2 & 2 & 2 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ 

Second Group of Rules

For these configurations, deposit a type-2 brick

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# Result

- 20×20×20 lattice
- 10 wasps
- After 20 000 simulation steps
- Axis and plateaus
- Resembles nest of *Parachartergus*



# Architectures Generated from Other Rule Sets



Fig. from Bonabeau & al., Swarm Intell.

### More Cubic Examples



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Fig. from Bonabeau & al., Swarm Intell.

# Cubic Examples (1)





Figs. from IASC Dept., ENST de Bretagne.

# Cubic Examples (2)



Figs. from IASC Dept., ENST de Bretagne.

# Cubic Examples (3)



Figs. from IASC Dept., ENST de Bretagne.

# Cubic Examples (4)





Figs. from IASC Dept., ENST de Bretagne.

# Cubic Examples (5)





Figs. from IASC Dept., ENST de Bretagne.

# An Interesting Example



- Includes
  - central axis
  - external envelope
  - long-range helical ramp
- Similar to *Apicotermes* termite nest

# Similar Results with Hexagonal Lattice



- $20 \times 20 \times 20$  lattice
- 10 wasps
- All resemble nests of wasp species
- (d) is (c) with envelope cut away
- (e) has envelope cut away

#### More Hexagonal Examples





Figs. from IASC Dept., ENST de Bretagne.

# Effects of Randomness (Coordinated Algorithm)



- Specifically different (i.e., different in details)
- Generically the same (qualitatively identical)
- Sometimes results are <u>fully constrained</u>

Fig. from Bonabeau & al., Swarm Intell.

# Effects of Randomness (Non-coordinated Algorithm)



Fig. from Bonabeau & al., Swarm Intell.

#### Non-coordinated Algorithms

- Stimulating configurations are not ordered in time and space
- Many of them overlap
- Architecture grows without any coherence
- May be convergent, but are still unstructured

#### **Coordinated Algorithm**

- Non-conflicting rules
  - can't prescribe two different actions for the same configuration
- Stimulating configurations for different building stages cannot overlap
- At each stage, "handshakes" and "interlocks" are required to prevent conflicts in parallel assembly

#### More Formally...

- Let  $C = \{c_1, c_2, ..., c_n\}$  be the set of local stimulating configurations
- Let  $(S_1, S_2, ..., S_m)$  be a sequence of assembly stages
- These stages partition C into mutually disjoint subsets  $C(S_p)$
- Completion of  $S_p$  signaled by appearance of a configuration in  $C(S_{p+1})$



Example

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Fig. from Camazine &al., Self-Org. Biol. Sys.




Example



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#### Modular Structure



- Recurrent states induce cycles in group behavior
- These cycles induce modular structure
- Each module is built during a cycle
- Modules are qualitatively similar

# Possible Termination Mechanisms

- Qualitative
  - the assembly process leads to a configuration that is not stimulating
- Quantitative
  - a separate rule inhibiting building when nest a certain size relative to population
  - "empty cells rule": make new cells only when no empties available
  - growing nest may inhibit positive feedback mechanisms

### Observations

• Random algorithms tend to lead to uninteresting structures

random or space-filling shapes

- Similar structured architectures tend to be generated by similar coordinated algorithms
- Algorithms that generate structured architectures seem to be confined to a small region of rule-space

# Analysis

- Define matrix M:
  - 12 columns for 12 sample structured architectures
  - 211 rows for stimulating configurations
  - $M_{ij} = 1$  if architecture *j* requires configuration *i*



#### Factorial Correspondence Analysis



### Conclusions

- Simple rules that exploit discrete (qualitative) stigmergy can be used by autonomous agents to assemble complex, 3D structures
- The rules must be non-conflicting and coordinated according to stage of assembly
- The rules corresponding to interesting structures occupy a comparatively small region in rule-space

