

# Form of the Solution

Write out all KVL/KCL eqs & element diff eqs & hope to manipulate to

$$k_N \frac{d^N}{dt^N} v_{rx}(t) + \dots + k_2 \frac{d^2}{dt^2} v_{rx}(t) + k_1 \frac{d}{dt} v_{rx}(t) + k_0 v_{rx}(t) = \sqrt{V_{TX}} \sin(\omega t)$$

$$\sum_{i=0}^N k_i \frac{d^i}{dt^i} v_{rx} = \sqrt{V_{TX}} \sin(\omega t)$$

Solution for  $v_{rx}(t)$  will look like  
 $v_{rx}(t) = v_{rx,h}(t) + v_{rx,p}(t)$

Homogeneous / Natural / Transient response

$$\sum_{i=0}^N k_i \frac{d^i}{dt^i} v_{rx} = 0$$

$$\rightarrow v_{rx} = \sum_{i=1}^n A_i e^{s_i t} \quad \text{assume no repeated roots}$$

$s_i \rightarrow$  roots of characteristic polynomial  
 $A_i \rightarrow$  from ICs

$s_i \rightarrow$  some time constants / frequencies associated with the circuit independent of input

transient response  $\rightarrow$  for any real circuit (damped) this response will die out over time

particular / steady-state / Natural Response

$$\sum_{i=0}^N k_i \frac{d^i}{dt^i} v_{rx} = \sqrt{V_{TX}} \sin(\omega t)$$

pick a guess, for this equation

$$v_{rx} = A \sin(\omega t + \phi)$$

$$\begin{aligned} v_{rx}(t) &= A \sin(\omega t + \phi) &= A \cos(\omega t + \phi - 90^\circ) \\ v'_{rx}(t) &= \omega A \cos(\omega t + \phi) &= \omega A \cos(\omega t + \phi) \\ v''_{rx}(t) &= -\omega^2 A \sin(\omega t + \phi) &= \omega^2 A \cos(\omega t + \phi + 90^\circ) \\ v'''_{rx}(t) &= -\omega^3 A \cos(\omega t + \phi) &= \omega^3 A \cos(\omega t + \phi + 180^\circ) \\ v^{(4)}_{rx}(t) &= \omega^4 A \sin(\omega t + \phi) &= \omega^4 A \cos(\omega t + \phi + 270^\circ) \end{aligned}$$

every derivative multiply by  $\omega$  & add  $90^\circ$  to the phase.

any linear combination will be

$$v_{rx}(t) = C \cos(\omega t + \theta)$$

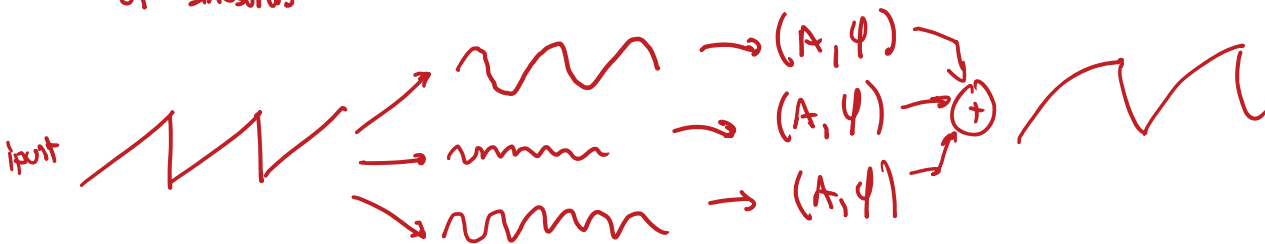
$$\sin(\theta) = \cos(\theta - 90^\circ)$$

Property of all LTI systems: if input is a sinusoid at  $\omega$ , output is a sinusoid at  $\omega$ . (only mag & phase change)

# Frequency Domain: Preview (sneak peek)

LTC: sinusoids in  $\rightarrow$  sinusoids out (same freq)

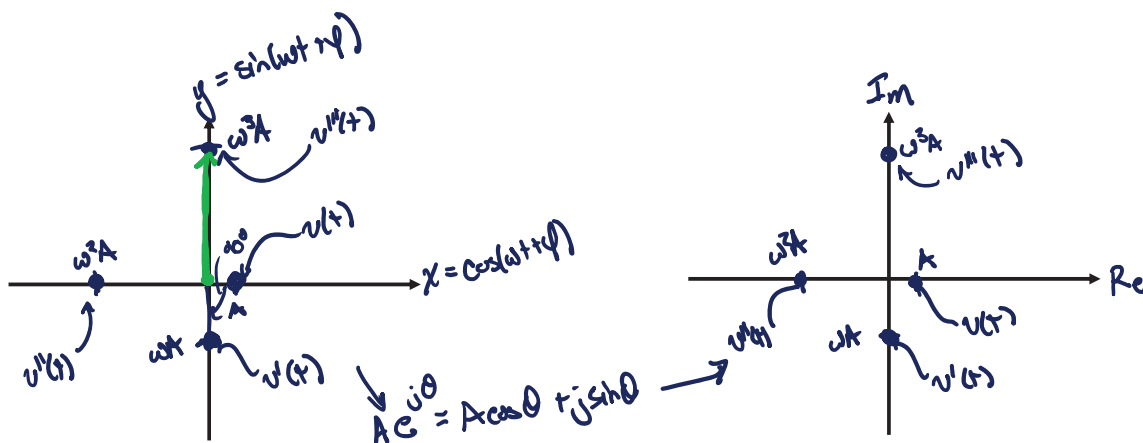
1. Make it really easy to solve circuits for sinusoidal inputs
2. Find away to represent any signal as a linear combination of sinusoids



Fourier  $\rightarrow$  Fourier Series  $\rightarrow$  for periodic signal  
 $\rightarrow$  Fourier Transform  $\rightarrow$  for everything else

## Sinusoidal Steady State

$v(t) = A \cos(\omega t + \phi)$	$\rightarrow \cos$	Derivative $\rightarrow$ rotate $90^\circ$ $\neq$ scale length by $\omega$
$v'(t) = \omega A \cos(\omega t + \phi + 90^\circ)$	$\rightarrow -\sin$	
$v''(t) = \omega^2 A \cos(\omega t + \phi + 180^\circ)$	$\rightarrow -\cos$	
$\vdots$	$\rightarrow \sin$	
	$\rightarrow \cos$	



# Complex Numbers (Review)

$$z = x + jy = r e^{j\theta}$$

Rectangular form      Polar Form

$$\begin{cases} r = \sqrt{x^2 + y^2} \rightarrow \text{Magnitude} \\ \theta = \tan^{-1}\left(\frac{y}{x}\right) \rightarrow \text{Phase} \end{cases}$$

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

Euler's Formula

$$Ae^{j\theta} = A \cos \theta + jA \sin \theta$$

$$z = x + jy = r e^{j\theta} \quad \rightarrow$$

$$jz = jx - y$$

$$\operatorname{Re}\{z\} = x \quad \operatorname{Im}(z) = y$$

$$\operatorname{Re}\{jz\} = -y \quad \operatorname{Im}\{jz\} = x$$