
Overview of Core Loss Calculation Techniques

ECE 6930

Core Loss in Magnetics

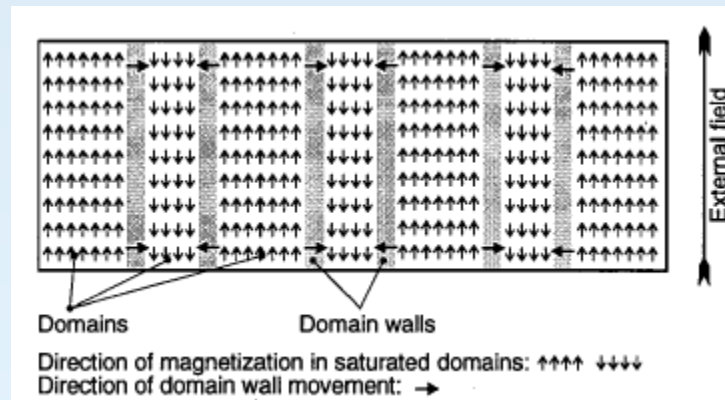
- Two common methods for calculating core loss:
 1. Hysteresis models, often introducing an intermediate step of calculating B-H loop
 2. Empirical equations, often of the form of the Steinmetz equation [1]:

$$P_v = C_m f^\alpha B^\beta$$

- Steinmetz parameters given in most datasheets for sinusoidal excitation, so we would like to have a Loss calculation methods that takes advantage of this – not requiring additional experimentation so calculations can be iterated over many core materials.

Physical Origin of Core Loss

- Both Hysteresis and Eddy Current losses occur from domain wall shifting, that is, “the damping of domain wall movement by eddy currents and spin-relaxation”. [2]



- Therefore, core loss should be directly related to the remagnetization velocity, dM/dt , rather than the excitation frequency, f .

[2] Reinert, J.; Brockmeyer, A.; De Doncker, R.W.; , "Calculation of losses in ferro- and ferrimagnetic materials based on the modified Steinmetz equation," *Industry Applications Conference, 1999. Thirty-Fourth IAS Annual Meeting. Conference Record of the 1999 IEEE* , vol.3, no., pp.2087-2092 vol.3, 1999

Steinmetz for Non-Sinusoidal Magnetization

- Typically, $1 < \alpha < 3$ and $2 < \beta < 3$, indicating the possibility of nonlinearity between losses and flux density, frequency.
 - Therefore, a Taylor series expansion will not provide correct results.
- Rather, we need to find a way of incorporating dM/dt , or its proportional equivalent dB/dt , into the Steinmetz equation parameters

Modified Steinmetz Equation

- Extends the Steinmetz equation parameters by equating the weighted time derivative of B for arbitrary magnetizing currents with those of a sine-wave

$$\left\langle \frac{dB_w}{dt} \right\rangle = \int_0^T \frac{\frac{dB^2}{dt}}{B_{\max} - B_{\min}} dt$$

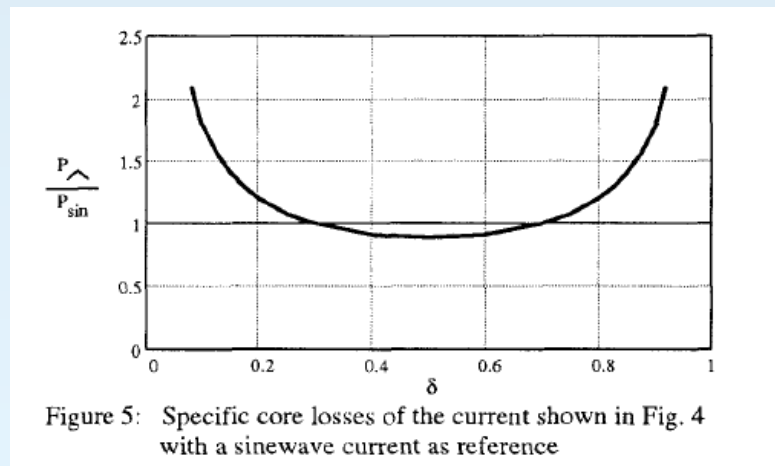
- Next, a sine-wave of frequency $f_{sin,eq}$ is found such that

$$\left\langle \frac{dB_w}{dt} \right\rangle = \left\langle \frac{dB_{w,sin}}{dt} \right\rangle$$

- Then, the Steinmetz equation can be used with parameters selected according to $f_{sin,eq}$

Modified Steinmetz Equation Results

- Table given for square wave voltage excitation / triangle wave magnetizing current.
- Results show that power loss is slightly less for near 50% triangle wave magnetization than for sine wave magnetization.



- [3] claims results experimentally confirmed in [4]

[3] Albach, M.; Durbaum, T.; Brockmeyer, A.; , "Calculating core losses in transformers for arbitrary magnetizing currents a comparison of different approaches," *Power Electronics Specialists Conference, 1996. PESC '96 Record., 27th Annual IEEE* , vol.2, no., pp.1463-1468 vol.2, 23-27 Jun 1996

[4] Chen, D. Y., "Comparison of the High Frequency Magnetic Core Losses under two different Driving Conditions: A Sinusoid Voltage and a Squarewave Voltage", 1978, *PESC'78*, 237-241

Modified Steinmetz Equation Issues

- Primary issue is the implicit assumption of losses proportional to f^2 while still assuming losses proportional to f^α . Thus, losses are only accurate for $\alpha \approx 2$ (Demonstrated in [5])
- Subloops must be extracted and treated individually to maintain validity

Generalized Steinmetz Equation

- Hypothesizes that instantaneous power loss can be given by the “physically plausible” equation:

$$P_v(t) = k_1 \left| \frac{dB}{dt} \right|^\alpha |B(t)|^{\beta-\alpha}$$

- Thus, the per volume power loss can be given by:

$$\langle P_v(t) \rangle = \frac{1}{T} \int_0^T k_1 \left| \frac{dB}{dt} \right|^\alpha |B(t)|^{\beta-\alpha} dt$$

- Where, by comparison to the result for sine waves,

$$k_1 = \frac{k}{(2\pi)^{\alpha-1} \int_0^{2\pi} |\cos \theta|^\alpha |\sin \theta|^{\beta-\alpha} d\theta}$$

Generalized Steinmetz Equation Issues

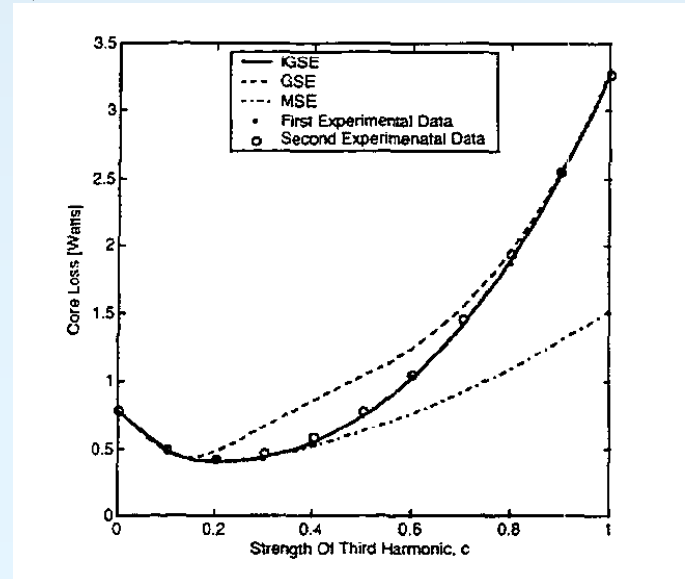
- Not, in fact, always a better prediction than MSE.
- Because Steinmetz equation parameters vary with frequency, parameters may need to be selected differently, or results may be inaccurate for waveforms with high harmonic content
- Subloops still need to be treated separately

Improved General Steinmetz Equation

- States that core loss depends not only on B and dB/dt , but also on the time-history of the flux waveform
- Incorporates ΔB as in MSE to account for local max and min, as well as take into account local subloops

$$\langle P_v(t) \rangle = \frac{1}{T} \int_0^T k_1 \left| \frac{dB}{dt} \right|^\alpha (\Delta B)^{\beta-\alpha} dt$$

- Results show good matching to experimental data, including advantages of both MSE and GSE



[6] Venkatachalam, K.; Sullivan, C.R.; Abdallah, T.; Tacca, H.; , "Accurate prediction of ferrite core loss with nonsinusoidal waveforms using only Steinmetz parameters," *Computers in Power Electronics, 2002. Proceedings. 2002 IEEE Workshop on* , vol., no., pp. 36-41, 3-4 June 2002

Improved General Steinmetz Equation Issues

- Maintains issues with selection of appropriate parameters for Steinmetz equations; may be inaccurate for waveforms with high harmonic content
- The effects of DC magnetization are not taken into account

Natural Steinmetz Equation

- Independently developed equation matching exactly iGSE

$$P_{NSE} = \left(\frac{\Delta B}{2} \right)^{\beta-\alpha} \frac{k_N}{T} \int_0^T \left| \frac{dB}{dt} \right|^\alpha dt$$

$$k_N = \frac{k}{(2\pi)^{\alpha-1} \int_0^{2\pi} |\cos \theta|^\alpha d\theta}$$

- Note that, for $\alpha=1$ or $\alpha=2$, or $D \approx .5$, the NSE does not differ significantly from the MSE.