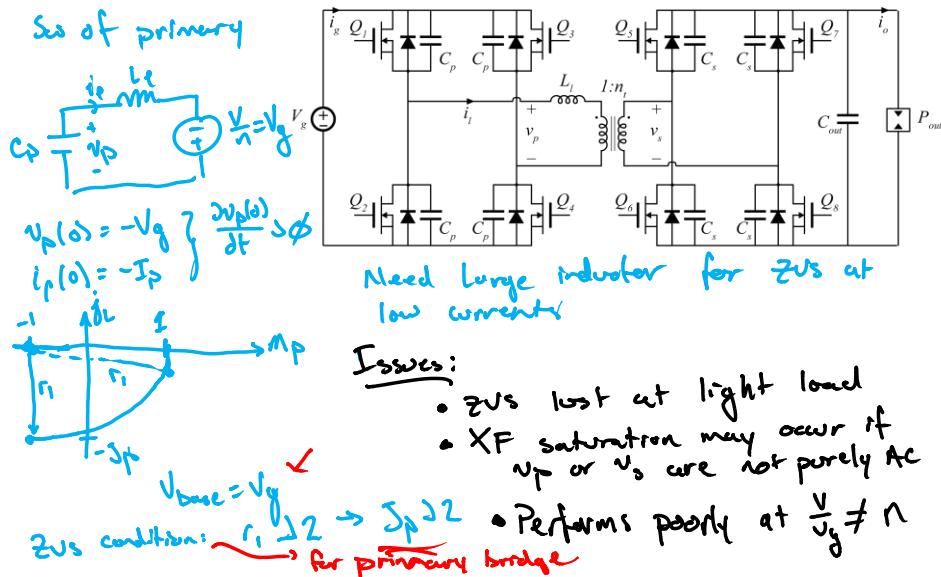




Dual Active Bridge Converter



ZVS cond'n on primary

$$S_p \gg 2$$

$$I_{base} S_p \gg 2 I_{base}$$

$$I_p \gg 2 \frac{V_g}{R_o} = 2 V_g \sqrt{\frac{C_p}{L_p}}$$

$$\rightarrow \boxed{\frac{1}{2} L_p I_p^2 \gg (2V_g)^2 C_p \frac{1}{2}}$$

E in L_p @ start of prim dev time \rightarrow Energy needed to ZVS primary devices

$$I_p \leftarrow I_{out}$$

$$V_{base} = V_g$$

$$I_{base} = \frac{V_g}{R_o}$$

$$R_o = \sqrt{\frac{L_p}{C_p}}$$

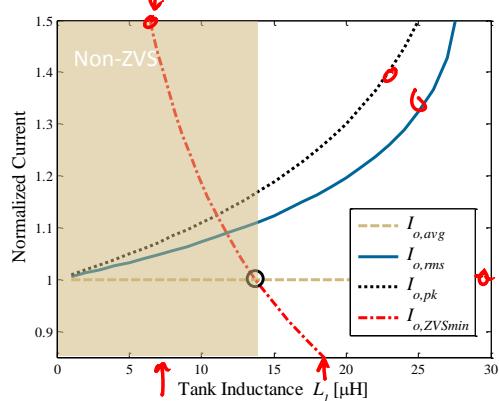
Large L_p desired to obtain ZVS at low P_{out}

\rightarrow DAB in Phase-shift modulation will lose ZVS at light load

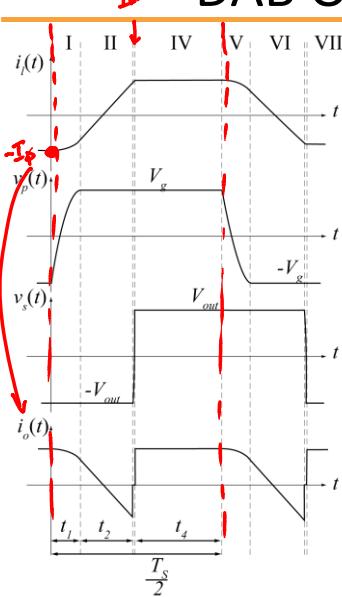


Constraints on Inductance

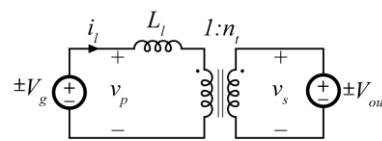
- From previous analysis, smaller L_i results in smaller RMS currents in converter
- However, L_i must be large enough to store energy necessary for ZVS
- Near-optimal design at a single operating point by selecting L_i just large enough to obtain ZVS



DAB Operation Analysis



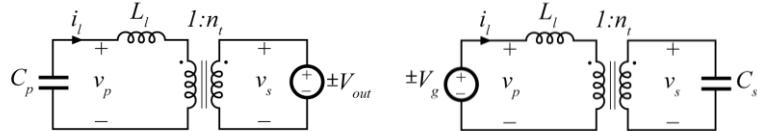
- Phase-shifted DAB has four unique intervals per half-period
 - Primary dead time **I**
 - Phase shift **II**
 - Secondary dead time **III**
 - Main power delivery **IV**
- Begin by considering DCX operation, where $V_{out} = n_t V_g$
- Even-numbered intervals, circuit reduces to



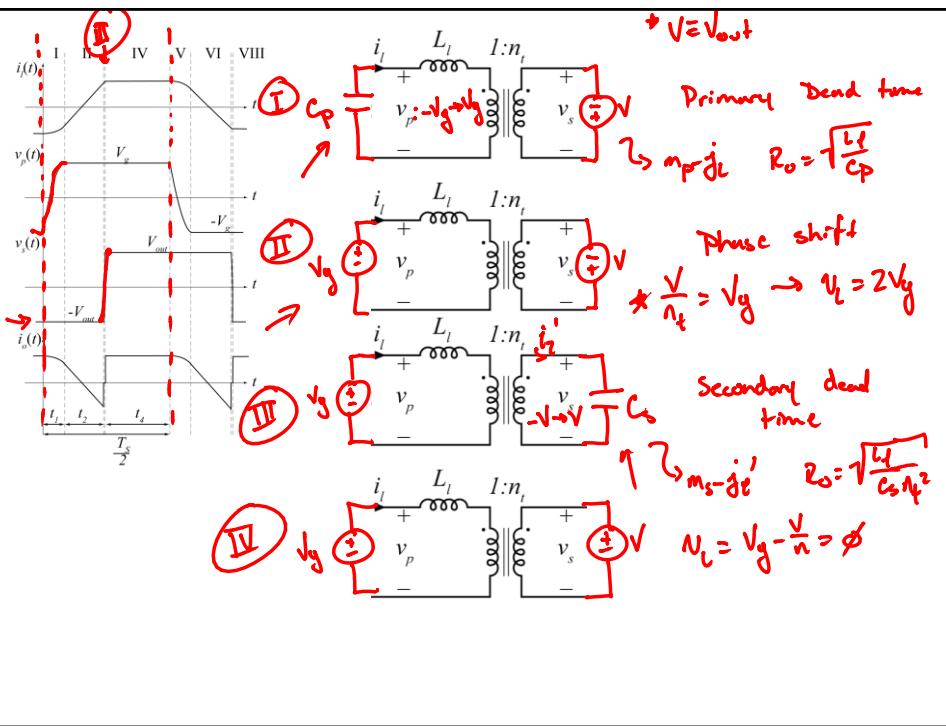
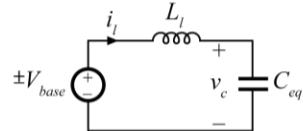


Resonant Interval Analysis

- Resonant intervals have equivalent circuits of the form:

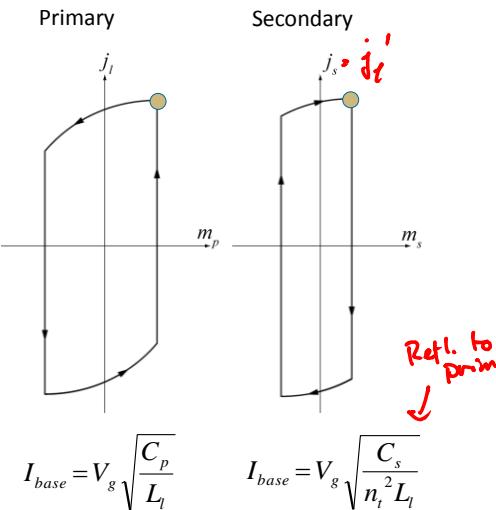
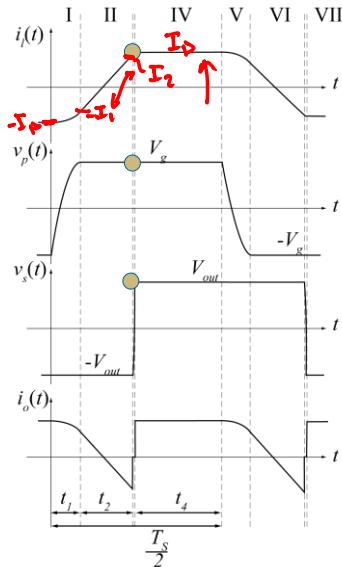


- Both of which can be simplified to:





State Plane Analysis of DAB Converter



State Plane Analysis of DAB Converter

$$\textcircled{I} \quad \alpha = \sin^{-1}\left(\frac{2}{J_p}\right)$$

$$J_p = \sqrt{4 + J_1^2}$$

ZVS: $J_p > 2$

Primary

$$\textcircled{II} \quad \frac{(J_2 + J_1)}{t_2 \omega_0} = \frac{2V_g}{L_p \omega_0}$$

$$\frac{(J_2 + J_1)}{\beta} = \frac{2V_g}{4 \cdot \frac{1}{4} C_p} = \frac{2V_g}{R_0}$$

$$J_2 + J_1 = 2\beta$$

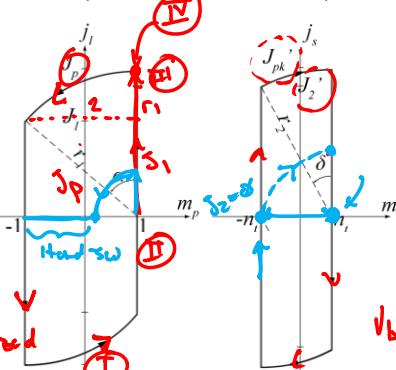
$$\textcircled{III} \quad \delta' = \sin^{-1}\left(\frac{2n_t}{J_{pk}}\right)$$

$$J_{pk}' = \sqrt{(2n_t)^2 + J_2^2}$$

* note: normalized wrt. secondary

ZVS: χ

Secondary



$$\textcircled{IV} \rightarrow X$$

$$\hookrightarrow T_s \cdot \frac{1}{2} = \frac{\alpha}{\omega_0} + \frac{\beta}{\omega_0} + \frac{\delta}{\omega_0} + \frac{h}{\omega_0} \rightarrow \frac{\pi}{f} = \alpha + \beta + \delta + h$$

$$I_{base} = V_g \sqrt{\frac{C_p}{L_l}}$$

$$I_{base}' = V_g \sqrt{\frac{C_s}{n_t^2 L_l}}$$