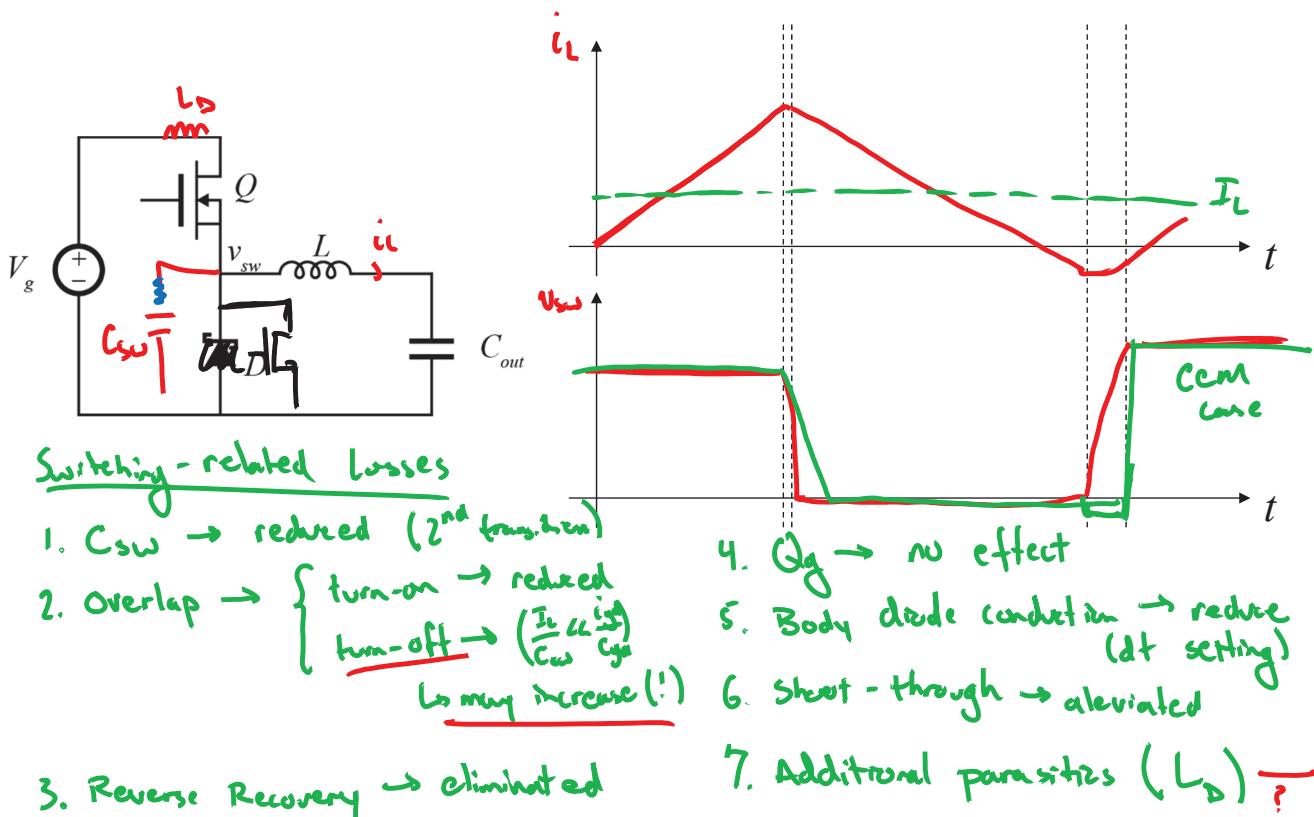


# Remaining Switching Losses



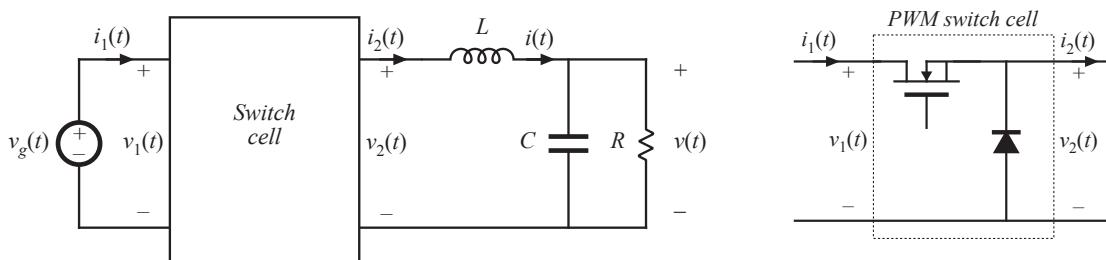
## Chapter 20: Resonant Switch Topologies

- Introduction
- 20.1 The zero-current-switching quasi-resonant switch cell
  - 20.1.1 Waveforms of the half-wave ZCS quasi-resonant switch cell
  - 20.1.2 The average terminal waveforms
  - 20.1.3 The full-wave ZCS quasi-resonant switch cell
- 20.2 Resonant switch topologies
  - 20.2.1 The zero-voltage-switching quasi-resonant switch
  - 20.2.2 The zero-voltage-switching multiresonant switch
  - 20.2.3 Quasi-square-wave resonant switches
- 20.3 Ac modeling of quasi-resonant converters
- 20.4 Summary of key points

# The resonant switch concept

General idea:

- PWM switch network is replaced by a resonant switch network
- This leads to a quasi-resonant or quasi-squarewave version of the original PWM converter

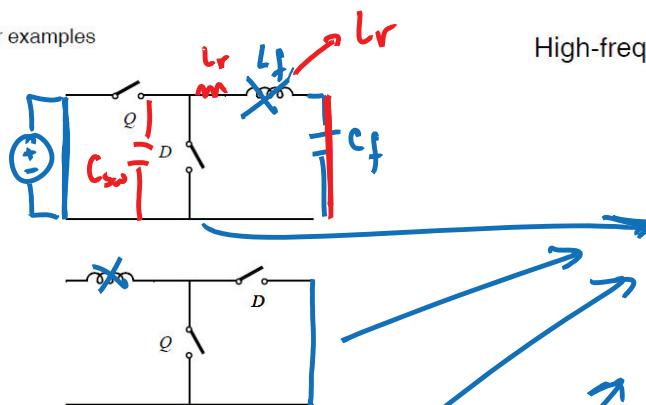


Example: realization of the switch cell in the buck converter

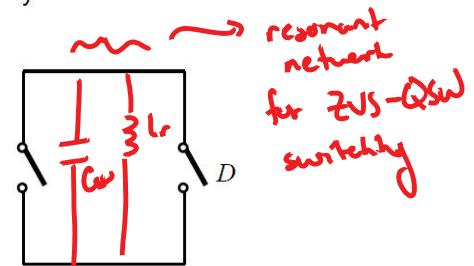


## High Frequency Switch Network

Converter examples



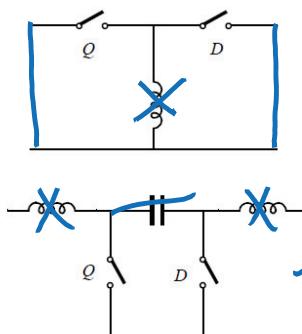
High-frequency view of the switch network



Basic switch implementation options

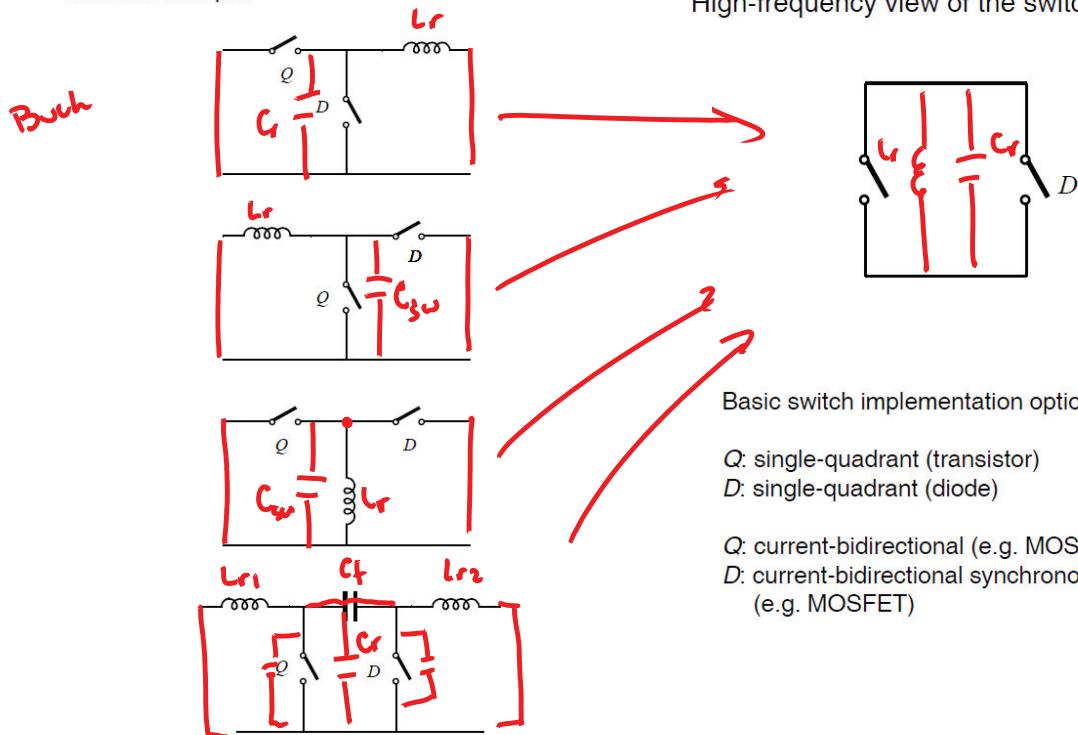
Q: single-quadrant (transistor)  
D: single-quadrant (diode)

Q: current-bidirectional (e.g. MOSFET)  
D: current-bidirectional synchronous rectifier  
(e.g. MOSFET)



# ZVS-QSW: Review

Converter examples



High-frequency view of the switch network

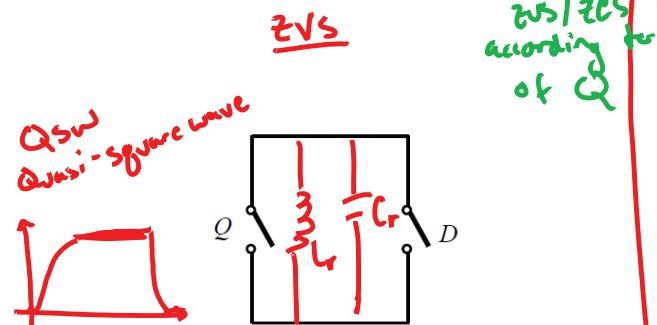
Basic switch implementation options

$Q$ : single-quadrant (transistor)  
 $D$ : single-quadrant (diode)

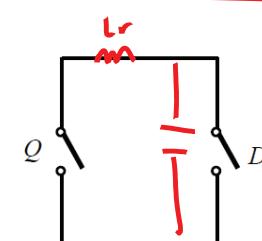
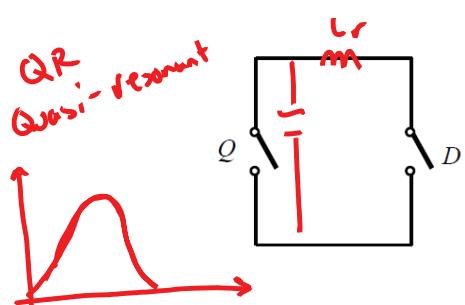
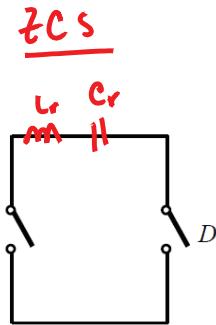
$Q$ : current-bidirectional (e.g. MOSFET)  
 $D$ : current-bidirectional synchronous rectifier  
(e.g. MOSFET)



## Classification of Resonant-Switch Converters

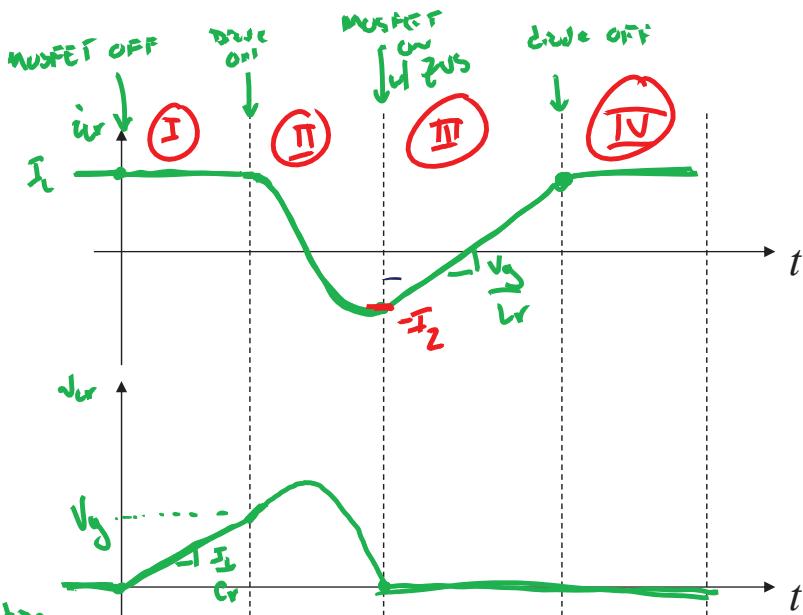
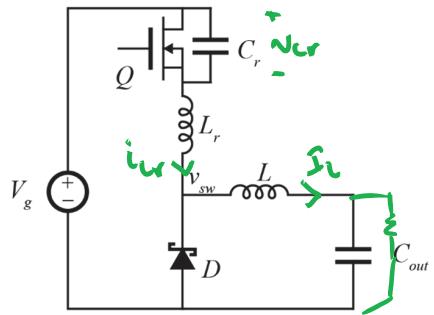


*ZVS/ZCS named according to Q*



*Discussed in detail in Chapter 20*

# ZVS-QR Buck

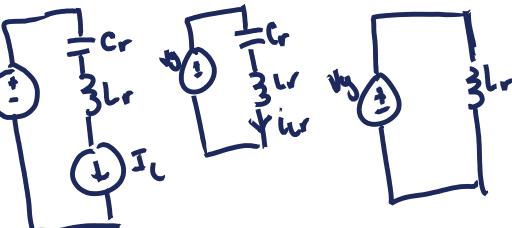


+ Incorporates both  $C_{ds}$  &  $L_s$  of MOSFET into operation

$$+ i_{ds,ph} = I_L$$

-  $V_{ds,ph}$  will increase significantly

- Diode assumed ideal



## ZVS-QR State Plane

$$\sqrt{L_r C_r} > V_g \quad R_0 = \sqrt{L_r / C_r}$$

$$\textcircled{I}: \frac{V_g}{C_r} t_1 = V_g \rightarrow \theta_1 = \frac{1}{\omega_r} t_1$$

$$\textcircled{II}: r_2^2 = \omega_r^2 = \omega_2^2 + 1$$

$$\omega_2 = \sqrt{\omega_r^2 - 1}$$

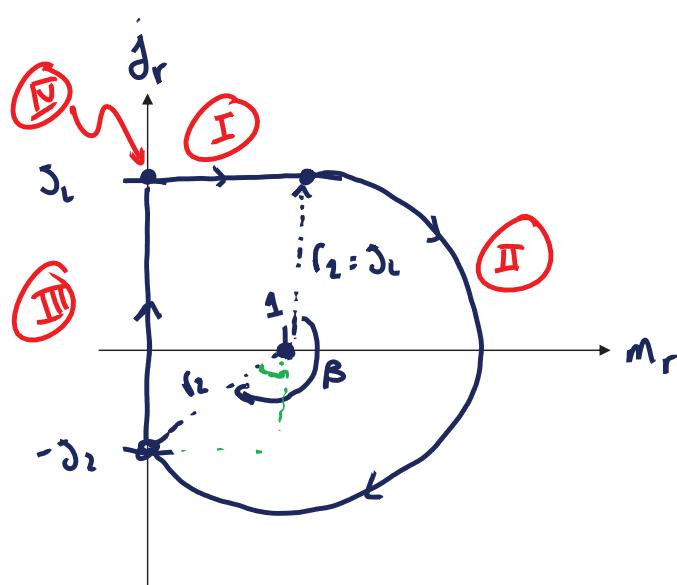
$$\beta = \pi + \sin^{-1}\left(\frac{1}{\omega_r}\right)$$

$$\textcircled{III} \quad \frac{V_g}{L_r} t_3 = I_2 + I_L$$

$$\theta_3 = \omega_2 + \omega_r$$

$$\textcircled{IV}: X$$

$$\theta_1 + \beta + \theta_3 + \theta_4 = \frac{2\pi}{F}$$



# Averaging

Apply volt-second balance on  $\text{Lf}$

$$\langle v_{lf} \rangle = \phi = \langle v_{sw} \rangle - V$$
$$\phi = V_g - \langle v_{cr} \rangle - \cancel{\langle v_{lf} \rangle} - V$$

$$V = V_g - \langle v_{cr} \rangle$$

