Magnetostatics II

Exams (Test 2 & the Final) will not cover the vector potential. This is an important topic, however, if you have further interest in microwave engineering, antennas, etc.

Read the following notes along with Section 5-4 of the textbook (running the extra mile):

If a vector field has no curl, it must be something's gradient. Conservative.

Now, another analogy between the \( \vec{E} \) & \( \vec{B} \) fields.

For the \( \vec{E} \) field, \( \nabla \times \vec{E} = 0 \) or \( \oint \vec{E} \cdot d\vec{l} = 0 \)

Thus \( \nabla \times (\nabla \phi) = 0 \) the curl of a gradient.

Therefore we can define \( \nabla \phi = -\vec{E} \)

\[ V_A - V_B = \int_{A}^{B} \vec{B} \cdot d\vec{l} \]

\( \vec{E} \) is conservative. If it's conservative, it must be something's gradient.
If a vector field has no divergence, it must be something's curl. Solenoidal.

For the magnetic field
\[ \nabla \cdot \vec{B} = 0. \]

we say the \( \vec{B} \) field is solenoidal.

Mathematically, we have
\[ \nabla \cdot (\nabla \times \vec{A}) = 0 \]

The divergence of curl is 0.

The curl of any field has zero divergence.

This can help you remember the math in a physical context.
\[ \vec{j} = \nabla \times \vec{A} \]

\[ \nabla \cdot \vec{j} = 0 \]

Ampere's law

\[ \nabla \cdot \vec{B} = 0 \]

We can always define some \( \vec{A} \) such that
\[ \vec{B} = \nabla \times \vec{A} \]

\( \vec{A} \) is called the vector potential.

Notice that, for a given \( \vec{B} \), \( \vec{A} \) is not unique.

for example, if \( \vec{B} = \nabla \times \vec{A} \)

the \( \vec{B} = \nabla \times (\vec{A} + \vec{A}_0) \) where \( \vec{A}_0 \) is a constant. Since \( \nabla \times \vec{A}_0 = 0 \)

Analogy: \( V + V_0 \).
Why do we define $\vec{A}$?
\[
\nabla \times \vec{H} = \frac{\dot{J}}{\mu} \\
\nabla \times \vec{E} = \mu \vec{J} \\
\n\nabla \cdot (\nabla \times \vec{A}) = \mu \vec{J}
\]

Going through the math, you'll get
\[
\nabla^2 \vec{A} - \nabla (\nabla \cdot \vec{A}) = -\mu \vec{J}
\]

I will define what $\nabla^2 \vec{A}$ means in a second.

Recall that the choice of $\vec{A}$ is not unique for $\vec{E} = \nabla \times \vec{A}$, so we can always choose $\vec{A}$ such that $\nabla \cdot \vec{A} = 0$.

So, $\nabla^2 \vec{A} = -\mu \vec{J}$

Define $\nabla^2$.
\[
\nabla^2 \vec{A} = \nabla^2 A_x \hat{x} + \nabla^2 A_y \hat{y} + \nabla^2 A_z \hat{z}
\]

So, the eq. actually means three eqs.,
\[
\begin{align*}
\nabla^2 A_x &= -\mu J_x \\
\nabla^2 A_y &= -\mu J_y \\
\nabla^2 A_z &= -\mu J_z
\end{align*}
\]

Compare to the Poisson eq.
\[
\nabla^2 \phi = -\frac{P}{\varepsilon}
\]

These are just formally 3 Poisson eq's.
How are they used? You use them to find $Ax$, $Ay$, $Az$. So you have $\vec{A}$, and then $\vec{B} = \nabla \times \vec{A}$.

This is just the same as you use the Poisson eq. to find the electric potential $V$ and then $\vec{E} = -\nabla V$. The difference is that the mag field is more complicated, you need to solve 3 eq’s. That’s why the $\vec{A}$ is called the vector potential & $V$ is called the scalar potential.

Now let’s summarize the methods to find the $\vec{E}$ & $\vec{B}$ fields and compare them.

**Electric**

1. Coulomb’s law
   \[ d\vec{E} = \frac{P dV}{4\pi \varepsilon R^2} \hat{R} \]

2. For hi-symmetry structures
   \[ \vec{\nabla} \cdot \vec{D} = \oint d\vec{S} = \int \rho dV = Q \]

3. Poisson Eq
   \[ \nabla^2 V = -\frac{P}{\varepsilon} \]
   \[ \text{then} \quad \vec{E} = -\nabla V \]

**Magnetic**

1. Biot–Savart law
   \[ d\vec{H} = \frac{I d\vec{l} \times \hat{R}}{4\pi R^2} \]

2. General
   \[ \oint \vec{H} \cdot d\vec{l} = \oint \vec{J} \cdot d\vec{s} = I \]

You find the trick. Usually high school math is sufficient.

Then take integral to find total $\vec{E}$ or $\vec{H}$.
A is a very important concept in both physics & microwave engineering. Here, I want you to have this big picture to know the 3 methods of finding the fields. I also know that very few of you will actually become microwave engineers or physicists. So, there won't be homework problems about A, nor will it be tested in any exams.

I hope you take good notes and understand the concept.

Now, the last topic in Magnetostatics: the boundary conditions.

\[ \nabla \cdot \vec{B} = 0 \Rightarrow \vec{B}_1 \cdot \hat{n} \, dS = \vec{B}_2 \cdot \hat{n} \, dS \Rightarrow B_{1n} = B_{2n} \]

\[ \oint \vec{H} \cdot dl = I \Rightarrow -H_{1t} \Delta l + H_{2t} \Delta l = J_s \Delta L \]

\[ \Rightarrow H_{2t} - H_{1t} = J_s \]

Think about the electrostatic analogy on your own.