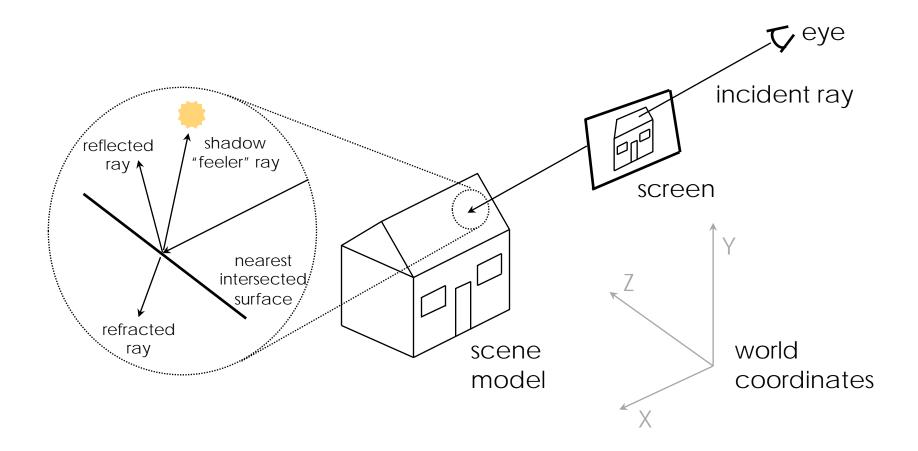
# Ray Tracing

Jian Huang

# Ray Tracing



# Ray-Tracing Pseudocode

 For each ray r from eye to pixel, color the pixel the value returned by ray\_cast(r):

```
ray\_cast(\mathbf{r}) {

s \leftarrow nearest\_intersected\_surface(\mathbf{r});

\mathbf{p} \leftarrow point\_of\_intersection(\mathbf{r}, s);

\mathbf{u} \leftarrow reflect(\mathbf{r}, s, \mathbf{p});

\mathbf{v} \leftarrow refract(\mathbf{r}, s, \mathbf{p});

c \leftarrow phong(\mathbf{p}, s, \mathbf{r}) +

s.k_{reflect} \times ray\_cast(\mathbf{u}) +

s.k_{refract} \times ray\_cast(\mathbf{v});

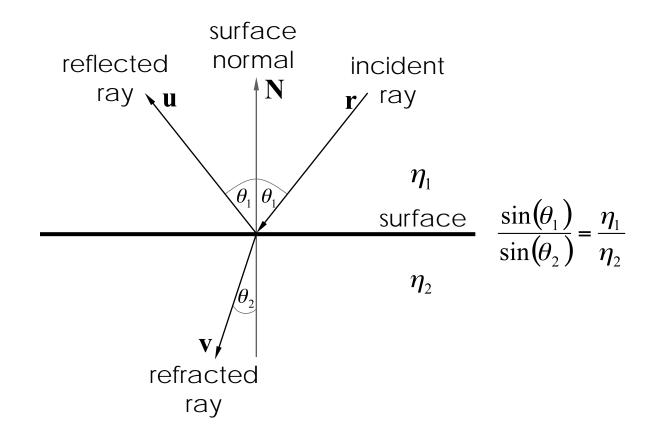
return(\mathbf{c});
```

#### Pseudocode Explained

- s ← nearest\_intersected\_surface(r);
  - Use geometric searching to find the nearest surface  ${\bf s}$  intersected by the ray  ${\bf r}$
- **p** ← point\_of\_intersection(**r**, s);
  - Compute  $\mathbf{p}_{\text{r}}$  the point of intersection of ray  $\mathbf{r}$  with surface s
- **u**← reflect(**r**, s, **p**); **v**← refract(**r**, s, **p**);
  - Compute the reflected ray u and the refracted ray v using Snell's Laws

#### Reflected and Refracted Rays

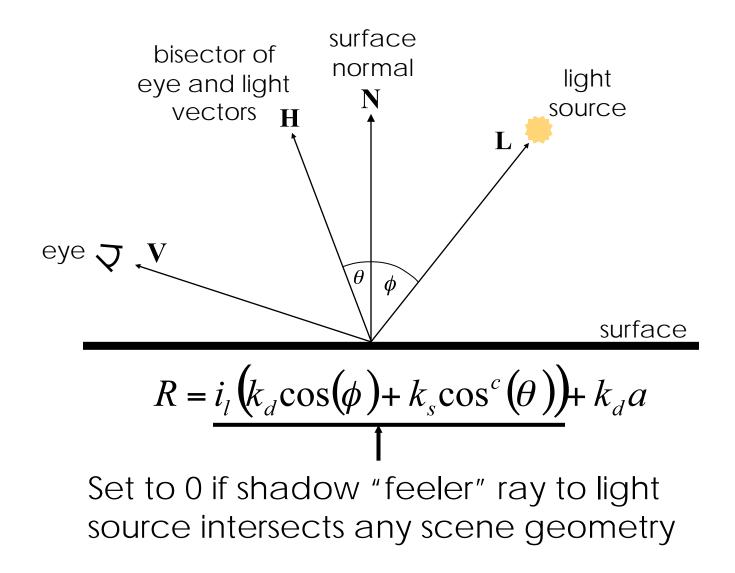
 Reflected and refracted rays are computed using Snell's Law



# Pseudocode Explained

- phong(**p**, s, **r**)
  - Evaluate the Phong reflection model for the ray r at point p on surface s, taking shadowing into account (see next slide)
- $s.k_{reflect} \times ray\_cast(\mathbf{u})$ 
  - Multiply the contribution from the reflected ray
     u by the specular-reflection coefficient k<sub>reflect</sub> for surface s
- $s.k_{refract} \times ray\_cast(\mathbf{v})$ 
  - Multiply the contribution from the refracted ray
     v by the specular-refraction coefficient k<sub>refract</sub> for surface s

### The Phong Reflection Model



# About Those Calls to ray\_cast()...

- The function ray\_cast() calls itself *recursively*
- There is a potential for infinite recursion
  - Consider a "hall of mirrors"
- Solution: limit the depth of recursion
  - A typical limit is five calls deep
  - Note that the deeper the recursion, the less the ray's contribution to the image, so limiting the depth of recursion does not affect the final image much

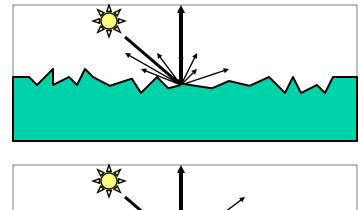
# Pros and Cons of Ray Tracing

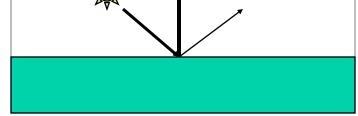
- Advantages of ray tracing
  - All the advantages of the Phong model
  - Also handles shadows, reflection, and refraction
- Disadvantages of ray tracing
  - Computational expense
  - No diffuse inter-reflection between surfaces
  - Not physically accurate
- Other techniques exist to handle these shortcomings, at even greater expense!

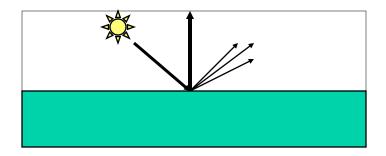
# An Aside on Antialiasing

- Our simple ray tracer produces images with noticeable "jaggies"
- Jaggies and other unwanted artifacts can be eliminated by antialiasing:
  - Cast multiple rays through each image pixel
  - Color the pixel the average ray contribution
  - An easy solution, but it increases the number of rays, and hence computation time, by an order of magnitude or more

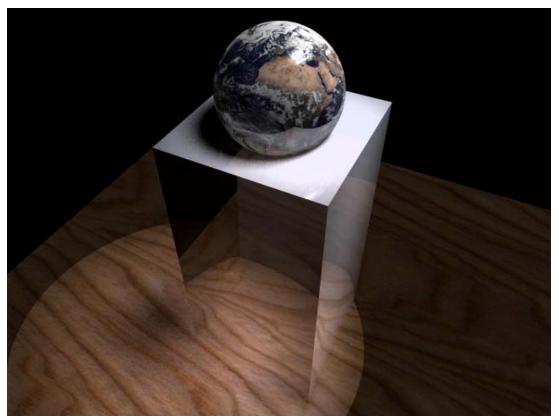
- We normally deal with a perfectly diffuse surface.
- With ray-tracing, we can easily handle perfect reflections.
- Phong allows for glossy reflections of the light source.







 If we are reflecting the scene or other objects, rather than the light source, then ray-tracing will only handle perfect mirrors.



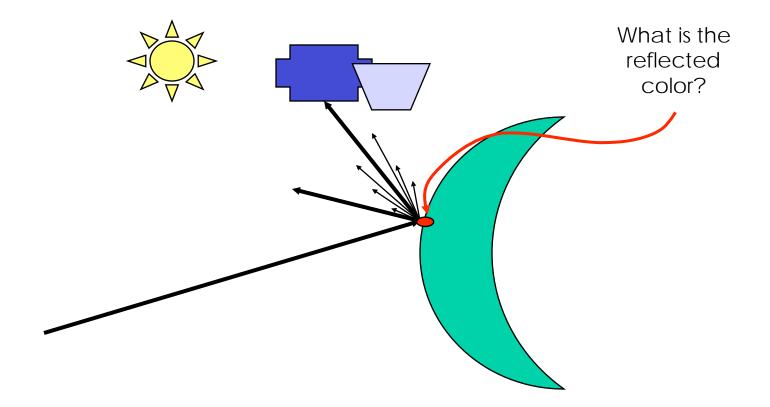
Jason Bryan, cis782, Ohio State, 2000

#### • Glossy reflections blur the reflection.



Jason Bryan, cis782, Ohio State, 2000

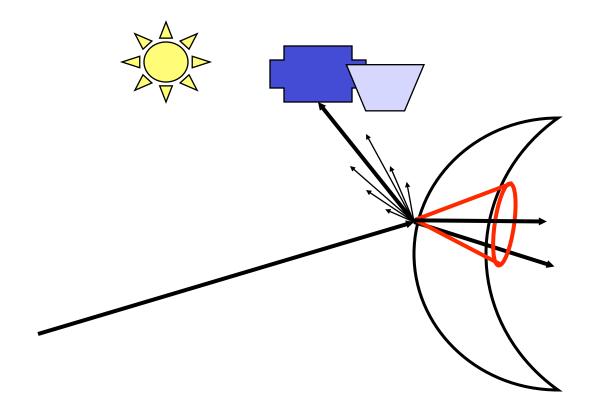
• Mathematically, what does this mean?

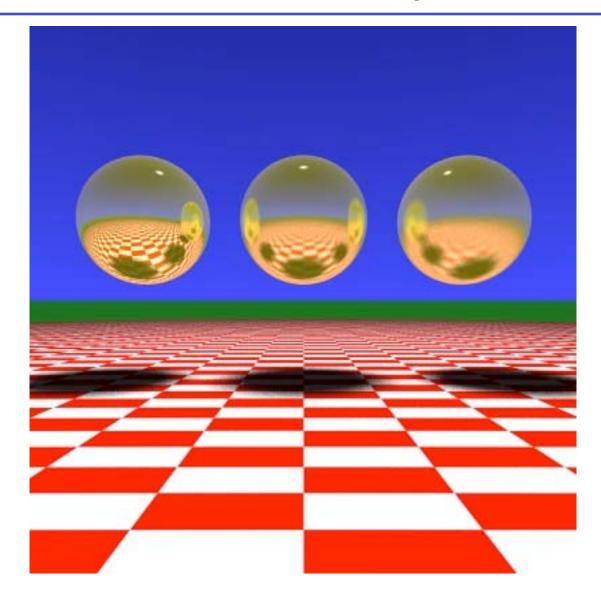


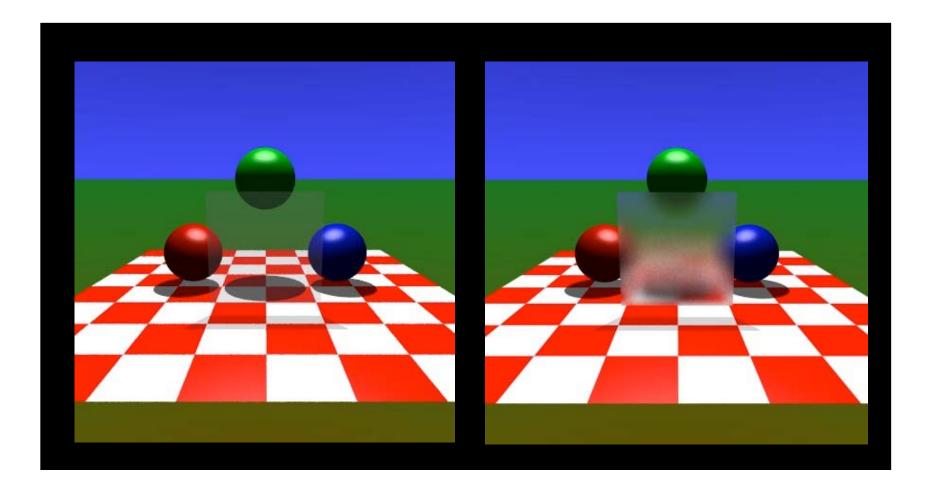
# **Glossy Reflections**

- We need to integrate the color over the reflected cone.
- Weighted by the reflection coefficient in that direction.

• Likewise, for blurred refractions, we need to integrate around the refracted angle.









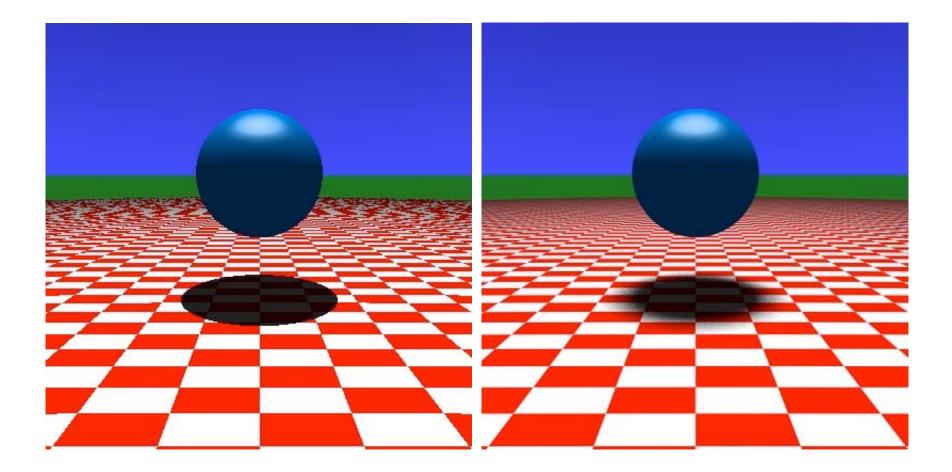
# Calculating the integrals

- How do we calculate these integrals?
  - Two-dimensional of the angles and ray-depth of the cone.
  - Unknown function -> the rendered scene.
- Use Monte-Carlo integration

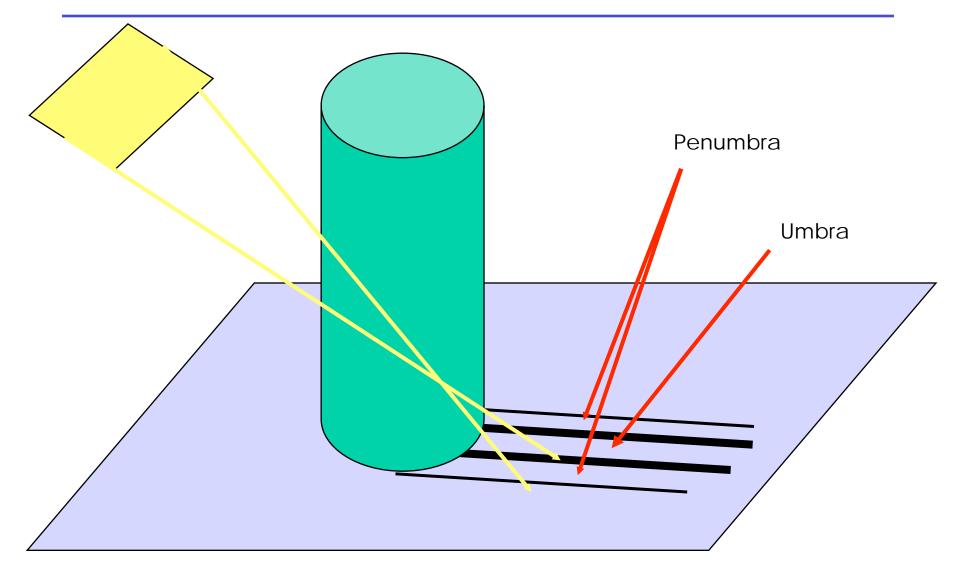
### Shadows

- Ray tracing casts shadow feelers to a point light source.
- Many light sources are illuminated over a finite area.
- The shadows between these are substantially different.
- Area light sources cast soft shadows
  - Penumbra
  - Umbra

#### Soft Shadows



#### Soft Shadows



### Soft Shadows

- Umbra No part of the light source is visible.
- Penumbra Part of the light source is occluded and part is visible (to a varying degree).
- Which part? How much? What is the Light Intensity reaching the surface?

### Camera Models

- Up to now, we have used a pinhole camera model.
- These has everything in focus throughout the scene.
- The eye and most cameras have a larger lens or aperature.



# Depth of Field

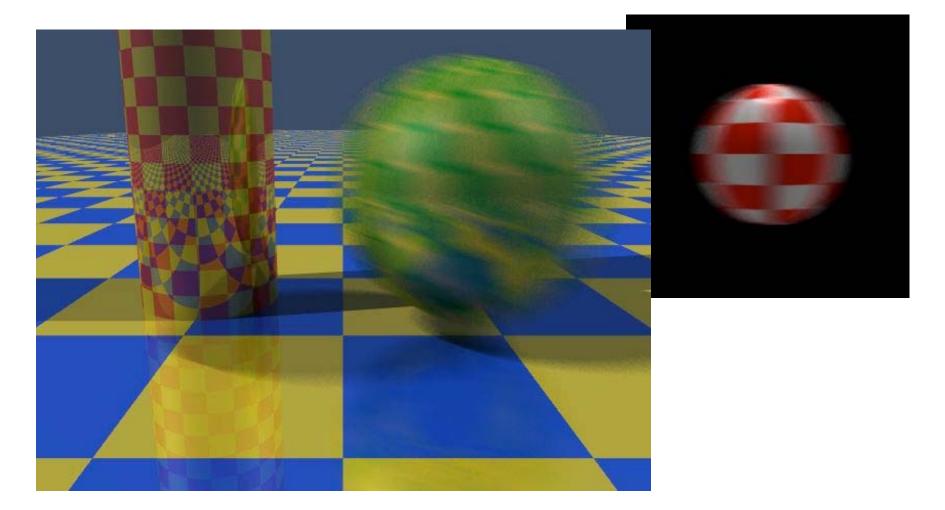


# Depth-of-Field

• Details

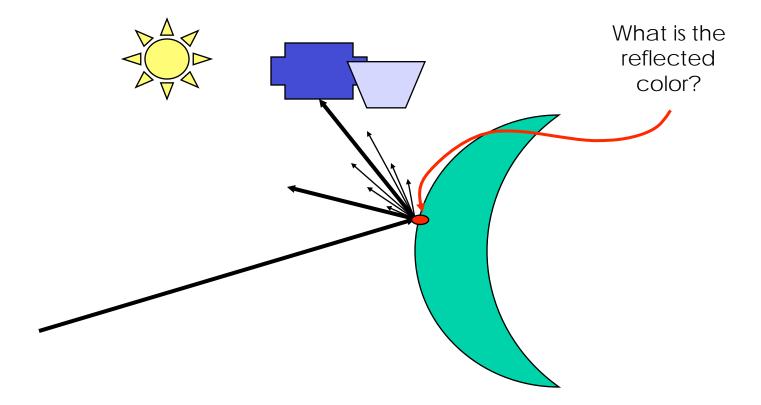
#### Motion Blur

• Integrate (or sample) over the frame time.



# Rendering the Scene

 So, we ask again, what is the color returned for each pixel?



# Rendering a Scene

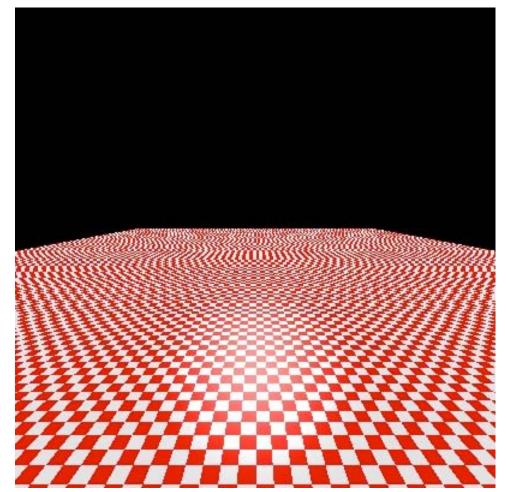
- For each frame
  - Generate samples in time and average (t):
    - For each Pixel (nxn)
      - Sample the Camera lens (IxI)
        - Sample the area light source for illumination (sxs)
        - Recursively sample the reflected direction cone (rxr).
        - Recursively sample the refracted direction cone (axa).
- Total complexity *O(p\*p\*t\*l\*l\*s\*s\*r\*r\*a\*a)!!!!!*
- Where p is the number of rays cast in the recursion n<sup>2</sup> primary rays, 3n<sup>2</sup> secondary, ...
- If we super-sample on a fine sub-pixel grid, it gets even worse!!!

# Rendering a Scene

If we only sample the 2D integrals with a *mxm* grid, and time with 10 samples, we have a complexity of *O(m<sup>9</sup>p<sup>2</sup>)*.

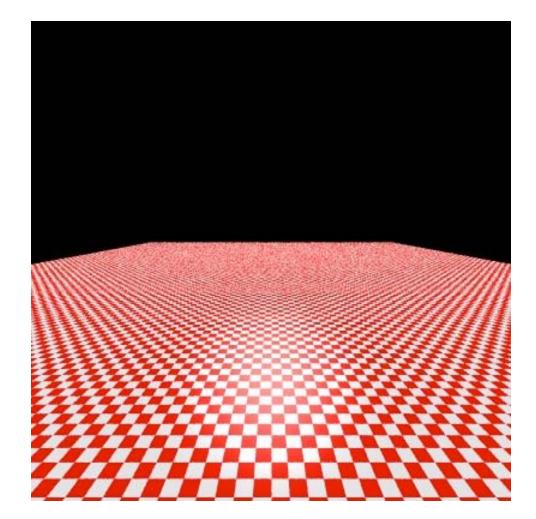
# Supersampling

1 sample per pixel



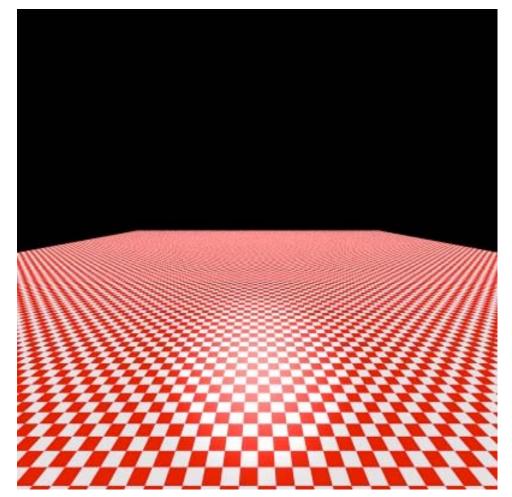
# Supersampling

16 samples per pixel



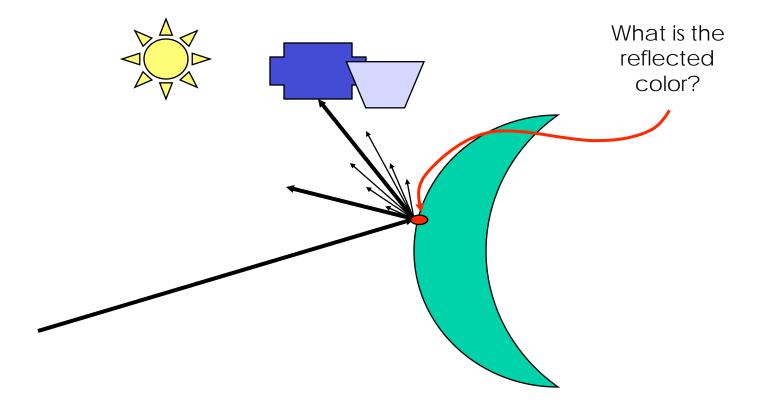
# Supersampling

• 256 samples per pixel



# Rendering the Scene

 So, we ask a third time, what is the color returned for each pixel?



# Rendering the Scene

 If we were to write this as an integral, each pixel would take the form:

 $\iiint \int \int \int \int \int f(\theta_{ref b} r_{ref b} x_{light}, y_{light}, \theta_{ref racb} r_{ref racb} lens_x, lens_y, time, u, v) d\theta dr dx dy d\theta dr dl_x dl_y dt du dv$ 

• Someone try this in Matlab!!!

# Rendering the scene

- So, what does this tell us?
- Rather than compute a bunch of 2D integrals everywhere, use Monte-Carlo integration to compute this one integral.

# **Distributed Ray-Tracing**

Details of how Monte-Carlo integration is used in DRT.