# CS302 Final Exam: December 4, 2008.

### Six Questions -- Answer all Questions

### **Question 1 (Six Points)**

**Part 1**: What is the maximum flow of the graph to the right? (This is simply a number).

**Part 2**: What is the minimum cut of the graph to the right? (This is not a number).



### **Question 2 (Nine Points)**

For each problem below, choose the algorithm that will solve the given problem in the most natural and efficient manner. If two algorithms are both naturally suited to solve a problem, give the most efficient. Here are the algorithms:

(a): STL Sets and Maps.

(b): Insertion Sort.

(c): Quicksort.

- (d): Bucket Sort (placing values in their approximate places and using insertion sort).
- (e): Depth-First Search.
- (f): Breadth-First Search on an Unweighted Graph.
- (g): Dijkstra's Algorithm.

(*h*): Network Flow.

- (i): Minimum Spanning Tree.
- (*j*): Disjoint Sets.

**Problem 1**: Finding the fastest driving route between two points, as in Mapquest or Yahoo maps.

Problem 2: Sorting 1,000,000 numbers uniformly distributed between 0 and 1.

Problem 3: Sorting 1,000,000 numbers distributed as an exponential whose mean is 3.500.

Problem 4: Sorting 1,000,000 numbers, where we have no idea about their distribution.

**Problem 5**: Determining the nodes in a graph reachable from a given node.

**Problem 6**: In Kruskal's algorithm, determining whether an edge connects two unconnected components.

# **Question 3 (Six points)**

This question concerns the undirected graph below. To the right is a listing of the edges of the graph, ordered from smallest weight to greatest.



**Part 1:** From the answers below, choose the one that shows the order in which edges are added to the Minimum Spanning Tree, using Kruskal's algorithm.

**Part 2:** From the answers below, choose the one that shows the order in which edges are added to the Minimum Spanning Tree, using Prim's algorithm.

If the algorithm requires a starting point, start from node A.

Answers: (Note, they are in alphabetical order, so you can find yours easily).

(a). AB, AE, AF, CG, DH, FI, FJ, GH, GK, HL, JK
(b). AF, AE, AB, BF, DH, EF, FI, FJ, GK, HL, JK
(c). AF, AE, AB, CG, DH, FI, FJ, GH, GK, HL, JK
(d). AF, AE, AB, FI, FJ, CG, DH, GH, GK, HL, JK
(e). AF, AE, AB, FI, FJ, JK, GK, GH, HL, DH, CG
(f). AF, AE, AB, HL, DH, JK, GK, GH, CG, FJ, FI
(g). AF, AE, DH, EF, AB, FJ, FI, JK, GK, BF, HL
(h). AF, AE, DH, EF, FI, HL, GK, BF, FJ, AB, JK
(i). AF, AE, DH, JK, HL, CG, GH, AB, FI, FJ, GK
(j). AF, AE, EF, HL, JK, GK, AB, BF, FI, FJ, DH
(l). AF, AE, GH, JK, HL, AB, GK, FJ, CG, DH, FI
(m). AF, AE, HL, CG, AB, GK, DH, FJ, FI, GH, JK
(n). AF, AE, HL, JK, GK, AB, BF, FI, FJ, DH, GH
(o). AF, AE, HL, JK, GK, AB, FI, FJ, DH, GH, CG

### **Question 4 (Nine Points)**

This question concerns the directed graph to the right. For each of the three augmenting path algorithms listed, state which of the answers gives the first two augmenting paths for finding the network flow through the graph. Included with each path is its flow, and that must be correct as well (in other words, even though answers (a) and (b) have the same paths, they specify different flows through the paths).

If an algorithm does not have a unique first two augmenting paths, simply give one answer that could result legally from that algorithm. For example, suppose both answers (a) and (e) could result as the first two paths of the Edmonds-Karp algorithm. Then either answer would be correct.



**Part 1:** The Edmonds-Karp algorithm.

**Part 2:** The modification to Dijkstra's algorithm that finds the max flow path.

Part 3: The greedy depth-first search algorithm.

#### Answers

- (a). ABCFBEFI (Flow 20), ADHFI (Flow 38). (p). ABEFI (Flow 179), ADHFI (Flow 157). (b). ABCFBEFI (Flow 20), ADHFI (Flow 106). (q). ABEFI (Flow 179), ADHI (Flow 157). (c). ABCFBEFI (Flow 20), ADHI (Flow 26). (r). ADBCFI (Flow 117), ABCFI (Flow 30). (a). **ABCFBEFI** (Flow 20), **ADHI** (Flow 106). (s). ADBCFI (Flow 117), ABDFI (Flow 82). (t). ADGHI (Flow 138), ABCFI (Flow 147). (e). ABCFI (Flow 82), ADHFI (Flow 24). (f). ABCFI (Flow 82), ADHFI (Flow 38). (*u*). **ADHFI** (Flow 38), **ABCFI** (Flow 68). (g). **ABCFI** (Flow 82), **ADHI** (Flow 26). (v). **ADHFI** (Flow 38), **ABCFI** (Flow 82). (*h*). **ABCFI** (Flow 147), **ADHFI** (Flow 24). (w). ADHFI (Flow 157), ABCFI (Flow 82). (i). ABCFI (Flow 147), ADHFI (Flow 106). (x). ADHFI (Flow 157), ABCFI (Flow 147). (*j*). **ABCFI** (Flow 147), **ADHI** (Flow 26). (y). ADHI (Flow 26), ABEFI (Flow 20). (k). ABCFI (Flow 147), ADHI (Flow 157). (z). ADHI (Flow 26), ABFI (Flow 21). (*l*). **ABEFI** (Flow 20), **ABCFI** (Flow 38). (1). ADHI (Flow 26), ADGHFI (Flow 38). (2). ADHI (Flow 26), ADGHFI (Flow 91). (*m*). **ABEFI** (Flow 20), **ADHFI** (Flow 38). (n). ABEFI (Flow 20), ADHI (Flow 26). (3). ADHI (Flow 117), ABCFI (Flow 82).
- (o). ABEFI (Flow 179), ABCFI (Flow 147).
- (4). ADHI (Flow 157), ABCFI (Flow 147).

I have included work sheets for this question. Don't hand in the work sheet. Just the answer.

# Question 5 (12 points)

You are provided with the following procedures:

```
void insertion_sort(double *array, int size);
int partition(double *array, int size, double value);
```

insertion\_sort() implements insertion sort.

**partition**() partitions an array, and works as follows: Suppose **rv** is the return value of a call to **partition**(). Then the first **rv** elements of **array** will contain values less than or equal to **value**, and the remaining (**size-rv**) elements of **array** will contain values greater than or equal to **value**.

Use these procedures to implement the fastest version of Quicksort that you can. And I mean the fastest. Don't be lazy - remember the sorting lecture and the things that make Quicksort run faster.

Here's the prototype:

```
void quick_sort(double *array, int size);
```

Note, you are only to write **quick\_sort(**). You are to assume that **insertion\_sort(**) and **partition(**) are already written.

### **Question 6 (17 points)**

Behold the header file to the right:

Implement the method **Min\_Hop\_Path()**, which finds the path from **source** to **sink** with the fewest number of hops. In other words, it finds the path that contains the fewest number of intermediate nodes. Obviously, if there is no path from **source** to **sink**, then it should return an empty list.

You may assume that when **Min\_Hop\_Path**() is called, **tmp** equals zero for all nodes.

List routines to remember:

- **push\_front**() pushes a new node on the front of a list.
- push\_back() pushes a new node on the back of a list.
- erase(iterator) erases the node to which the iterator points.
- **empty()** returns whether the list is empty.
- **begin()** returns an iterator to the beginning of the list.
- end() returns an iterator one past the end of the list..

```
#include <list>
using namespace std;
class Node {
  public:
    string name;
    list <class Edge *> adj;
    Edge *backedge;
    int tmp;
};
class Edge {
  public:
    string name;
    Node *from;
    Node *to;
    double weight;
};
class Graph {
  public:
    Node *source;
    Node *sink;
    list <Edge *> Min Hop Path();
};
```

# Work Sheet for Question 3



### Work Sheet for Question 4

