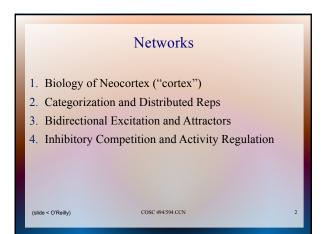
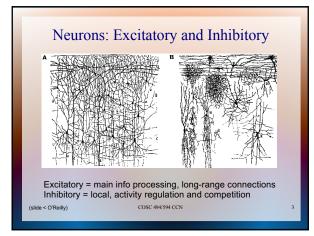
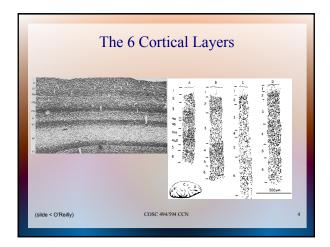
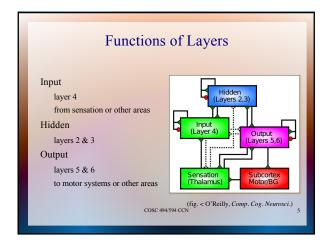
3. Networks



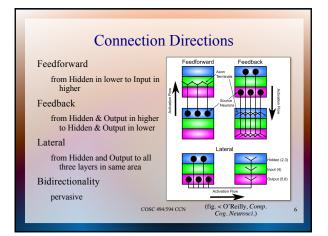


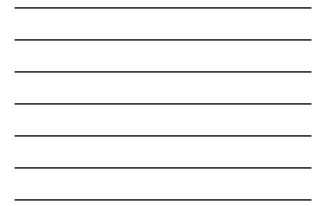


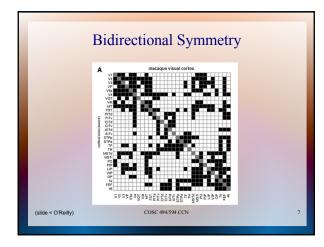










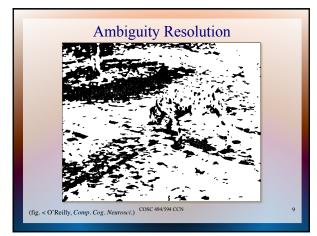


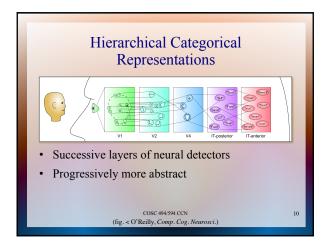


$Biology \Rightarrow Function$

- Feedforward excitation = categorization of inputs
 larger patterns, more invariant w.r.t instances & space
- Feedback excitation = attractor dynamics
 ambiguity resolution & constraint satisfaction
- Lateral inhibition = competition, activity regulation
 sharpens response

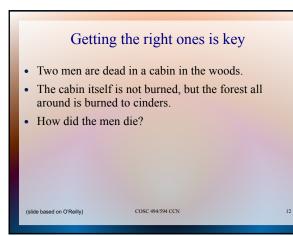
(slide based on O'Reilly) COSC 494/594 CCN











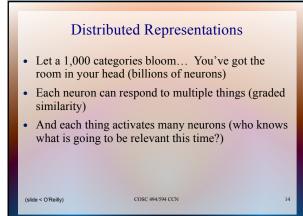
Categories: A Philosophical Problem

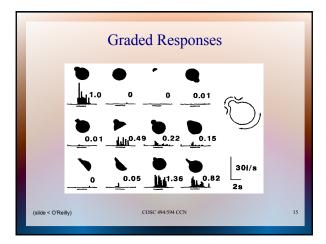
- A long-standing problem:
 - Socrates (d. 399 BCE) says, "that which we know we must surely be able to tell." (*Laches* 190c)
 - Must knowledge be encoded in language-like structures?

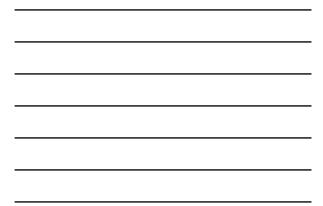
13

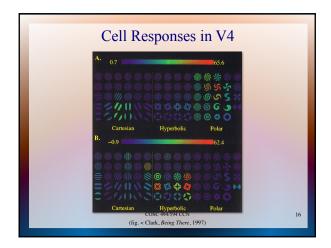
- What makes a mental categorization accurate? Is there something "real" about a "chair?"
- Stereotypes are mental categories...
- Can you encode multiple categories at the same time?

(slide based on O'Reilly) COSC 494/594 CCN

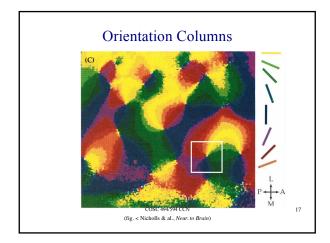




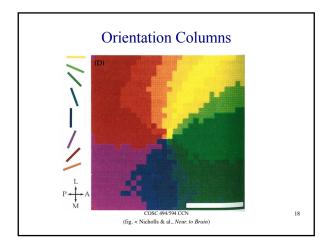




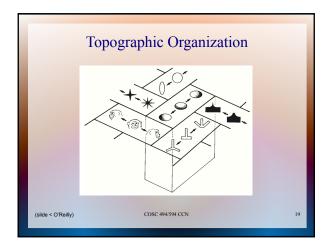




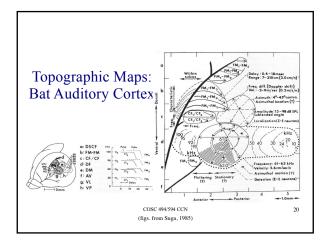


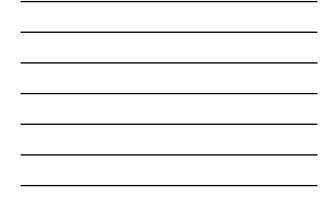


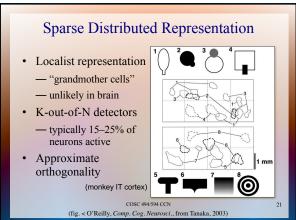


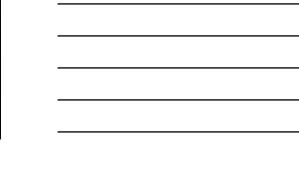


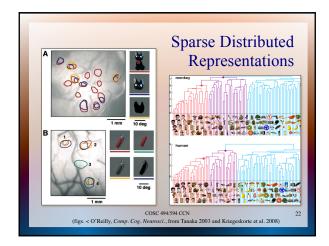




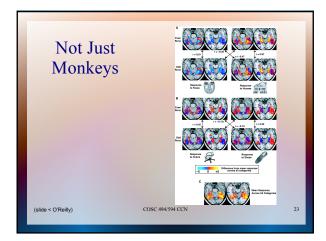




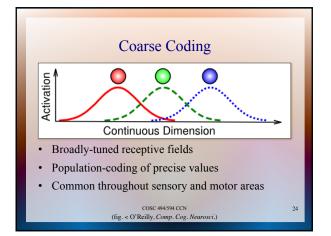








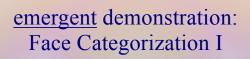


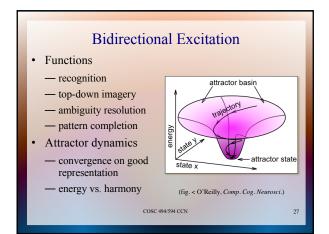


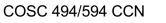


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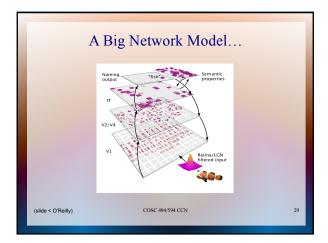




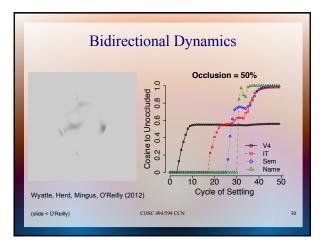








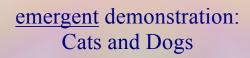








COSC 494/594 CCN

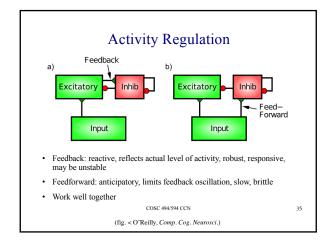


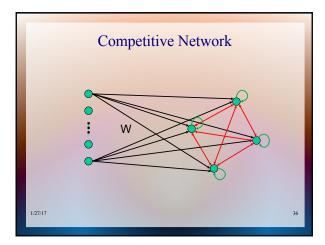
COSC 494/594 CCN

emergent demonstration: Necker Cube

Inhibitory Competition and Activity Regulation

- Activity regulation
- Selective attention
- Competition
- Sparse distributed representation







Competitive Learning

- Competitive learning network
 - two layers, randomly initialized weights
 - second is self-reinforcing, mutually inhibitory
 - "winner takes all" dynamics
- Learning
 - winner moves toward last
 - weight vectors move to centers of clusters

1/27/17

FFFB Inhibition Approximation

- Approximates total effect of all inhibition in a layer
- Inhibition determined by feedforward and feedback terms: $g_i(t) = gi[FF(t) + FB(t)]$

- FF term is excess average input over set point: FF(t) = ff[$\langle \eta \rangle$ - ff0]⁺ where $\langle \eta \rangle$ = $n^{-1} \sum_{i=1}^{n} \eta_i$ is average input
- FB term varies with average activity: $FB(t) = dt[fb\langle y \rangle - FB(t)]$ where $\langle y \rangle = n^{-1} \sum_{i=1}^{n} y_i$ is average activity
- Will stabilize with $FB(t) = fb\langle y \rangle$

