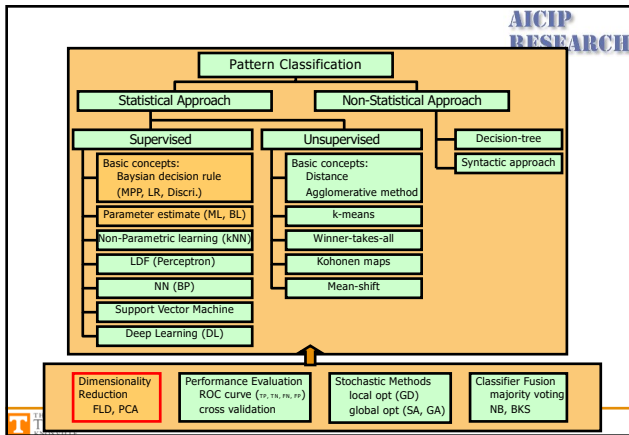



ECE471-571 – Pattern Recognition

Lecture 7 – Dimensionality Reduction – Principal Component Analysis


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Principal Component Analysis or K-L Transform

◆ How to find a new feature space (m-dimensional) that is adequate to describe the original feature space (d-dimensional). Suppose $m < d$


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K-L Transform (1)

- Describe vector \mathbf{x} in terms of a set of basis vectors \mathbf{b}_i .

$$\mathbf{x} = \sum_{i=1}^d y_i \mathbf{b}_i \quad y_i = \mathbf{b}_i^T \mathbf{x}$$

- The basis vectors (\mathbf{b}_i) should be linearly independent and orthonormal, that is,

$$\mathbf{b}_i^T \mathbf{b}_j = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases}$$

K-L Transform (2)

- Suppose we wish to ignore all but m ($m < d$) components of \mathbf{y} and still represent \mathbf{x} , although with some error. We will thus calculate the first m elements of \mathbf{y} and replace the others with constants

$$\mathbf{x} = \sum_{i=1}^m y_i \mathbf{b}_i + \sum_{i=m+1}^d y_i \mathbf{b}_i \approx \sum_{i=1}^m y_i \mathbf{b}_i + \sum_{i=m+1}^d \alpha_i \mathbf{b}_i$$

$$\text{Error: } \Delta \mathbf{x} = \sum_{i=m+1}^d (y_i - \alpha_i) \mathbf{b}_i$$

K-L Transform (3)

- Use mean-square error to quantify the error

$$\begin{aligned} \varepsilon^2(m) &= E \left\{ \sum_{i=m+1}^d \sum_{j=m+1}^d (y_i - \alpha_i) \mathbf{b}_i^T (y_j - \alpha_j) \mathbf{b}_j \right\} \\ &= E \left\{ \sum_{i=m+1}^d \sum_{j=m+1}^d (y_i - \alpha_i)(y_j - \alpha_j) \mathbf{b}_i^T \mathbf{b}_j \right\} \\ &= \sum_{i=m+1}^d E \left\{ (y_i - \alpha_i)^2 \right\} \end{aligned}$$

K-L Transform (4)

- Find the optimal α_i to minimize ε^2

$$\frac{\partial \varepsilon^2}{\partial \alpha_i} = -2(E\{y_i\} - \alpha_i) = 0$$

$$\alpha_i = E\{y_i\}$$

- Therefore, the error is now equal to

$$\varepsilon^2(m) = \sum_{i=m+1}^d E\{y_i - E\{y_i\}\}^2$$

$$= \sum_{i=m+1}^d E\{\mathbf{b}_i^T \mathbf{x} - E\{\mathbf{b}_i^T \mathbf{x}\}\}^2 = \sum_{i=m+1}^d E\{\mathbf{b}_i^T \mathbf{x} - E\{\mathbf{b}_i^T \mathbf{x}\}\}(\mathbf{x}^T \mathbf{b}_i - E\{\mathbf{x}^T \mathbf{b}_i\})$$

$$= \sum_{i=m+1}^d \mathbf{b}_i^T E\{\mathbf{x} - E\{\mathbf{x}\}\}(\mathbf{x} - E\{\mathbf{x}\})^T \mathbf{b}_i = \sum_{i=m+1}^d \mathbf{b}_i^T \Sigma_{\mathbf{x}} \mathbf{b}_i = \sum_{i=m+1}^d \lambda_i$$

K-L Transform (5)

- The optimal choice of basis vectors is the eigenvectors of $\Sigma_{\mathbf{x}}$
- The expansion of a random vector in terms of the eigenvectors of the covariance matrix is referred to as the Karhunen-Loeve expansion, or the "K-L expansion"
- Without loss of generality, we will sort the eigenvectors \mathbf{b}_i in terms of their eigenvalues. That is $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_d$. Then we refer to \mathbf{b}_1 , corresponding to λ_1 , as the "major eigenvector", or "principal component"

Summary

- Raw data \rightarrow covariance matrix \rightarrow eigenvalue \rightarrow eigenvector \rightarrow principal component
- How to use error rate?
