

Phasor Transformation

"Phasor" is a complex number that represents a sinusoid
→ useful in analyzing single-frequency sinusoidal circuits in steady-state

$$A \cos(\omega t + \phi)$$

$$A \cos(\omega t + \phi) = \operatorname{Re} \{ A e^{j\omega t} e^{j\phi} \}$$

phasor transform \downarrow
 $\rightarrow A e^{j\phi}$

$\left\{ \begin{array}{l} A \text{ amplitude} \\ \phi \text{ phase} \\ \omega \text{ frequency} \\ \cos \text{ sinusoidal} \\ t \text{ time} \end{array} \right.$

→ for single-frequency circuits
→ by convention, always use \cos
→ steady-state, single-frequency

Phasor Notation

$$v(t) = A \cos(\omega t + \varphi) = \operatorname{Re} \{ A e^{j\omega t} e^{j\varphi} \}$$

$$\begin{array}{c} \text{transform} \\ \downarrow \\ \underline{V} = A e^{j\varphi} \\ \uparrow \\ \omega \end{array}$$

$$\longleftrightarrow A \angle \varphi \text{ (short hand)}$$

Bold in book
underline in lecture

$$\begin{aligned} i(t) &= B \sin(\omega t + \theta) \\ &= B \cos(\omega t + \theta - 90^\circ) \end{aligned}$$

$$\begin{array}{c} \text{transform} \\ \downarrow \\ \underline{I} = B e^{j(\theta - \frac{\pi}{2})} \end{array}$$

$$\longleftrightarrow B \angle (\theta - \frac{\pi}{2})$$

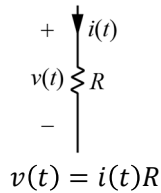
Comments:

- Phasor transform works for all voltage/current sources & signals
- Everything must be at same frequency ω
- Using complex numbers in transformation
 - No "t" in any phasor expression
 - No complex # in time domain

Phasor Circuit Elements

Time Domain

Phasor Domain



→ $\underline{V} = \underline{I}R$

$v(t) = A \cos(\omega t + \phi)$ →

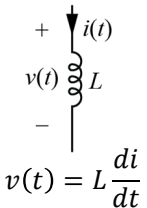
$i(t) = \frac{A}{R} \cos(\omega t + \phi)$ →

$v(t) = i(t)R$ →

$\underline{V} = A e^{j\phi}$

$\underline{I} = \frac{A}{R} e^{j\phi}$

$\underline{V} = \underline{I}R$



→ $\underline{V} = j\omega L \underline{I}$

$i(t) = A \cos(\omega t + \phi)$ →

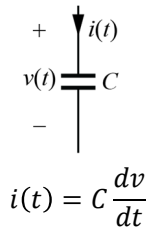
$v(t) = A L \omega \cos(\omega t + \phi + 90^\circ)$ →

$\underline{I} = A e^{j\phi}$

$\underline{V} = A \omega L e^{j(\phi + \frac{\pi}{2})}$

$\underline{V} = A j\omega L e^{j\phi}$

$\underline{V} = (j\omega L) \underline{I}$



→ $\underline{V} = \frac{-j}{\omega C} \underline{I}$

$v(t) = A \cos(\omega t + \phi)$ →

$i(t) = A C \omega \cos(\omega t + \phi + 90^\circ)$ →

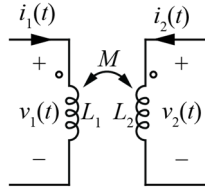
$\underline{V} = A e^{j\phi}$

$\underline{I} = A C \omega e^{j\phi} e^{j\frac{\pi}{2}}$

$\underline{I} = A j\omega C e^{j\phi}$

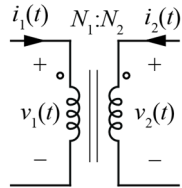
$\underline{V} = \frac{1}{j\omega C} \underline{I} = \frac{-j}{\omega C} \underline{I}$

Time Domain



$$v_1(t) = L_1 \frac{di_1}{dt} + M \frac{di_2}{dt}$$

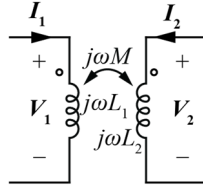
$$v_2(t) = M \frac{di_1}{dt} + L_2 \frac{di_2}{dt}$$



$$\frac{v_1(t)}{N_1} = \frac{v_2(t)}{N_2}$$

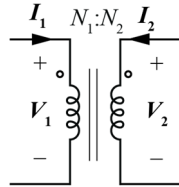
$$N_1 i_1(t) + N_2 i_2(t) = 0$$

Phasor Domain



$$\underline{V}_1 = j\omega L_1 \underline{I}_1 + j\omega M \underline{I}_2$$

$$\underline{V}_2 = j\omega M \underline{I}_1 + j\omega L_2 \underline{I}_2$$

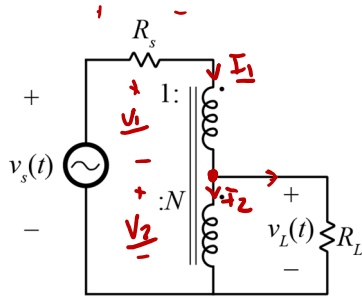


$$\frac{\underline{V}_1}{N_1} = \frac{\underline{V}_2}{N_2}$$

$$N_1 \underline{I}_1 + N_2 \underline{I}_2 = 0$$

Example Problem

$$\omega = 2\pi 60$$



Find $v_L(t)$ for $v_s(t) = 170\cos(2\pi 60t)$ and for $R_s = 10 \Omega$, $N = 0.1$, and $R_L = 50 \Omega$

$$v_L(t) \rightarrow \underline{V_L} = 170 \angle 0^\circ \quad \text{or} \quad 170 e^{j0} \quad \text{or} \quad 170 + j\phi$$

$$v_s(t) \rightarrow \underline{V_s} = 170 \angle 0^\circ$$

$$R_s \rightarrow R_s \quad R_L \rightarrow R_L$$

$$1 + \frac{1}{N} = \frac{N+1}{N}$$

$$\frac{V_1}{1} = \frac{V_2}{N}, \quad I_1 + N I_2 = 0$$

Loop

$$\underline{V_s} = \underline{V_1} + \underline{V_2} + \underline{I_1} R_s$$

$$\underline{V_s} = \left(\frac{1}{N} + 1\right) \underline{V_L} + \underline{I_1} R_s$$

$$\underline{V_2} = \left(\frac{N+1}{N}\right) \underline{V_L} + \frac{R_s}{R_L} \left(\frac{1}{N+1}\right) \underline{V_L}$$

Node:

$$\underline{I_1} = \underline{I_2} + \frac{\underline{V_L}}{R_L}$$

$$\left(1 + \frac{1}{N}\right) \underline{I_1} = \frac{\underline{V_L}}{R_L}$$

$$\underline{V_L} = \underline{V_s} \frac{1}{\frac{N+1}{N} + \frac{R_s}{R_L} \frac{1}{N+1}}$$

$$v_L(t) = 15.5 \cos(2\pi 60t + 0^\circ)$$

compute & inverse transform