

Announcements

- Experiment 2 Posted
- Guest lecture feedback (Dr. Mukhopadhyay)
 - Worked problems posted to website
- Midterm Wednesday March 6th

HW4 and Quiz 2 Notes

- $v(t)$ is always a time domain expression
 - $v(t) = V_A \cos(\omega t + \varphi)$
 - $\underline{V} = \underline{V} = A + jX = V_A e^{j\varphi} = V_A \angle \varphi$
- SI prefixes

PREFIX	ABBREVIATION	MEANING
pico-	p	0.000000000001 or 10^{-12}
nano-	n	0.000000001 or 10^{-9}
micro-	μ	0.000001 or 10^{-6}
milli-	m	0.001 or 10^{-3}
kilo	k	1,000 or 10^3
Mega-	M	1,000,000 or 10^6
Giga-	G	1,000,000,000 or 10^9
Tera-	T	1,000,000,000,000 or 10^{12}

Midterm

- Midterm Wednesday March 6th
 - Covers coupled inductors and transformers, phasor circuit analysis and complex power
 - 3 problems, ~3x quiz length, Full class period for the exam
 - Lectures 1-16, HW 1-5, Quiz 1-2, Chapters 10,11, & 13
 - Recommended:
 - Review all lecture slides and in-class examples
 - Review solutions to HW problems where you missed points
 - Rework Quizzes
 - Create crib sheet
 - Practice complex numbers on your calculator
 - Read through Experiment 1 and 2 review/introductions

Midterm Problems:

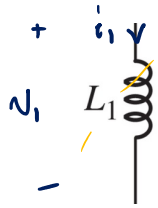
1. Phasor circuit analysis with transformer and multiple sources
 - Solve for output signal
2. Phasor circuit analysis with mutual inductances
 - Understand coupling coefficient and dot notation
 - Solve for output signal
3. Phasor power
 - Solve for and implement matched load impedance (Max Power)
 - Solve S and PF

Chapter 13

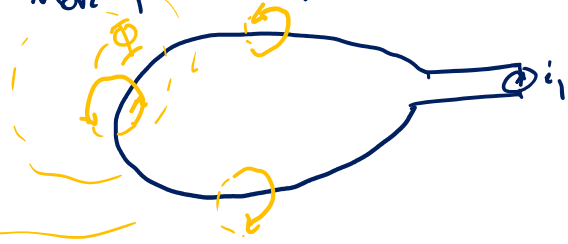
MUTUAL INDUCTANCE

Inductance: Review

We know inductor has circuit behavior $v_i = L_1 \frac{di_1}{dt}$



More fundamentally



Ampere's law $\oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 I_{enc}$
 total flux $\Phi = \alpha i_1$
 parameter depends on geometry & physical constants

for an inductor
 $\Phi = \Phi_r$
 $v_i = \alpha \frac{di_1}{dt}$
 \uparrow
 $= L$ for single-turn



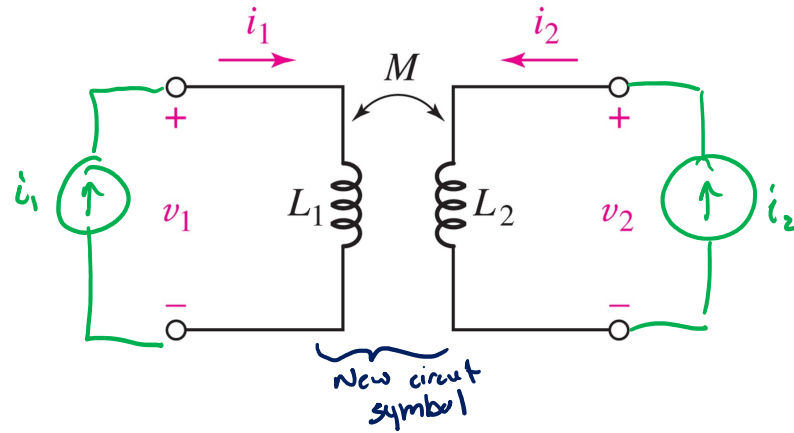
Faraday's law
 $v_i = \frac{d\Phi_r}{dt}$

For an N-turn inductor
 $\Phi = N \alpha i_1$

$$v_i = N \frac{d\Phi}{dt}$$

$$v_i = N^2 \alpha \frac{di_1}{dt}$$

Mutual Inductance



By superposition

$$\begin{cases} v_1 = L_1 \frac{di_1}{dt} + M \frac{di_2}{dt} \\ v_2 = \pm M \frac{di_1}{dt} + L_2 \frac{di_2}{dt} \end{cases}$$

Apply superposition

with $i_2 = \phi$

$$\begin{cases} v_1 = L_1 \frac{di_1}{dt} \\ v_2 = M \frac{di_1}{dt} \end{cases}$$

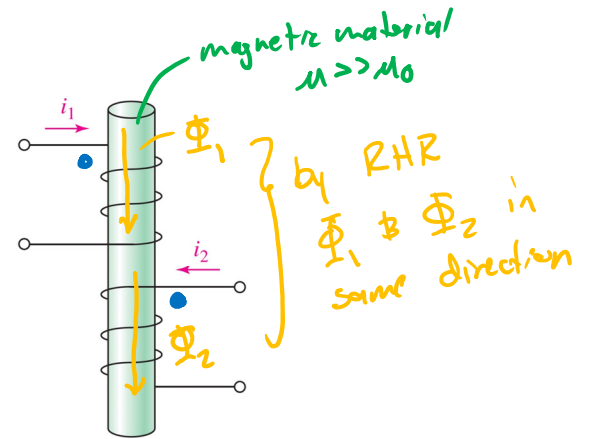
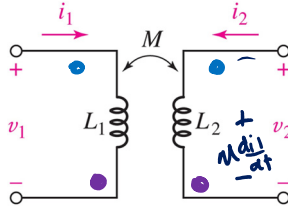
with $i_1 = \phi$

$$\begin{cases} v_1 = M \frac{di_2}{dt} \\ v_2 = L_2 \frac{di_2}{dt} \end{cases}$$

Symbols and Dot Convention

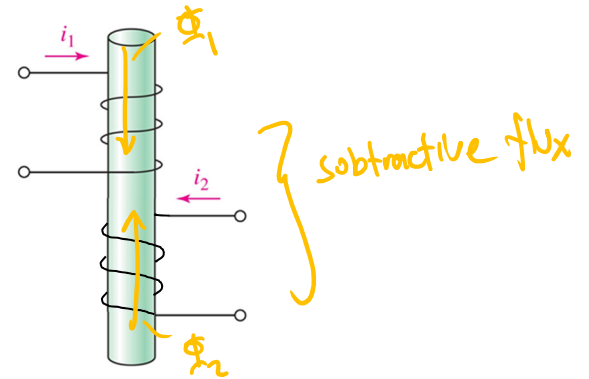
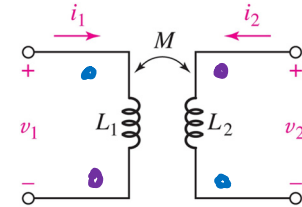
* Make sure to use passive convention sign

$$\begin{cases} v_1 = L_1 \frac{di_1}{dt} + M \frac{di_2}{dt} \\ v_2 = M \frac{di_1}{dt} + L_2 \frac{di_2}{dt} \end{cases}$$



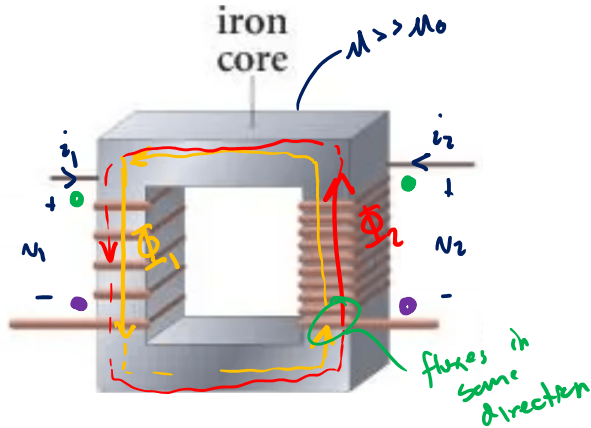
Physical: If both i_1 & i_2 enter the dotted terminals of L_1 & L_2 , they produce additive flux

$$\begin{cases} v_1 = L_1 \frac{di_1}{dt} - M \frac{di_2}{dt} \\ v_2 = -M \frac{di_1}{dt} + L_2 \frac{di_2}{dt} \end{cases}$$

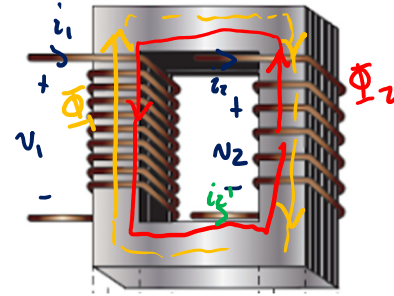


Circuit: current flowing into the dotted terminal will produce a positive voltage relative to the dotted terminal of the other winding (in open circuit)

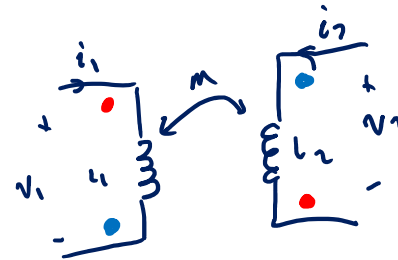
Dot Notation Example



Find which terminals should be dotted on each winding (2 possibilities)

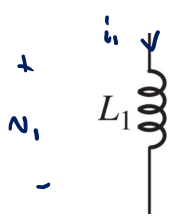


Sketch circuit symbol with same reference polarities



Energy Storage

@ $t = \phi$, $i_1 = \phi$, @ $t = t_0$, $i_1 = I_0$



Review

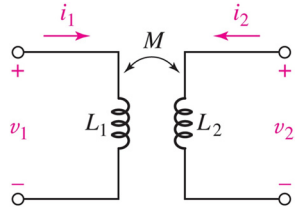
$$E_L = \int_0^{t_0} v_1 \cdot i_1 dt = \int_0^{t_0} L_1 \left[i_1 \cdot \frac{di_1}{dt} \right] dt$$

$$= \frac{1}{2} L_1 \int_0^{t_0} \frac{d}{dt} i_1(t)^2 dt = \frac{1}{2} L_1 \left[i_1(t=t_0)^2 - i_1(t=0)^2 \right]$$

$$i_1 \frac{di_1}{dt} = \frac{1}{2} \left[\frac{d}{dt} i_1(t)^2 \right]$$

$$= \frac{1}{2} \left[2 i_1(t) \frac{di_1(t)}{dt} \right]$$

$$E_L = \frac{1}{2} L_1 I_0^2$$



At $t = \phi$, $i_1 = \phi$ & $i_2 = \phi$, at $t = t_0$, $i_1 = I_1$, $i_2 = I_2$

$$E = \int_0^{t_0} (v_1 i_1 + v_2 i_2) dt$$

$$= \int_0^{t_0} \left(L_1 i_1 \frac{di_1}{dt} \pm M i_1 \frac{di_2}{dt} + L_2 i_2 \frac{di_2}{dt} \pm M i_2 \frac{di_1}{dt} \right) dt$$

$$= \frac{1}{2} L_1 I_1^2 + \frac{1}{2} L_2 I_2^2 \pm \int_0^{t_0} \left(M i_1 \frac{di_2}{dt} + M i_2 \frac{di_1}{dt} \right) dt$$

$$= M \frac{d}{dt} (i_1 \cdot i_2)$$

$$E = \frac{1}{2} L_1 I_1^2 + \frac{1}{2} L_2 I_2^2 \pm M I_1 I_2$$

starting from zero currents & ramping up to $i_1 = I_1$ & $i_2 = I_2$, must be true that

$$E = \frac{1}{2} L_1 I_1^2 + \frac{1}{2} L_2 I_2^2 \pm M I_1 I_2 > 0$$

$$M < \frac{\frac{1}{2} L_1 I_1^2 + \frac{1}{2} L_2 I_2^2}{I_1 I_2} = \frac{1}{2} L_1 \frac{I_1}{I_2} + \frac{1}{2} L_2 \frac{I_2}{I_1}$$

find minimum of $\frac{1}{2} L_1 x + \frac{1}{2} L_2 \frac{1}{x}$, $x = \frac{I_1}{I_2}$

$$\frac{\partial M}{\partial x} = \frac{1}{2} L_1 - \frac{1}{2} L_2 \frac{1}{x^2} = 0 \quad x = \sqrt{\frac{L_2}{L_1}}$$

$$\frac{\partial^2 M}{\partial x^2} = L_2 \frac{1}{x^3} \quad \checkmark$$

so,

$$M < \frac{1}{2} L_1 \sqrt{\frac{L_2}{L_1}} + \frac{1}{2} L_2 \sqrt{\frac{L_1}{L_2}} = \frac{1}{2} \sqrt{L_1 L_2} + \frac{1}{2} \sqrt{L_1 L_2}$$

$$M < \sqrt{L_1 L_2}$$

Coupling Coefficient

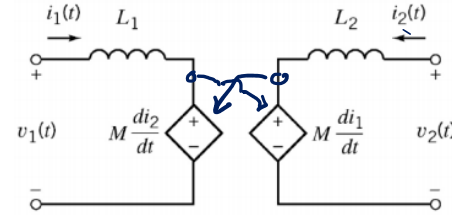
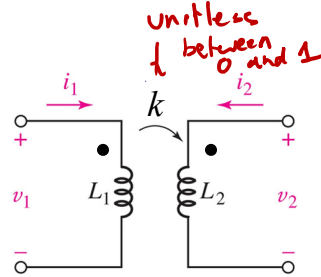
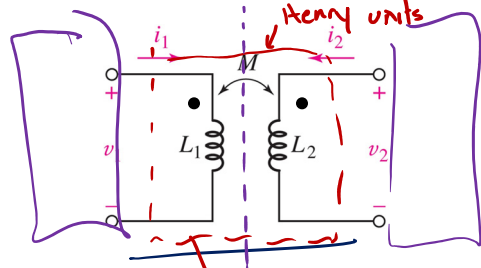
define coupling coefficient $k = \frac{M}{\sqrt{L_1 L_2}}$

$$0 \leq k \leq 1$$

$k = 0 \rightarrow$ two separate inductors

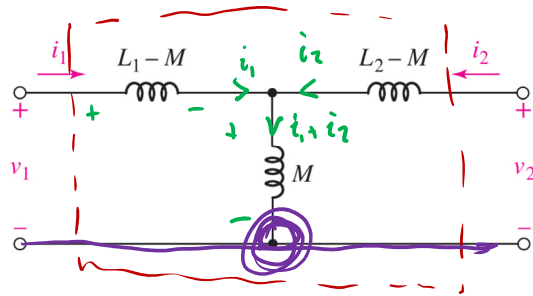
$k = 1 \rightarrow$ perfect coupling between them
all of Φ_1 flows through L_2 & vice-versa
known as a "transformer"

Equivalent Circuits



$$\begin{cases} v_1 = L_1 \frac{di_1}{dt} \pm M \frac{di_2}{dt} \\ v_2 = \pm M \frac{di_1}{dt} + L_2 \frac{di_2}{dt} \end{cases}$$

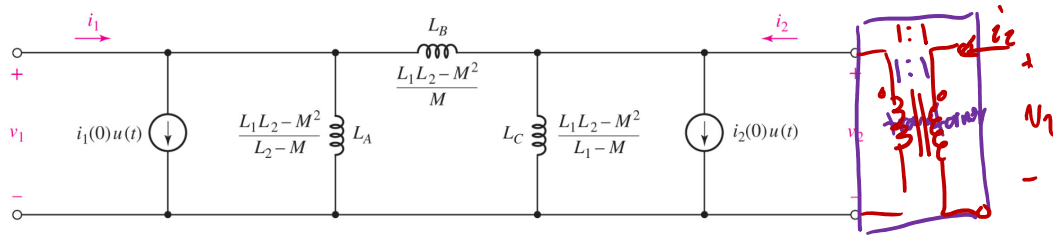
T-network



$$\begin{cases} v_1 = (L_1 - M) \frac{di_1}{dt} + M \frac{d(i_1 + i_2)}{dt} \\ v_2 = M \frac{d(i_1 + i_2)}{dt} + (L_2 - M) \frac{di_2}{dt} \end{cases}$$

for positive polarity

π-network



Transformers

Special case of coupled inductors

$$\begin{cases} V_1 = L_1 \frac{di_1}{dt} \pm M \frac{di_2}{dt} \\ V_2 = \pm M \frac{di_1}{dt} + L_2 \frac{di_2}{dt} \end{cases}$$

with $k=1 \iff$ perfect coupling $\iff M = \sqrt{L_1 L_2}$

$M = \sqrt{L_1 L_2}$



$$\begin{cases} V_1 = L_1 \frac{di_1}{dt} \pm \sqrt{L_1 L_2} \frac{di_2}{dt} \\ V_2 = \pm \sqrt{L_1 L_2} \frac{di_1}{dt} + L_2 \frac{di_2}{dt} \end{cases}$$

$$V_1 = \sqrt{\frac{L_1}{L_2}} V_2$$

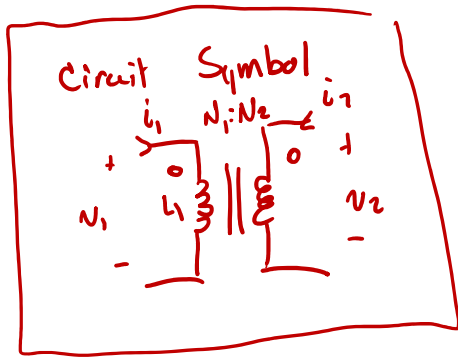


$$V_1 = \sqrt{\frac{\cancel{\alpha_1} N_1^2}{\cancel{\alpha_2} N_2^2}} V_2$$

if $k=1$, it must be true that $\alpha_1 = \alpha_2$

$$V_1 = \frac{N_1}{N_2} V_2$$

$\frac{N_1}{N_2}$ is the "turns ratio"



$N_1:N_2$ is the same as

$1:N$

$N = \frac{N_2}{N_1}$

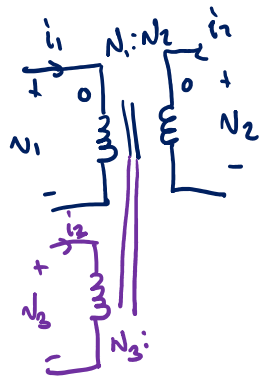
Ideal Transformer

"Ideal" transformer has very large $L_1 \& L_2$

Recall: Inductors (\neq transformers) cannot have DC voltage applied to their windings

- $V_1 = L_1 \frac{di_1}{dt} \rightarrow i_1 = \frac{1}{L_1} \int_0^t N_1 dt \rightarrow$ DC voltage causes current to go to ∞
- Materials \rightarrow core materials needed for $K \approx 1$ $\&$ will saturate $\&$ stop working at some finite current
- $V = N \frac{d\Phi}{dt} \rightarrow$ Faraday's Law, need time-varying waveforms

When $L_1 \& L_2$ are large enough \rightarrow no energy storage



$$V_1 = \frac{N_1}{N_2} V_2$$

No energy storage, so $V_1 i_1 + V_2 i_2 = \phi$

$$\left(\frac{N_1}{N_2} V_2\right) i_1 + V_2 i_2 = \phi$$

$$N_1 i_1 + N_2 i_2 = \phi$$

$$i_1 = -\frac{N_2}{N_1} i_2$$

for more than two turns \rightarrow

$$\frac{V_1}{N_1} = \frac{V_2}{N_2} = \frac{V_3}{N_3} = \dots$$

$$N_1 i_1 + N_2 i_2 + N_3 i_3 + \dots = \phi$$

Transformer Reflection

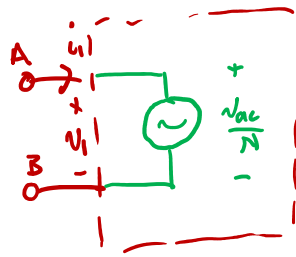
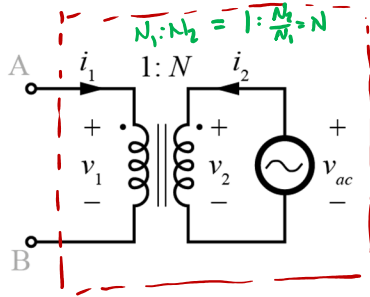
equivalent circuit @ primary

$$\frac{V_1}{I_1} = \frac{Z_2}{N^2}$$

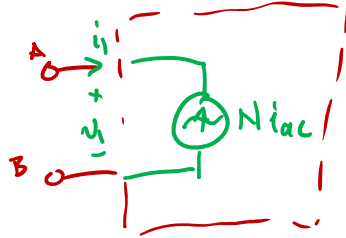
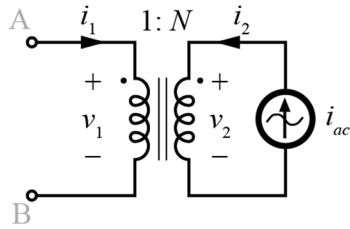
$$1i_1 + Ni_2 = \phi$$

$$N_1 = \frac{N_2}{N}$$

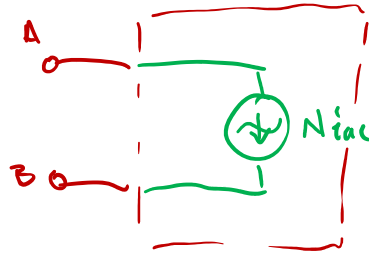
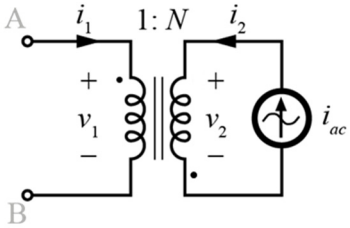
$$i_1 = -Ni_2$$



$$N_1 = \frac{N_2}{N}$$

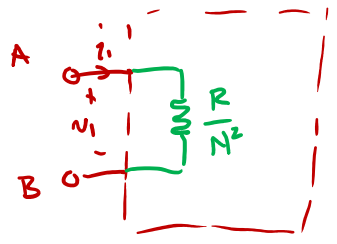
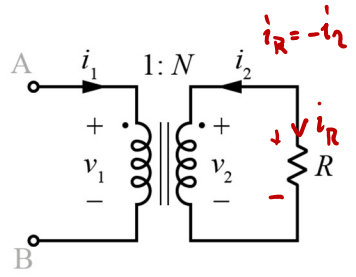


$$i_1 = -Ni_2$$



$$v_1 = \frac{1}{N} \frac{d\lambda}{dt}$$

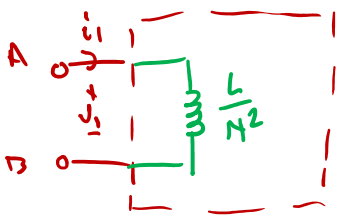
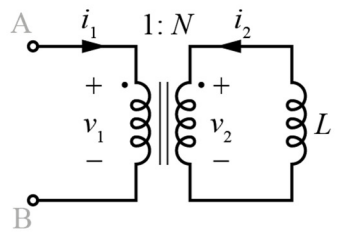
$$i_1 = -N i_2$$



$$v_2 = (-i_2) R$$

$$N v_1 = \left(\frac{1}{N}\right) i_1 R$$

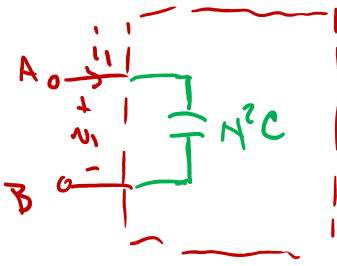
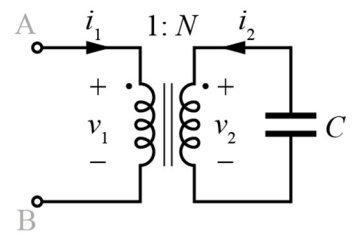
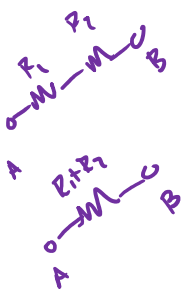
$$v_1 = \left(\frac{1}{N^2} R\right) i_1$$



$$v_2 = L \frac{d(-i_2)}{dt}$$

$$N v_1 = L \frac{d}{dt} \left(\frac{1}{N} i_1\right)$$

$$v_1 = \frac{1}{N^2} L \frac{di_1}{dt}$$



$$-i_2 = C \frac{dv_2}{dt}$$

$$\frac{1}{N} i_1 = C \frac{d}{dt} N v_1$$

$$i_1 = N^2 C \frac{dv_1}{dt}$$

Chapter 10

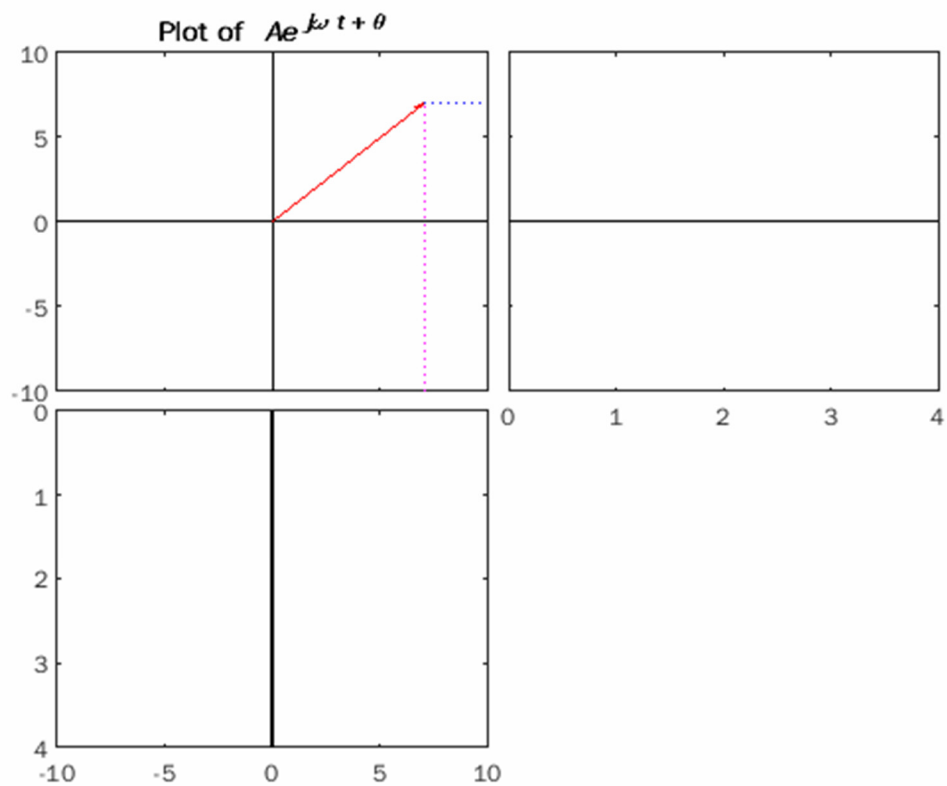
PHASOR MODELING

Sinusoids as Complex Numbers

$$\begin{aligned}v(t) &= A \cos(\omega t + \phi) \\&= \operatorname{Re} \{ A e^{j(\omega t + \phi)} \} \\&= \operatorname{Re} \{ A e^{j\omega t} e^{j\phi} \}\end{aligned}$$

cosine magnitude sinusoid phase

$$\begin{aligned}\frac{d}{dt} v(t) &= -A\omega \sin(\omega t + \phi) = A\omega \cos(\omega t + \phi + 90^\circ) \\&= \operatorname{Re} \{ A\omega e^{j\omega t} e^{j\phi} e^{j\frac{\pi}{2}} \} \\&= \operatorname{Re} \{ \underline{A(j\omega)} e^{j\omega t} e^{j\phi} \}\end{aligned}$$



Phasor Transformation

"Phasor" is a complex number that represents a sinusoid
→ useful in analyzing single-frequency sinusoidal circuits in steady-state

$$A \cos(\omega t + \phi)$$

$$A \cos(\omega t + \phi) = \operatorname{Re} \{ A e^{j\omega t} e^{j\phi} \}$$

phasor transform \downarrow
 $\rightarrow A e^{j\phi}$

$\left\{ \begin{array}{l} A \text{ amplitude} \\ \phi \text{ phase} \\ \omega \text{ frequency} \\ \cos \text{ sinusoidal} \\ t \text{ time} \end{array} \right.$

→ for single-frequency circuits
function → by convention, always use \cos
→ steady-state, single-frequency

Phasor Notation

$$v(t) = A \cos(\omega t + \varphi) = \operatorname{Re} \{ A e^{j\omega t} e^{j\varphi} \}$$

$$\begin{array}{c} \text{transform} \\ \downarrow \\ \underline{V} = A e^{j\varphi} \end{array}$$

$$\longleftrightarrow A \angle \varphi$$

(short hand)

Bold in book
underline in lecture

$$\begin{aligned} i(t) &= B \sin(\omega t + \theta) \\ &= B \cos(\omega t + \theta - 90^\circ) \end{aligned}$$

$$\begin{array}{c} \text{transform} \\ \downarrow \\ \underline{I} = B e^{j(\theta - \frac{\pi}{2})} \end{array}$$

$$\longleftrightarrow B \angle (\theta - \frac{\pi}{2})$$

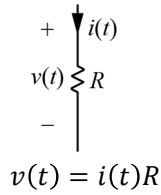
Comments:

- Phasor transform works for all voltage/current sources & signals
- Everything must be at same frequency ω
- Using complex numbers in transformation
 - No "t" in any phasor expression
 - No complex # in time domain

Phasor Circuit Elements

Time Domain

Phasor Domain



$\underline{V} = \underline{I}R$

$v(t) = A \cos(\omega t + \phi)$

$i(t) = \frac{A}{R} \cos(\omega t + \phi)$

$v(t) = i(t)R$

→

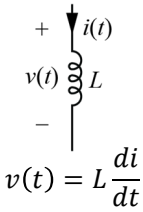
→

→

$\underline{V} = A e^{j\phi}$

$\underline{I} = \frac{A}{R} e^{j\phi}$

$\underline{V} = \underline{I}R$



$\underline{V} = j\omega L \underline{I}$

$i(t) = A \cos(\omega t + \phi)$

$v(t) = A L \omega \cos(\omega t + \phi + 90^\circ)$

→

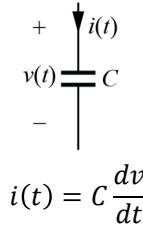
→

$\underline{I} = A e^{j\phi}$

$\underline{V} = A \omega L e^{j(\phi + \frac{\pi}{2})}$

$\underline{V} = A j\omega L e^{j\phi}$

$\underline{V} = (j\omega L) \underline{I}$



$\underline{V} = \frac{-j}{\omega C} \underline{I}$

$v(t) = A \cos(\omega t + \phi)$

$i(t) = A C \omega \cos(\omega t + \phi + 90^\circ)$

→

→

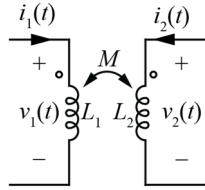
$\underline{V} = A e^{j\phi}$

$\underline{I} = A C \omega e^{j\phi} e^{j\frac{\pi}{2}}$

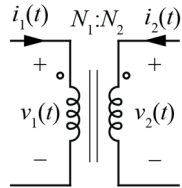
$\underline{I} = A j\omega C e^{j\phi}$

$\underline{V} = \frac{1}{j\omega C} \underline{I} = \frac{-j}{\omega C} \underline{I}$

Time Domain

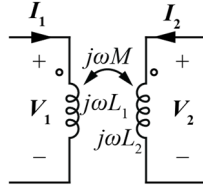


$$v_1(t) = L_1 \frac{di_1}{dt} + M \frac{di_2}{dt}$$
$$v_2(t) = M \frac{di_1}{dt} + L_2 \frac{di_2}{dt}$$

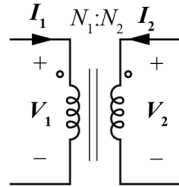


$$\frac{v_1(t)}{N_1} = \frac{v_2(t)}{N_2}$$
$$N_1 i_1(t) + N_2 i_2(t) = 0$$

Phasor Domain



$$\underline{V}_1 = j\omega L_1 \underline{I}_1 + j\omega M \underline{I}_2$$
$$\underline{V}_2 = j\omega M \underline{I}_1 + j\omega L_2 \underline{I}_2$$



$$\frac{\underline{V}_1}{N_1} = \frac{\underline{V}_2}{N_2}$$
$$N_1 \underline{I}_1 + N_2 \underline{I}_2 = 0$$

Impedance

Phasor equivalent of ohm's law

$$\underline{V} = \underline{I} Z$$

$Z \rightarrow$ "impedance"

$$Z = R + jX$$

"resistance"
 $\text{Re}\{Z\}$

"reactance"
 $\text{Im}\{Z\}$

$$Y = \text{"Admittance"} = \frac{1}{Z} = G + jB$$

"conductance" \rightarrow G \rightarrow "susceptance" \rightarrow B

\rightarrow units of siemens (or mhos)

$$\left\{ \begin{array}{l} Z_R = R \quad \text{for resistor} \\ Z_L = j\omega L \quad \text{for inductor} \\ Z_C = \frac{-j}{\omega C} \quad \text{for capacitor} \end{array} \right.$$

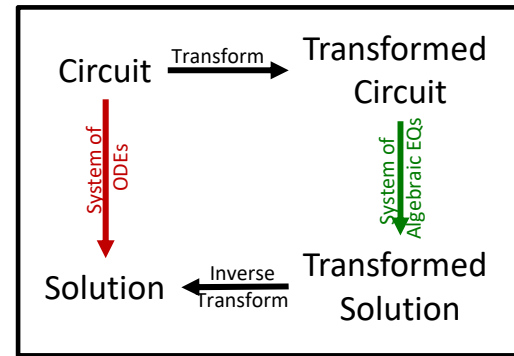
All Z have units of Ohms

$$\frac{1}{Z} \neq \frac{1}{R} + j \frac{1}{X}$$

$$\frac{1}{Z} = \frac{1}{R + jX} \frac{(R - jX)}{(R - jX)} = \frac{R - jX}{R^2 + X^2} = \frac{R}{R^2 + X^2} - j \frac{X}{R^2 + X^2}$$

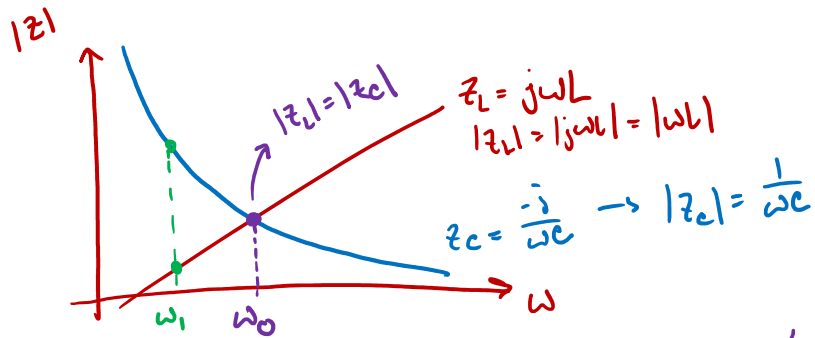
Phasor Circuit Analysis

Goal: Analyze a LTI circuit to find steady-state solution with only single-frequency sinusoidal source(s)



1. Transform all sources & signals into their phasor equivalents
2. Transform all passives into impedances
3. Solve the circuit
 - Use 201 techniques for DC resistor-only circuits
4. Transform solution back into the time domain

Reactance and Resonance



@ $\omega_0 \rightarrow |z_L| = |z_c|$

$$\omega_0 L = \frac{1}{\omega_0 C}$$

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

resonant frequency

At low frequency $\omega \rightarrow \phi$

(\approx DC) $z_c \rightarrow \infty$ (open)
 $z_L \rightarrow \phi$ (short)

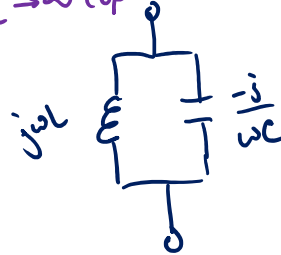
At resonance

At high frequency $\omega \rightarrow \infty$

$z_c \rightarrow \phi$ (short)
 $z_L \rightarrow \infty$ (open)

$\frac{j\omega L}{-j} \parallel \frac{-j}{\omega C} \Rightarrow$ short @ resonance (ω_0)

$$z_{eq} = j\omega L + \frac{-j}{\omega C}$$



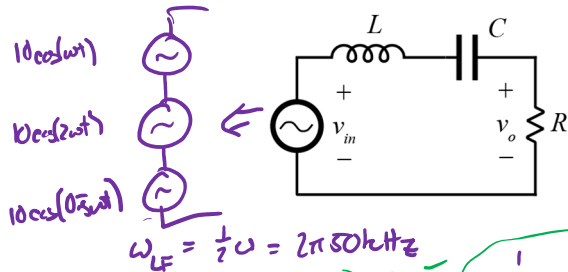
\Rightarrow open @ resonance

for only 2 in parallel

$$z_{eq} = \frac{1}{\frac{1}{j\omega L} + \frac{\omega C}{-j}} = \frac{j\omega L \cdot (-j/\omega C)}{j\omega L + \frac{-j}{\omega C}}$$

Phasor Superposition

3 frequencies \rightarrow apply superposition in time domain



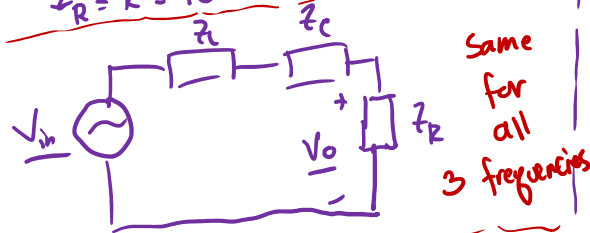
Find $v_o(t)$ for $v_{in}(t) = 10\cos(\omega t) + 10\cos(2\omega t) + 10\cos(0.5\omega t)$
and $\omega = 2\pi 100 \text{ kHz}$, $R = 10 \Omega$, $L = 10 \mu\text{H}$, and $C = 253 \text{ nF}$

$V_{in} = 10 \angle 0^\circ$
 $Z_L = j\omega_{LF} L = j\pi$
 $Z_C = \frac{-j}{\omega_{LF} C} = -j4\pi$
 $Z_R = R = 10 \Omega$

same \downarrow
 $V_o = V_{in} \frac{Z_R}{Z_L + Z_C + Z_R} = 0.73 \angle 43^\circ$
 $v_{o_{LF}}(t) = 0.73 \cos(0.5\omega t + 43^\circ)$

$\omega = 2\pi 100 \text{ kHz}$

$V_{in} = 10 \angle 0^\circ \rightarrow V_o$
 $Z_L = j\omega L = j2\pi$
 $Z_C = \frac{-j}{\omega C} = -j2\pi$
 $Z_R = R = 10$



$V_o = V_{in} \frac{Z_R}{Z_L + Z_C + Z_R} = 10 \angle 0^\circ$
 $v_o(t) = 10 \cos(\omega t)$

$\omega_{HF} = 2\omega = 2\pi 200 \text{ kHz}$

$V_{in} = 10 \angle 0^\circ$
 $Z_L = j\omega_{HF} L = j4\pi$
 $Z_C = \frac{-j}{\omega_{HF} C} = -j\pi$

$V_o = 0.73 \angle -43^\circ$

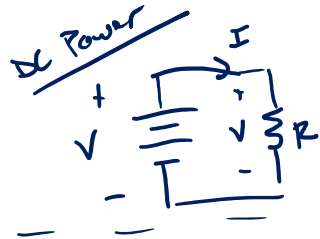
$v_{o_{HF}}(t) = 0.73 \cos(2\omega t - 43^\circ)$

$v_o(t) = 10 \cos(\omega t) + 0.73 \cos(0.5\omega t + 43^\circ) + 0.73 \cos(2\omega t - 43^\circ)$

Chapter 11

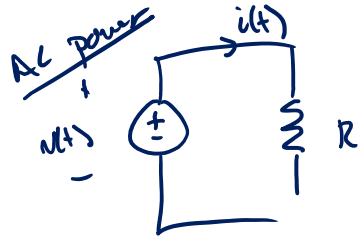
POWER IN SINUSOIDAL STEADY STATE

Average Power



$P_R = V \cdot I \rightarrow$ Generally true for any 2-terminal element

for a resistor $V = IR$
 $P_R = I^2 R = \frac{V^2}{R}$



$P_R(t) = v(t) \cdot i(t) \rightarrow$ Generally true of all 2-terminal elements

for a resistor $P_p(t) = i(t)^2 R = \frac{v(t)^2}{R}$

In any case, power calculation is not LTI

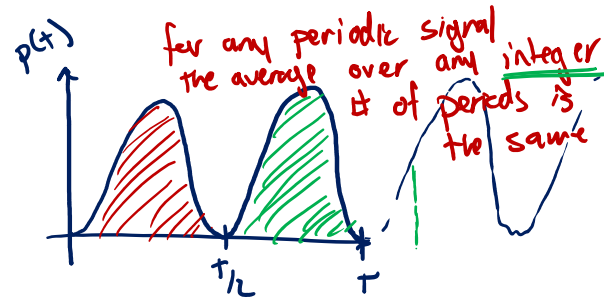
Average Power

Average power defined over some time interval $t \in [t_1, t_1 + T]$

capital "P" denotes average $\rightarrow P = \frac{1}{T} \int_{t_1}^{t_1+T} p(t) dt$

Average power over all time

$$P = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} p(t) dt$$



Power in a Resistor

Average power in a resistor with periodic (e.g. sinusoidal) sources

$$P_R = \frac{1}{T} \int_0^T P_R(t) dt = \frac{1}{T} \int_0^T i(t)^2 R dt$$
$$= R \frac{1}{T} \int_0^T i(t)^2 dt$$

$$P_R = R \sqrt{\frac{1}{T} \int_0^T i(t)^2 dt}^2$$

$$P_R = I_{rms}^2 R = \frac{V_{rms}^2}{R}$$

rms is 'root mean squared'

Define rms

$$X_{rms} = \sqrt{\frac{1}{T} \int_0^T x(t)^2 dt}$$

Note: Book calls this "effective" instead of rms

$$I_{eff} = I_{rms} \quad V_{eff} = V_{rms}$$

RMS of a sinusoid

$$\omega = 2\pi f \quad T = \frac{1}{f} = \frac{2\pi}{\omega}$$

$$i(t) = I_A \cos(\omega t + \phi)$$

$$I_{rms} = \sqrt{\frac{1}{T} \int_0^T (I_A \cos(\omega t + \phi))^2 dt}$$

$$I_{rms}^2 = \frac{1}{T} \int_0^T I_A^2 \cos^2(\omega t + \phi) dt$$

$$I_{rms}^2 = \frac{1}{T} I_A^2 \frac{1}{2} \int_0^T (1 + \cos(2\omega t + 2\phi)) dt$$

$$I_{rms}^2 = \frac{1}{T} I_A^2 \frac{1}{2} \left[t + \sin(2\omega t + 2\phi) \frac{1}{2\omega} \right] \Big|_0^{T = \frac{2\pi}{\omega}}$$

$$I_{rms}^2 = \frac{1}{T} I_A^2 \frac{1}{2} \left[\left(\frac{2\pi}{\omega} - 0 \right) + \frac{1}{2\omega} \left(\cancel{\sin(4\pi + 2\phi)} - \sin(2\phi) \right) \right]$$

$$I_{rms}^2 = \frac{\cancel{\omega}}{\cancel{2\pi}} I_A^2 \frac{1}{2} \frac{\cancel{2\pi}}{\cancel{\omega}}$$

$$I_{rms}^2 = \frac{I_A^2}{2}$$

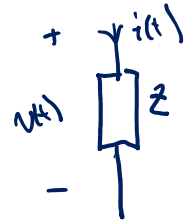
$$I_{rms} = \frac{I_A}{\sqrt{2}}$$

for any sinusoidal signal

trig identity

$$\cos^2(\theta) = \frac{1}{2}(1 + \cos 2\theta)$$

Power with Sinusoidal Sources



In steady-state with single-frequency sinusoidal sources @ ω

$$\begin{aligned} v(t) &\rightarrow \underline{V} = V_A e^{j\phi_V} \\ i(t) &= \underline{I} = I_A e^{j\phi_I} \end{aligned}$$

$$\underline{V} = \underline{I} Z$$

$$\rightarrow Z = \frac{\underline{V}}{\underline{I}} = \frac{V_A e^{j\phi_V}}{I_A e^{j\phi_I}} = \frac{V_A}{I_A} e^{j(\phi_V - \phi_I)}$$

power: since power is not LTI, we don't know how to calculate power w/ phasors
Not $\underline{V} \cdot \underline{I} \rightarrow$ go back to time domain to calculate

Trig identity: $2 \cos \theta \cos \psi = \cos(\theta + \psi) + \cos(\theta - \psi)$

$$p(t) = i(t) \cdot v(t) = I_A \cos(\omega t + \phi_I) \cdot V_A \cos(\omega t + \phi_V)$$

$$= \frac{I_A V_A}{2} \left(\underbrace{\cos(2\omega t + \phi_I + \phi_V)}_{\text{sinusoid @ } 2\omega} + \underbrace{\cos(\phi_I - \phi_V)}_{\text{constant (not time-varying)}} \right)$$

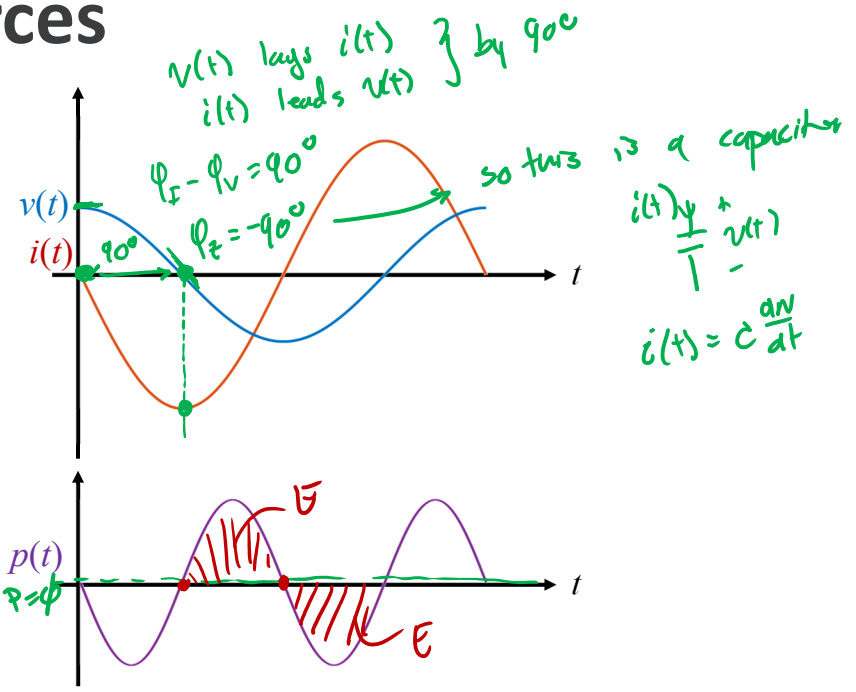
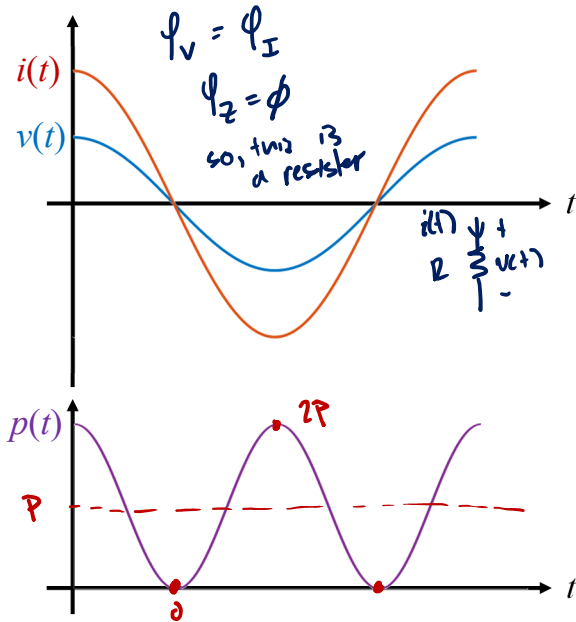
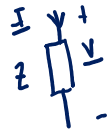
sinusoid @ 2ω

constant (not time-varying)

Average power

$$P_z = \frac{I_A V_A}{2} \cos(\phi_I - \phi_V) = \frac{I_{A_{\text{rms}}} V_{A_{\text{rms}}}}{2} \cos(\phi_z) = V_{\text{rms}} I_{\text{rms}} \cos(\phi_z)$$

Power with Sinusoidal Sources



$$P = \frac{V_A I_A}{2} \cos(\phi_V - \phi_I) = \frac{V_A I_A}{2} \cos(\phi_Z) = \frac{V_A I_A}{2} \cos(\phi) = \frac{V_A I_A}{2}$$

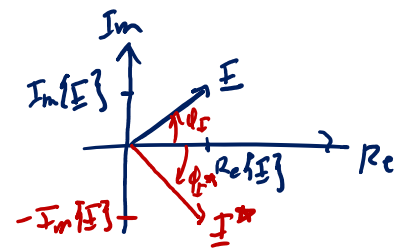
for a resistor

$$P = \frac{V_A I_A}{2} \cos(-90^\circ) = \phi$$

for a capacitor
Capacitors & inductors must have $P = \phi$ in steady-state

Complex Power

$$\begin{aligned}
 P &= \frac{V_A I_A}{2} \cos(\phi_V - \phi_I) = \left[\frac{1}{2} \operatorname{Re} \{ \underline{V} \underline{I}^* \} \right] \\
 &= \frac{1}{2} \operatorname{Re} \left\{ V_A e^{j\phi_V} \cdot I_A e^{j(-\phi_I)} \right\} \\
 &= \frac{1}{2} \operatorname{Re} \left\{ V_A I_A e^{j(\phi_V - \phi_I)} \right\} \\
 &= \frac{1}{2} V_A I_A \cos(\phi_V - \phi_I)
 \end{aligned}$$



What about the imaginary part of $\underline{V} \underline{I}^*$

$$\begin{aligned}
 S &= \frac{1}{2} \underline{V} \underline{I}^* = P + jQ \\
 \uparrow & \qquad \qquad \qquad \uparrow \qquad \qquad \qquad \uparrow \\
 \text{complex power} & \qquad \qquad \text{Average power} & \qquad \qquad \text{Reactive power} \\
 \text{[VA]} & \qquad \qquad \text{"Real power"} & \qquad \qquad \text{[VAR]} \\
 \text{Volt-amp} & \qquad \qquad \text{[W]} & \qquad \qquad \text{"volt-amp reactive"} \\
 & \qquad \qquad \text{watts} & \qquad \qquad
 \end{aligned}$$

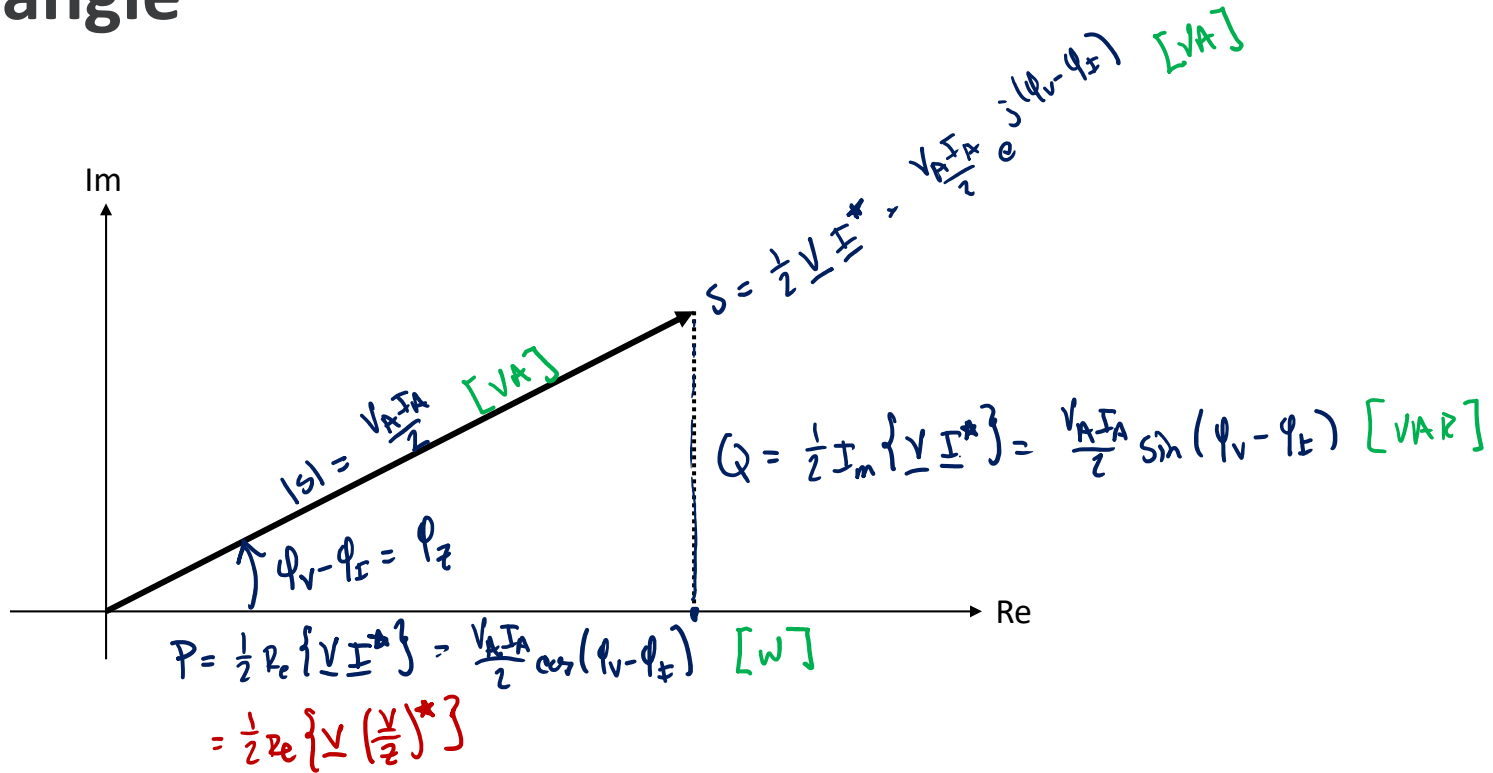
Power Triangle

$$V_A = \sqrt{2} V_{rms}$$

$$I_A = \sqrt{2} I_{rms}$$

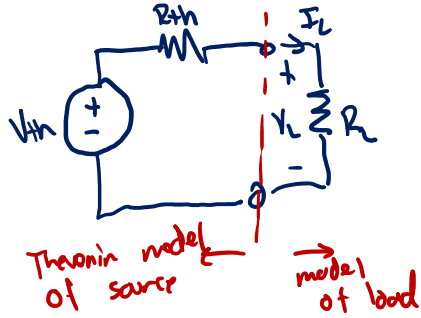
$$\phi_V - \phi_I = \phi_Z$$

$$\underline{V} = \underline{I} Z$$



$$PF = \frac{P}{|S|} = \cos(\phi_V - \phi_I) \quad \text{leading or lagging}$$

Maximum Power Transfer



what value of R_L will yield maximum power $P_L = V_L I_L$

Answer: $R_L = R_{th}$

$$P_L = V_L I_L = \left(V_{th} \frac{R_L}{R_L + R_{th}} \right) \left(\frac{V_{th}}{R_L + R_{th}} \right) = V_{th}^2 \frac{R_L}{(R_L + R_{th})^2}$$

to find extrema

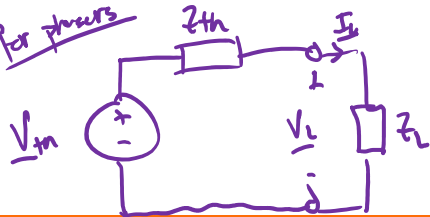
$$\frac{\partial P_L}{\partial R_L} = V_{th}^2 \left[\frac{1 \cdot (R_L + R_{th})^2 - R_L (2) (R_L + R_{th})}{(R_L + R_{th})^4} \right] = 0$$

$$0 = \frac{R_L + R_{th} - 2R_L}{(R_L + R_{th})^3} \rightarrow \text{numerator } R_{th} - R_L = 0$$

what value of R_{th} will give maximum power to a fixed R_L ?

$$R_{th} = 0$$

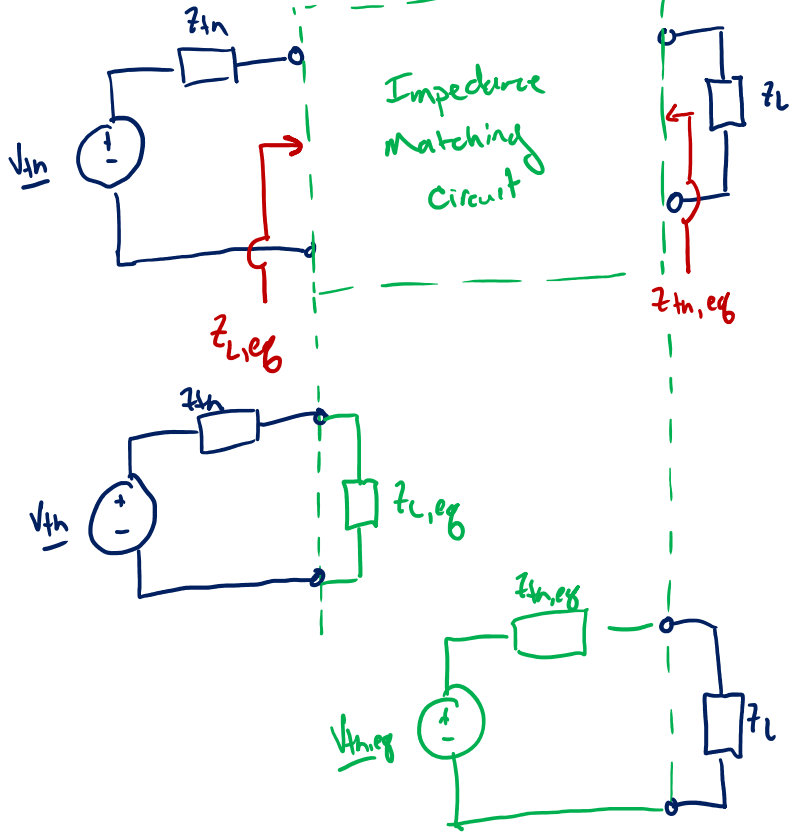
for power



what Z_L will maximize power transfer to the load?

$$Z_L = Z_{th}^*$$

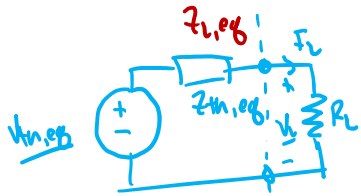
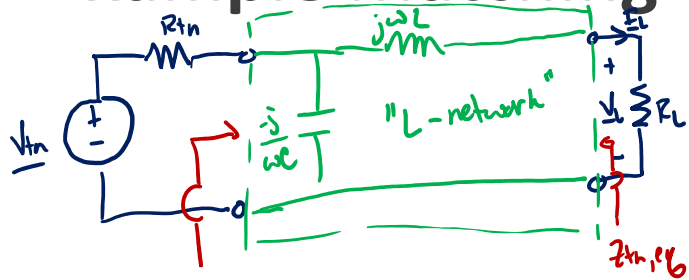
Impedance Matching



Impedance matching goals

- Maximize power transfer $\rightarrow z_L = z_{th,eq}^*$
- Minimize distortion $\rightarrow z_L = z_{th,eq}$
- Maximize efficiency $\rightarrow \text{Re}\{z_{th,eq}\} \ll \text{Re}\{z_L\}$
- Maximize Quality Factor $\rightarrow \text{Im}\{z_{L,eq}\} = \phi$

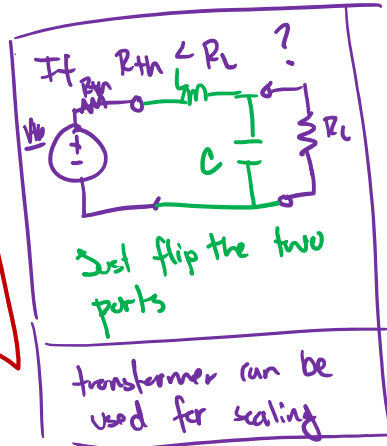
Example Matching Circuits



$$V_{th,eq} = \frac{V_{th}}{R_{th}} (R_{th} \parallel -jX_c)$$

$$X_c = \sqrt{\frac{R_L R_{th}^2}{R_{th} - R_L}}$$

$$X_L = \frac{X_c R_{th}^2}{R_{th}^2 + X_c^2}$$



$$z_{th,eq}$$

$R_{th} > R_L$, but want maximum possible power to R_L

using "L-network" set $Z_L = Z_{th,eq}^*$ or $Z_{L,og} = Z_{th}^*$

$Z_L = j\omega L = jX_L, X_L = \omega L$ | $Z_C = \frac{j}{\omega C} = -jX_C, X_C = \frac{1}{\omega C}$

$$Z_{th,eq} = (R_{th} \parallel -jX_c) + jX_L$$

$$= \frac{-jX_c R_{th}}{R_{th} - jX_c} + jX_L$$

$$= \frac{-jX_c R_{th}^2 + X_c^2 R_{th}}{R_{th}^2 + X_c^2} + jX_L$$

$$= \frac{X_c^2 R_{th}}{R_{th}^2 + X_c^2} + j \left[X_L - \frac{X_c^2 R_{th}}{R_{th}^2 + X_c^2} \right]$$

$$\text{Re}\{z_{th,eq}\} = R_L$$

$$\text{Im}\{z_{th,eq}\} = 0$$

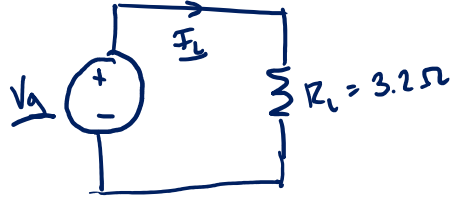
$X_c \rightarrow \infty$ $\text{Re}\{z_{th,eq}\} \rightarrow R_{th}$ } this circuit reaches
 $X_c \rightarrow 0$ $\text{Re}\{z_{th,eq}\} \rightarrow 0$ } R_{th}

Matching Example

$$\omega = 2\pi 60 \text{ Hz}$$

$$V_g = 170 \angle 0^\circ \text{ V}$$

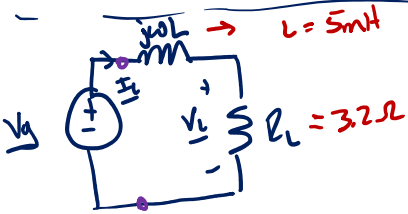
residential wall outlet is
120Vrms = 170Vpk @ 60Hz



with $R_L = 3.2 \Omega \approx$ equivalent model of plugged-in load

$$\underline{I}_L = \frac{V_g}{R_L} = \frac{170 \angle 0^\circ}{3.2} = \underline{53 \angle 0^\circ \text{ A}}$$

$$S_g = \frac{1}{2} V_g \underline{I}_L = \frac{1}{2} (170 \angle 0^\circ) (53 \angle 0^\circ) = \underline{4.5 \text{ kW} + j0 \text{ VAR}} = 4.5 \angle 0^\circ \text{ kVA}$$



$$Z_L = j(2\pi 60)(5 \times 10^{-3}) = j1.89 \Omega$$

$$\underline{I}_L = \frac{V_g}{j\omega L + R_L} = \frac{170 \angle 0^\circ}{3.2 + j1.89} = \underline{45 \angle -30^\circ \text{ A}}$$

$$\underline{V}_L = R_L \underline{I}_L = (3.2 \Omega) (45 \angle -30^\circ \text{ A}) = 146.5 \angle -30^\circ \text{ V}$$

$$P_L = \frac{1}{2} \text{Re}\{V_L \underline{I}_L^*\} = \frac{1}{2} \frac{|V_L| |I_L|}{2} \cos(\phi_{V_L} - \phi_{I_L}) = \frac{1}{2} (146.5) (45) = \underline{3.3 \text{ kW}}$$

$$S_g = \frac{1}{2} V_g \underline{I}_L^* = \frac{1}{2} (170 \angle 0^\circ) (45 \angle +30^\circ) = 3.8 \angle 30^\circ \text{ kVA} = \underline{3.3 \text{ kW}} + j \underline{1.9 \text{ kVAR}}$$

to R_L to L

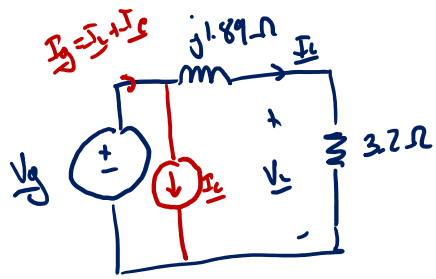
$$\text{PF}_g = \frac{P_g}{|S_g|} = \frac{3.3 \text{ kW}}{3.8 \text{ kVA}} = \underline{0.87 \text{ lagging}}$$

↳ current lags voltage

Generally, "lagging" corresponds to inductive loads
"leading" to capacitive

$$\text{PF} = \cos(\phi_V - \phi_I) = \cos(\phi_Z)$$

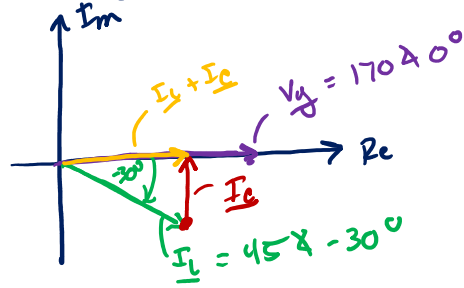
$$\phi_Z = \angle(j\omega L + R_L)$$



Can we return grid PF to unity

PF = 1, S_g is all real

$$PF = \cos(\phi_v - \phi_i)$$

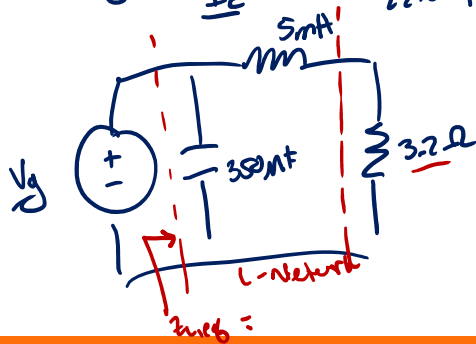


$$I_c = j I_m \{I_L\} = j 45 \sin(30^\circ)$$

$$= j 22.5 \text{ A} = 22.5 \angle +90^\circ$$

Can this be a passive impedance?

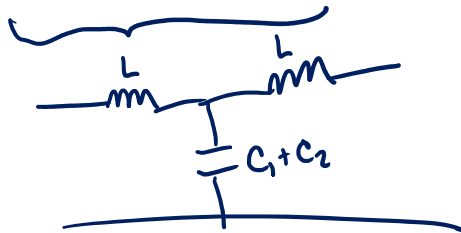
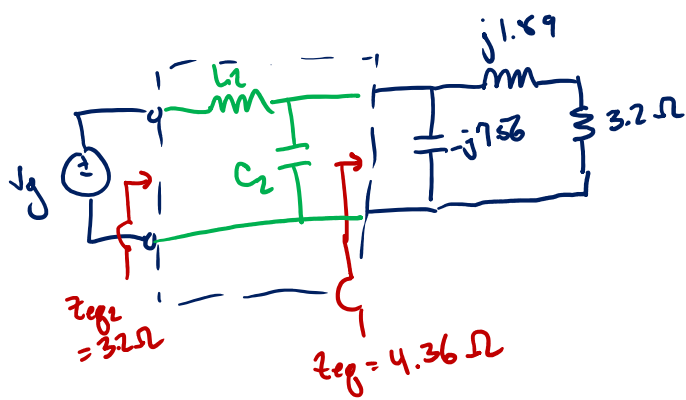
$$Z_c = \frac{V_g}{I_c} = \frac{170 \angle 0^\circ}{22.5 \angle +90^\circ} = 7.56 \angle -90^\circ = -j 7.56 \Omega = \frac{-j}{\omega C} \rightarrow C = 350 \mu\text{F}$$



$$S_g = \frac{1}{2} (V_g) (I_L + I_c)^* = \underline{3.3 \text{ kW}} + j 0 \text{ VAR}$$

$$I_g = 45 \cos(30^\circ) = 39 \text{ A}$$

$$Z_{L, \text{ req}} = \frac{V_g}{I_g} = 4.36 \Omega > 3.2 \Omega$$



from L-Network Analysis:

$$3.2 \Omega = \frac{X_{C2}^2 (4.3)}{(4.3)^2 + (X_{C2})^2}$$

$$\phi = \underline{X_{L2}} - \frac{X_{C2} (4.3)}{(4.3)^2 + (X_{C2})^2}$$

Cap: $X_{C2} = 7.4 \Omega \rightarrow C_2 = 360 \mu\text{F}$

Ind: $X_{L2} = 1.58 \Omega \rightarrow L_2 = 5 \text{mH}$

Simulation Example

