

# Initial and Final Value Theorems

## Initial Value Theorem

$$\mathcal{L}\left\{\frac{df}{dt}\right\} = \int_{0^-}^{\infty} e^{-st} \frac{df}{dt} dt = sF(s) - f(0^-)$$

$$\lim_{s \rightarrow \infty} \left[ \int_{0^-}^{0^+} e^{-st} \frac{df}{dt} dt + \int_{0^+}^{\infty} e^{-st} \frac{df}{dt} dt \right] = \lim_{s \rightarrow \infty} [sF(s) - f(0^-)]$$

$$= f(0^+) - f(0^-) = \lim_{s \rightarrow \infty} [sF(s)] - f(0^-)$$

$$\boxed{\lim_{t \rightarrow 0^+} f(t) = \lim_{s \rightarrow \infty} [sF(s)]}$$

↑ fastest part of response
↑ highest frequencies

## Final Value Theorem

$$\lim_{s \rightarrow 0} \left[ \int_{0^-}^{\infty} e^{-st} \frac{df}{dt} dt \right] = \lim_{s \rightarrow 0} [sF(s) - f(0^-)]$$

$$f(t \rightarrow \infty) - f(0^-) = \lim_{s \rightarrow 0} [sF(s)] - f(0^-)$$

$$\boxed{\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} [sF(s)]}$$

All poles in LHP

(Final value is defined)

**TABLE 14.2 Laplace Transform Operations**

Operation	$f(t)$	$\mathbf{F}(s)$
Addition	$f_1(t) \pm f_2(t)$	$\mathbf{F}_1(s) \pm \mathbf{F}_2(s)$
Scalar multiplication	$kf(t)$	$k\mathbf{F}(s)$
Time differentiation	$\frac{df}{dt}$	$s\mathbf{F}(s) - f(0^-)$
	$\frac{d^2f}{dt^2}$	$s^2\mathbf{F}(s) - sf(0^-) - f'(0^-)$
	$\frac{d^3f}{dt^3}$	$s^3\mathbf{F}(s) - s^2f(0^-) - sf'(0^-) - f''(0^-)$
Time integration	$\int_{0^-}^t f(t) dt$	$\frac{1}{s}\mathbf{F}(s)$
	$\int_{-\infty}^t f(t) dt$	$\frac{1}{s}\mathbf{F}(s) + \frac{1}{s} \int_{-\infty}^{0^-} f(t) dt$
Convolution	$f_1(t) * f_2(t)$	$\mathbf{F}_1(s)\mathbf{F}_2(s)$
Time shift	$f(t-a)u(t-a), a \geq 0$	$e^{-as}\mathbf{F}(s)$
Frequency shift	$f(t)e^{-at}$	$\mathbf{F}(s+a)$
Frequency differentiation	$tf(t)$	$-\frac{d\mathbf{F}(s)}{ds}$
Frequency integration	$\frac{f(t)}{t}$	$\int_s^{\infty} \mathbf{F}(s) ds$
Scaling	$f(at), a \geq 0$	$\frac{1}{a}\mathbf{F}\left(\frac{s}{a}\right)$
Initial value	$f(0^+)$	$\lim_{s \rightarrow \infty} s\mathbf{F}(s)$
Final value	$f(\infty)$	$\lim_{s \rightarrow 0} s\mathbf{F}(s)$ , all poles of $s\mathbf{F}(s)$ in LHP
Time periodicity	$f(t) = f(t+nT),$ $n = 1, 2, \dots$	$\frac{1}{1 - e^{-Ts}}\mathbf{F}_1(s),$ where $\mathbf{F}_1(s) = \int_{0^-}^T f(t) e^{-st} dt$

# Circuit Laplace Transform

Time Domain

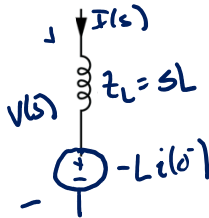
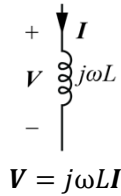
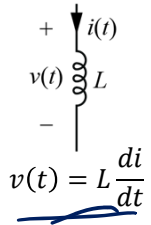
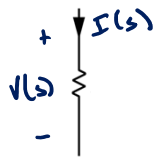
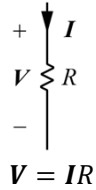
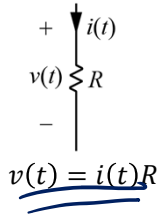
Phasor Domain

s-Domain

$$\mathcal{L}\{v(t)\} = \mathcal{L}\{i(t)R\}$$

$$V(s) = R I(s)$$

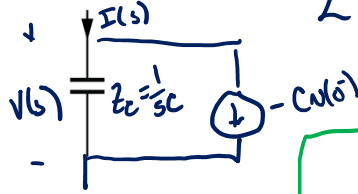
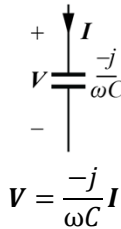
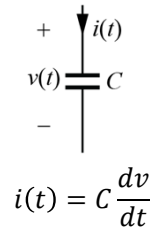
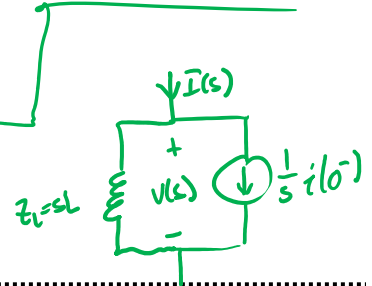
$Z_R = R \rightarrow$  still called "Impedance"



$$\mathcal{L}\{v(t)\} = \mathcal{L}\left\{L \frac{di(t)}{dt}\right\}$$

$$V(s) = sL I(s) - Li(0^-)$$

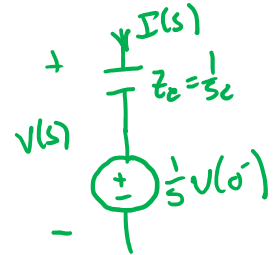
$$I(s) = \frac{V(s)}{sL} + \frac{1}{s} i(0^-)$$



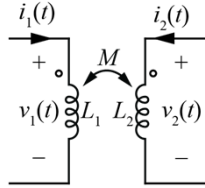
$$\mathcal{L}\{i(t)\} = \mathcal{L}\left\{C \frac{dv(t)}{dt}\right\}$$

$$I(s) = sC V(s) - C v(0^-)$$

$$V(s) = \frac{1}{sC} I(s) + \frac{1}{s} v(0^-)$$



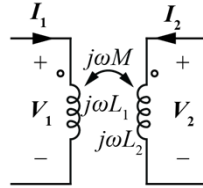
### Time Domain



$$v_1(t) = L_1 \frac{di_1}{dt} + M \frac{di_2}{dt}$$

$$v_2(t) = M \frac{di_1}{dt} + L_2 \frac{di_2}{dt}$$

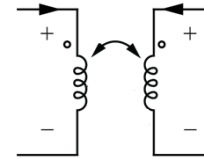
### Phasor Domain



$$V_1 = j\omega L_1 I_1 + j\omega M I_2$$

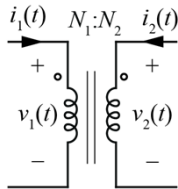
$$V_2 = j\omega M I_1 + j\omega L_2 I_2$$

### s-Domain



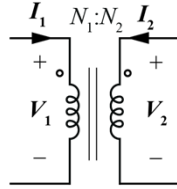
$$V_1(s) = sL_1 I_1(s) - L_1 i_1(0^-) + sM I_2(s) - M i_2(0^-)$$

$$V_2(s) = sM I_1(s) - M i_1(0^-) + sL_2 I_2(s) - L_2 i_2(0^-)$$



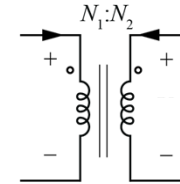
$$\frac{v_1(t)}{N_1} = \frac{v_2(t)}{N_2}$$

$$N_1 i_1(t) + N_2 i_2(t) = 0$$



$$\frac{V_1}{N_1} = \frac{V_2}{N_2}$$

$$N_1 I_1 + N_2 I_2 = 0$$



$$\frac{V_1(s)}{N_1} = \frac{V_2(s)}{N_2}$$

$$N_1 I_1(s) + N_2 I_2(s) = 0$$

# Laplace Transform of Diff EQs

$N^{\text{th}}$  order circuit with sinusoidal input described by ( $M \leq N$  for causality)

$$b_N \frac{d^N}{dt^N} v_o(t) + \dots + b_1 \frac{d}{dt} v_o(t) + b_0 v_o(t) = a_M \frac{d^M}{dt^M} v_i(t) + \dots + a_1 \frac{d}{dt} v_i(t) + a_0 v_i(t)$$

$$\sum_{i=0}^N b_i \frac{d^i}{dt^i} v_o(t) = \sum_{i=0}^M a_i \frac{d^i}{dt^i} v_i(t)$$

Then the Laplace transform of the circuit, neglecting initial conditions, is

$$\mathcal{L} \left\{ \sum_{i=0}^N b_i \frac{d^i}{dt^i} v_o(t) \right\} = \mathcal{L} \left\{ \sum_{i=0}^M a_i \frac{d^i}{dt^i} v_i(t) \right\}$$

$$\sum_{i=0}^N b_i s^i V_o(s) = \sum_{i=0}^M a_i s^i V_i(s)$$

Rearranging:

$$\boxed{\frac{V_o(s)}{V_i(s)} = \overset{\text{Transfer function}}{H(s)} = \frac{\sum_{i=0}^M a_i s^i}{\sum_{i=0}^N b_i s^i}}$$

if we replace  $s \rightarrow j\omega$   
in  $H(s)$   
we get  $H(j\omega)$ , the  
frequency response

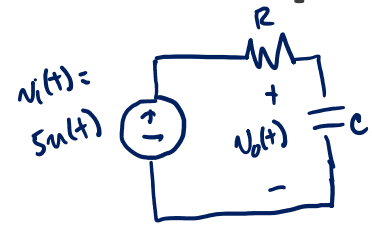
# Laplace Circuit Solution Algorithm

1. Transform all sources, signals into Laplace Domain
2. Transform circuit components (including initial conditions) into Laplace Domain
3. Solve the circuit using 201 techniques

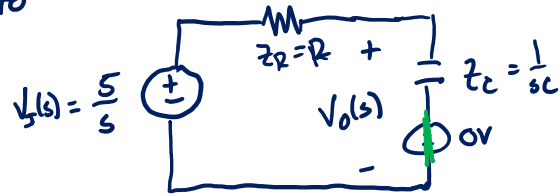
$$V_o(s) = H(s)V_i(s) = \frac{\sum_{i=0}^M a_i s^i}{\sum_{i=0}^N b_i s^i}$$

4. Inverse Laplace Transform to get back to time domain

# Example Laplace Circuit Analysis



$v_o(t) @ t \leq 0$  is zero



$v_o(t) = (5 - 5e^{-\frac{t}{RC}})u(t)$

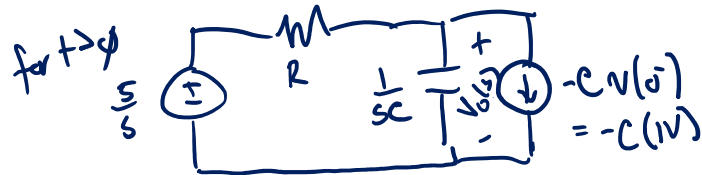
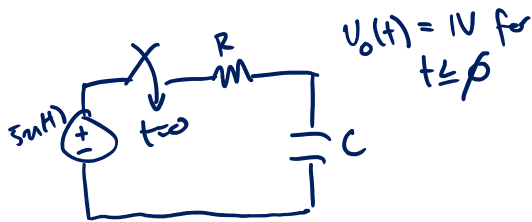


$$V_o(s) = V_i(s) \frac{Z_C}{Z_C + Z_R} = \frac{5}{s} \frac{\frac{1}{sC}}{\frac{1}{sC} + R} = \frac{5}{s} \frac{\frac{1}{RC}}{\frac{1}{RC} + s}$$

$$v_o(t) = \mathcal{L}^{-1}\{V_o(s)\} = \mathcal{L}^{-1}\left\{\frac{A}{s} + \frac{B}{\frac{1}{RC} + s}\right\} = \mathcal{L}^{-1}\left\{\frac{5}{s} + \frac{-5}{\frac{1}{RC} + s}\right\}$$

PFE (more review coming)

$$v(t) = \mathcal{L}^{-1}\left\{\frac{5}{s}\right\} + \mathcal{L}^{-1}\left\{\frac{-5}{\frac{1}{RC} + s}\right\} = \boxed{5u(t) - 5e^{-\frac{t}{RC}}u(t)}$$



$$V_o(s) = V_I(s) \frac{Z_C}{Z_C + Z_R} + C(1V) \left[ R \parallel \frac{1}{sC} \right]$$