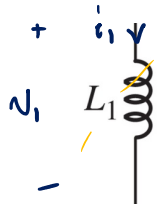
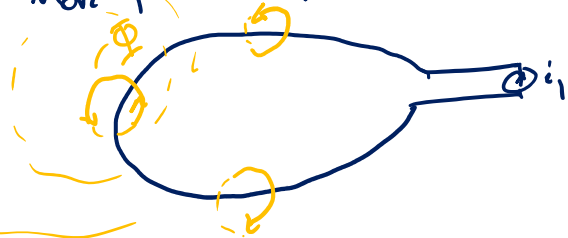


Inductance: Review

We know inductor has circuit behavior $v_l = L_1 \frac{di_1}{dt}$



More fundamentally



Ampere's law $\oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 I_{enc}$
 total flux $\Phi = \propto i_1$
 parameter depends on geometry & physical constants

for an inductor
 $\Phi = \Phi_r$
 $v_l = \alpha \frac{di_1}{dt}$
 \uparrow
 $= L$ for single-turn



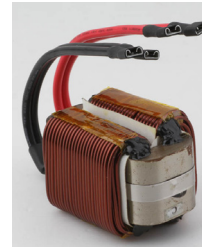
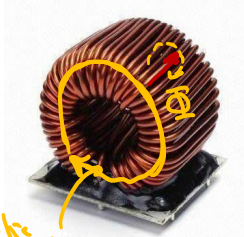
Faraday's law
 $v_l = \frac{d\Phi_r}{dt}$

For an N-turn inductor
 $\Phi = N \alpha i_1$

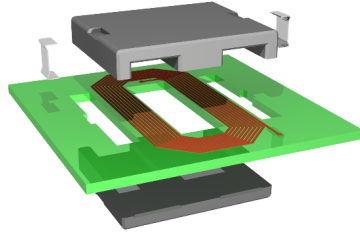
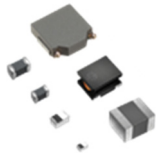
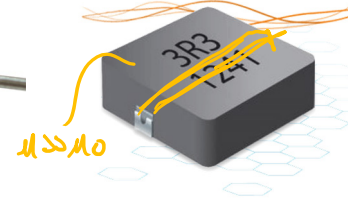
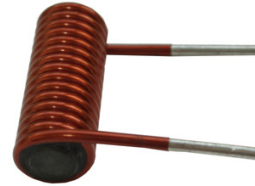
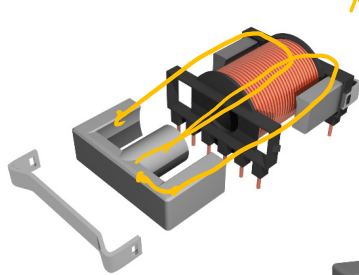
$$v_l = N \frac{d\Phi}{dt}$$

$$v_l = N^2 \alpha \frac{di_1}{dt}$$

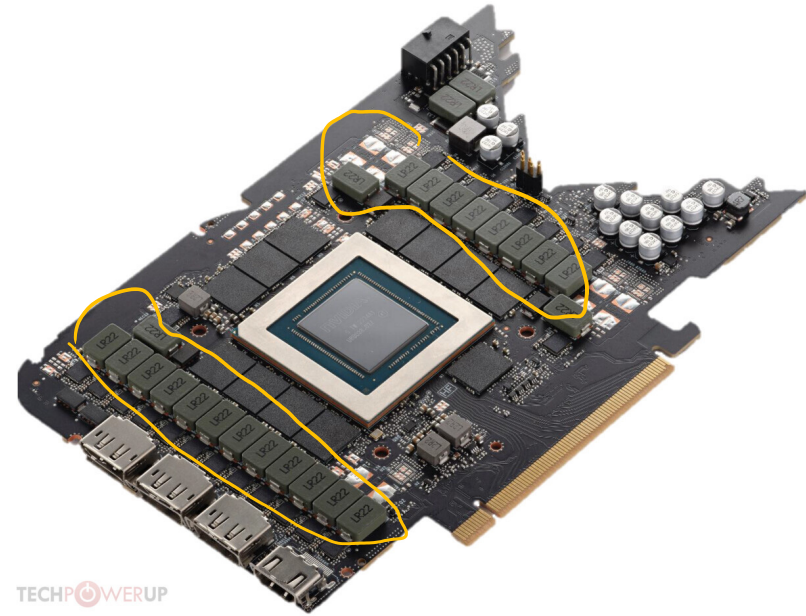
Some Inductor Examples



magnetic material
 $\mu \gg \mu_0$

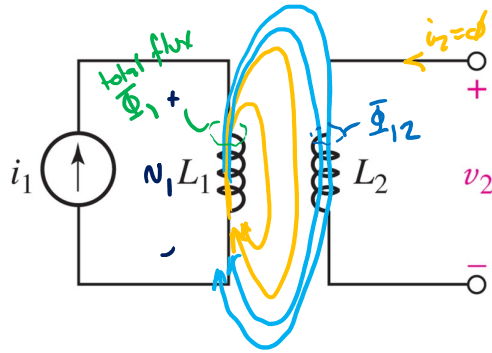


Example Desktop Motherboard and GPU



Magnetic Coupling

→ flux from one inductor goes through coils of another inductor



Case 1: $i_1 > \phi$ $i_2 = d$

L_1 behaves as before

$$\Phi_1 = \alpha_1 N_1 i_1$$

$$V_1 = N_1 \frac{d\Phi_1}{dt}$$

$$V_1 = \alpha_1 N_1^2 \frac{di_1}{dt}$$

$$L_1 = \alpha_1 N_1^2$$

Because Φ_{12} flows through L_2

$$V_2 = N_2 \frac{d\Phi_{12}}{dt}$$

$$\Phi_{12} = \alpha_{12} N_1 i_1$$

$$V_2 = \alpha_{12} N_1 N_2 \frac{di_1}{dt}$$

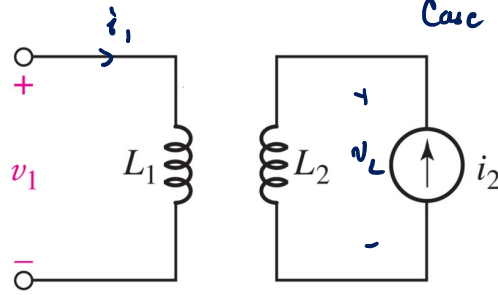
$$M = \alpha_{12} N_1 N_2$$

mutual Inductance

$$V_1 = L_1 \frac{di_1}{dt}$$

$$V_2 = M \frac{di_1}{dt}$$

Magnetic Coupling



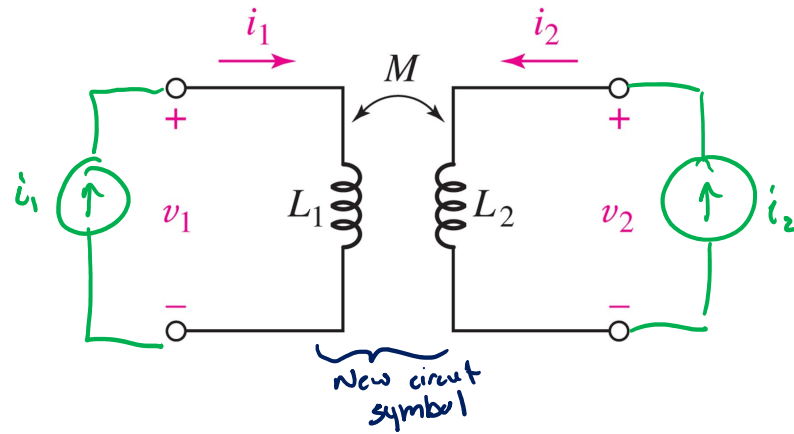
Case 2: $i_1 = \phi$, $i_2 \neq \phi$

same circuit just mirrored

$$\begin{cases} v_2 = L_2 \frac{di_2}{dt} \\ v_1 = M \frac{di_2}{dt} \end{cases}$$

$\alpha_{12} = \alpha_{21} \rightarrow$ so M is the same in both sets of equations

Mutual Inductance



By superposition

$$\begin{cases} v_1 = L_1 \frac{di_1}{dt} + M \frac{di_2}{dt} \\ v_2 = \pm M \frac{di_1}{dt} + L_2 \frac{di_2}{dt} \end{cases}$$

Apply superposition

with $i_2 = \phi$

$$\begin{cases} v_1 = L_1 \frac{di_1}{dt} \\ v_2 = M \frac{di_1}{dt} \end{cases}$$

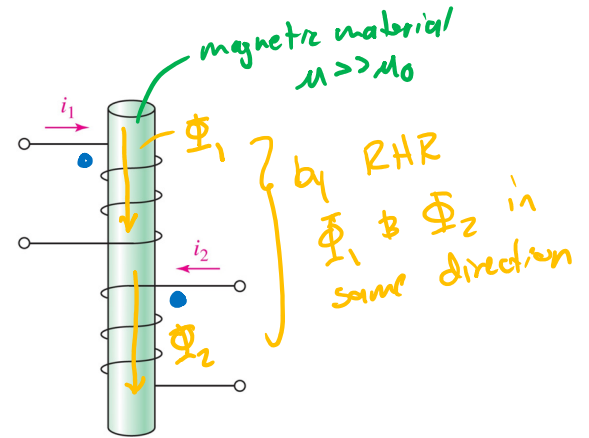
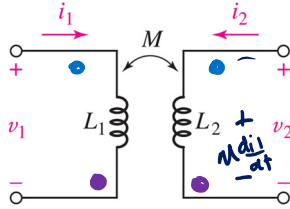
with $i_1 = \phi$

$$\begin{cases} v_1 = M \frac{di_2}{dt} \\ v_2 = L_2 \frac{di_2}{dt} \end{cases}$$

Symbols and Dot Convention

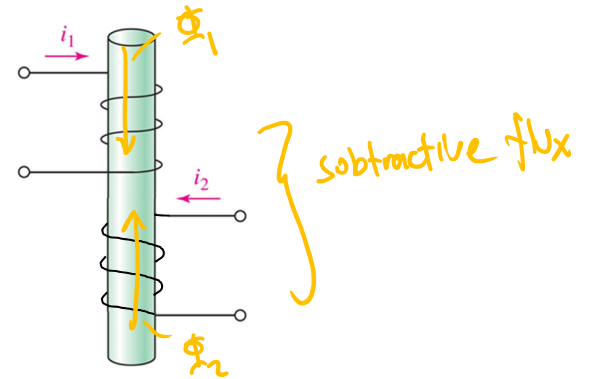
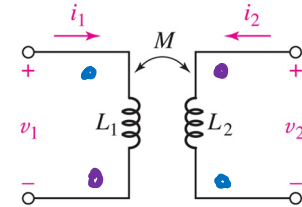
* Make sure to use passive convention sign

$$\begin{cases} v_1 = L_1 \frac{di_1}{dt} + M \frac{di_2}{dt} \\ v_2 = M \frac{di_1}{dt} + L_2 \frac{di_2}{dt} \end{cases}$$



Physical: If both i_1 & i_2 enter the dotted terminals of L_1 & L_2 , they produce additive flux

$$\begin{cases} v_1 = L_1 \frac{di_1}{dt} - M \frac{di_2}{dt} \\ v_2 = -M \frac{di_1}{dt} + L_2 \frac{di_2}{dt} \end{cases}$$



Circuit: current flowing into the dotted terminal will produce a positive voltage relative to the dotted terminal of the other winding (in open circuit)