

Announcements

- Return Analog Discovery Studio
- Office Hours
 - No (Dr. Costinett) Wednesday office hours due to EECS faculty meeting
 - Available via e-mail; Thursday office hours as normal
- TNvoice Open
 - Please fill out – Closes midnight May 8
 - +5 pts EC on final for 100% response rate

Final Exam

- Thursday May 9th, 3:30-6:00pm
- Roughly 2x midterm in length, w/ 3x time
- Covers all course material
 - Chapters 10-11, 13-15 & 17(partial)
 - All homeworks, quizzes, exams, and experiments 1-3
 - All lectures

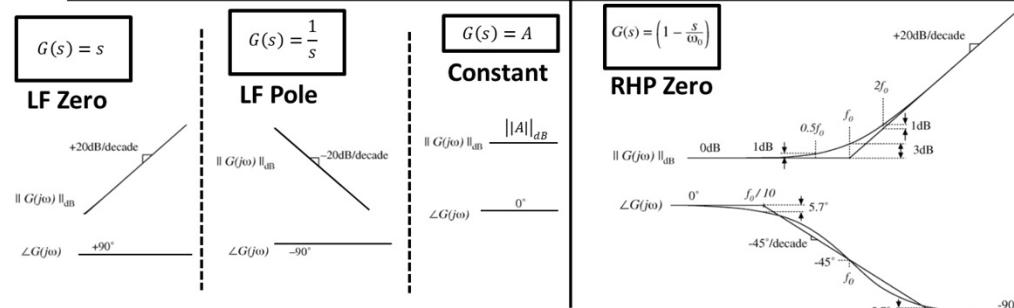
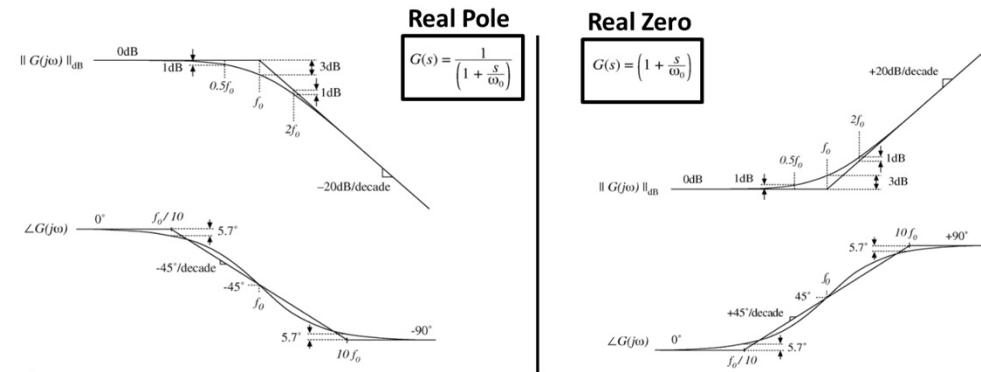
Final Exam Problems (Tentative)

- Power and impedance matching with sinusoidal input
- Bode plot ($\text{plot} \rightarrow H(s)$ and/or $H(s) \rightarrow \text{plot}$)
- Identify bounded/stable systems
- Solve Laplace with complex and repeated poles and zeroes
- Evaluate Fourier Series and frequency response
- Solve and compare different descriptions of circuit (e.g. $H(s)$, $h(t)$, Phasor circuit, etc.)
- Additional Notes:
 - Circuits will contain
 - coupled inductors and/or transformers
 - op-amps

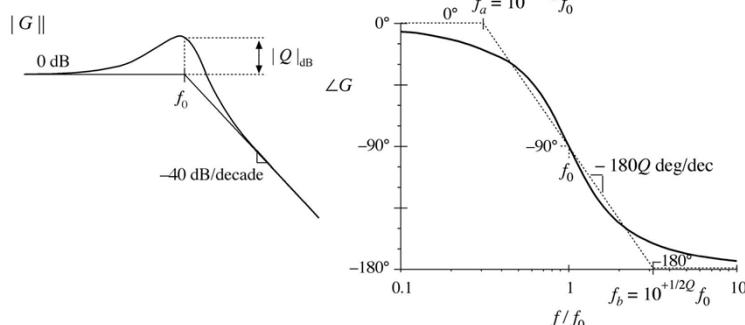
Exam Tables

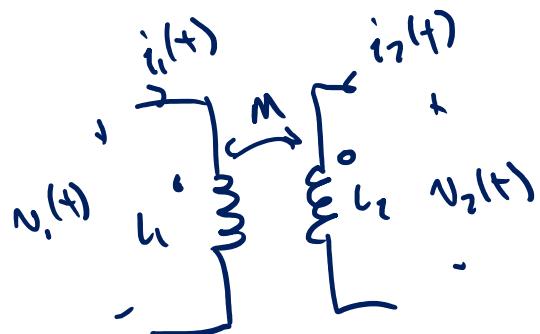
TABLE 14.1 Laplace Transform Pairs

$f(t) = \mathcal{L}^{-1}\{\mathbf{F}(s)\}$	$\mathbf{F}(s) = \mathcal{L}\{f(t)\}$	$f(t) = \mathcal{L}^{-1}\{\mathbf{F}(s)\}$	$\mathbf{F}(s) = \mathcal{L}\{f(t)\}$
$\delta(t)$	1	$\frac{1}{\beta - \alpha}(e^{-\alpha t} - e^{-\beta t})u(t)$	$\frac{1}{(s + \alpha)(s + \beta)}$
$u(t)$	$\frac{1}{s}$	<u>$\sin \omega t u(t)$</u>	$\frac{\omega}{s^2 + \omega^2}$
$t u(t)$	$\frac{1}{s^2}$	$\cos \omega t u(t)$	$\frac{s}{s^2 + \omega^2}$
$\frac{t^n - 1}{(n - 1)!} u(t), n = 1, 2, \dots$	$\frac{1}{s^n}$	$\sin(\omega t + \theta) u(t)$	$\frac{s \sin \theta + \omega \cos \theta}{s^2 + \omega^2}$
$e^{-\alpha t} u(t)$	$\frac{1}{s + \alpha}$	$\cos(\omega t + \theta) u(t)$	$\frac{s \cos \theta - \omega \sin \theta}{s^2 + \omega^2}$
$t e^{-\alpha t} u(t)$	$\frac{1}{(s + \alpha)^2}$	$e^{-\alpha t} \sin \omega t u(t)$	$\frac{\omega}{(s + \alpha)^2 + \omega^2}$
$\frac{t^n - 1}{(n - 1)!} e^{-\alpha t} u(t), n = 1, 2, \dots$	$\frac{1}{(s + \alpha)^n}$	$e^{-\alpha t} \cos \omega t u(t)$	$\frac{s + \alpha}{(s + \alpha)^2 + \omega^2}$
$2 k e^{\sigma t} \cos(\omega t - \angle k) u(t)$		$\frac{k}{s - (\sigma + j\omega)} + \frac{k^*}{s - (\sigma - j\omega)}$	
Operation	$f(t)$	$\mathbf{F}(s)$	
Addition	$f_1(t) \pm f_2(t)$	$\mathbf{F}_1(s) \pm \mathbf{F}_2(s)$	
Scalar multiplication	$k f(t)$	$k \mathbf{F}(s)$	
Time differentiation	$\frac{df}{dt}$	$s \mathbf{F}(s) - f(0^-)$	
	$\frac{d^2 f}{dt^2}$	$s^2 \mathbf{F}(s) - s f(0^-) - f'(0^-)$	
	$\frac{d^3 f}{dt^3}$	$s^3 \mathbf{F}(s) - s^2 f(0^-) - s f'(0^-) - f''(0^-)$	
Time integration	$\int_{0^-}^t f(t) dt$	$\frac{1}{s} \mathbf{F}(s)$	
	$\int_{-\infty}^t f(t) dt$	$\frac{1}{s} \mathbf{F}(s) + \frac{1}{s} \int_{-\infty}^{0^-} f(t) dt$	
Convolution	$f_1(t) * f_2(t)$	$\mathbf{F}_1(s) \mathbf{F}_2(s)$	
Time shift	$f(t - a)u(t - a), a \geq 0$	$e^{-as} \mathbf{F}(s)$	
Frequency shift	$f(t)e^{-at}$	$\mathbf{F}(s + a)$	
Frequency differentiation	$i f(t)$	$-\frac{d \mathbf{F}(s)}{ds}$	
Frequency integration	$\frac{f(t)}{t}$	$\int_s^\infty \mathbf{F}(s) ds$	
Scaling	$f(at), a > 0$	$\frac{1}{a} \mathbf{F}\left(\frac{s}{a}\right)$	
Initial value	$f(0^+)$	$\lim_{s \rightarrow \infty} s \mathbf{F}(s)$	
Final value	$f(\infty)$	$\lim_{s \rightarrow 0} s \mathbf{F}(s)$, all poles of $s \mathbf{F}(s)$ in LHP	
Time periodicity	$f(t) = f(t + nT), n = 1, 2, \dots$	$\frac{1}{1 - e^{-Ts}} \mathbf{F}_1(s)$, where $\mathbf{F}_1(s) = \int_{0^-}^T f(t) e^{-st} dt$	



Complex Poles





$$\left\{ \begin{array}{l} V_1(t) = L_1 \frac{di_1}{dt} + M \frac{di_2}{dt} \\ V_2(t) = L_2 \frac{di_2}{dt} + M \frac{di_1}{dt} \end{array} \right. \quad \text{Time}$$

$$\underline{V}_1 = L_1(j\omega) \underline{I}_1 + M(j\omega) \underline{I}_2$$

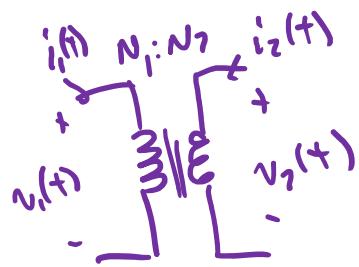
$$\underline{V}_2 = L_2(j\omega) \underline{I}_2 + M(j\omega) \underline{I}_1$$

Phasor

Laplace:

$$V_1 = L_1(s I_1 - i_1(0^-)) + M(s I_2 - i_2(0^-))$$

$$V_2 = L_2(s I_2 - i_2(0^-)) + M(s I_1 - i_1(0^-))$$



$$\frac{N_1(t)}{N_1} = \frac{V_2(t)}{N_2}$$

$$N_1 i_1(t) + N_2 i_2(t) = \phi$$

Time

Phasor

$$\frac{\underline{V}_1}{N_1} = \frac{\underline{V}_2}{N_2} \quad \nabla \quad N_1 \underline{I}_1 + N_2 \underline{I}_2 = \phi$$

Laplace

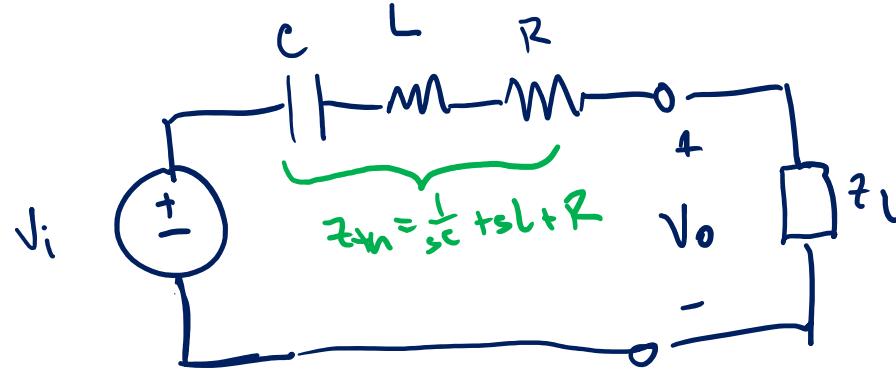
$$\frac{V_1(s)}{N_1} = \frac{V_2(s)}{N_2} \quad \nabla \quad N_1 I_1(s) + N_2 I_2(s) = \phi$$

$$P(s) = \frac{7s^2 + 3s + 1}{11s^2 + 2s + 5}$$

M=N, order of numerator = order of denominator

$$\begin{array}{r} 7 \\ s^2 + 2s + 5 \overline{) 7s^2 + 3s + 1} \\ - 7s^2 - 14s - 35 \\ \hline 0 - 11s - 34 \end{array}$$

$$P(s) = 7 + \frac{-11s - 34}{s^2 + 2s + 5}$$



Find Z_L that maximizes P_{out} (Real power to Z_L)

For max power transfer

$$Z_L = Z_{th}^*$$

$$Z_{th} = R + j(\omega L - \frac{1}{\omega C})$$

$$Z_L = Z_{th}^* = R - j(\omega L - \frac{1}{\omega C})$$

$$\begin{aligned} Y_L &= \frac{1}{Z_L} = \frac{R + j(\omega L - \frac{1}{\omega C})}{R^2 + (\omega L - \frac{1}{\omega C})^2} \\ &= G + jB \end{aligned}$$

$$\text{if } \omega L > \omega C$$

$$Z_L = R - jX$$

$$\begin{aligned} X &> \phi \\ \frac{j}{\omega C} &= -jX \end{aligned}$$

$$\begin{aligned} \frac{1}{C} &= \frac{1}{\omega X} \\ \frac{1}{C} &= \frac{1}{\omega X} \quad G \xrightarrow{\parallel} \frac{1}{\omega X} \\ \frac{1}{C} &= \frac{1}{\omega X} \quad jB \xrightarrow{\parallel} \frac{1}{\omega X} \end{aligned}$$

$$\text{if } \omega L < \omega C$$

$$Z_L = R + jX$$

$$\begin{aligned} X &> \phi \\ j\omega L &= jX \end{aligned}$$

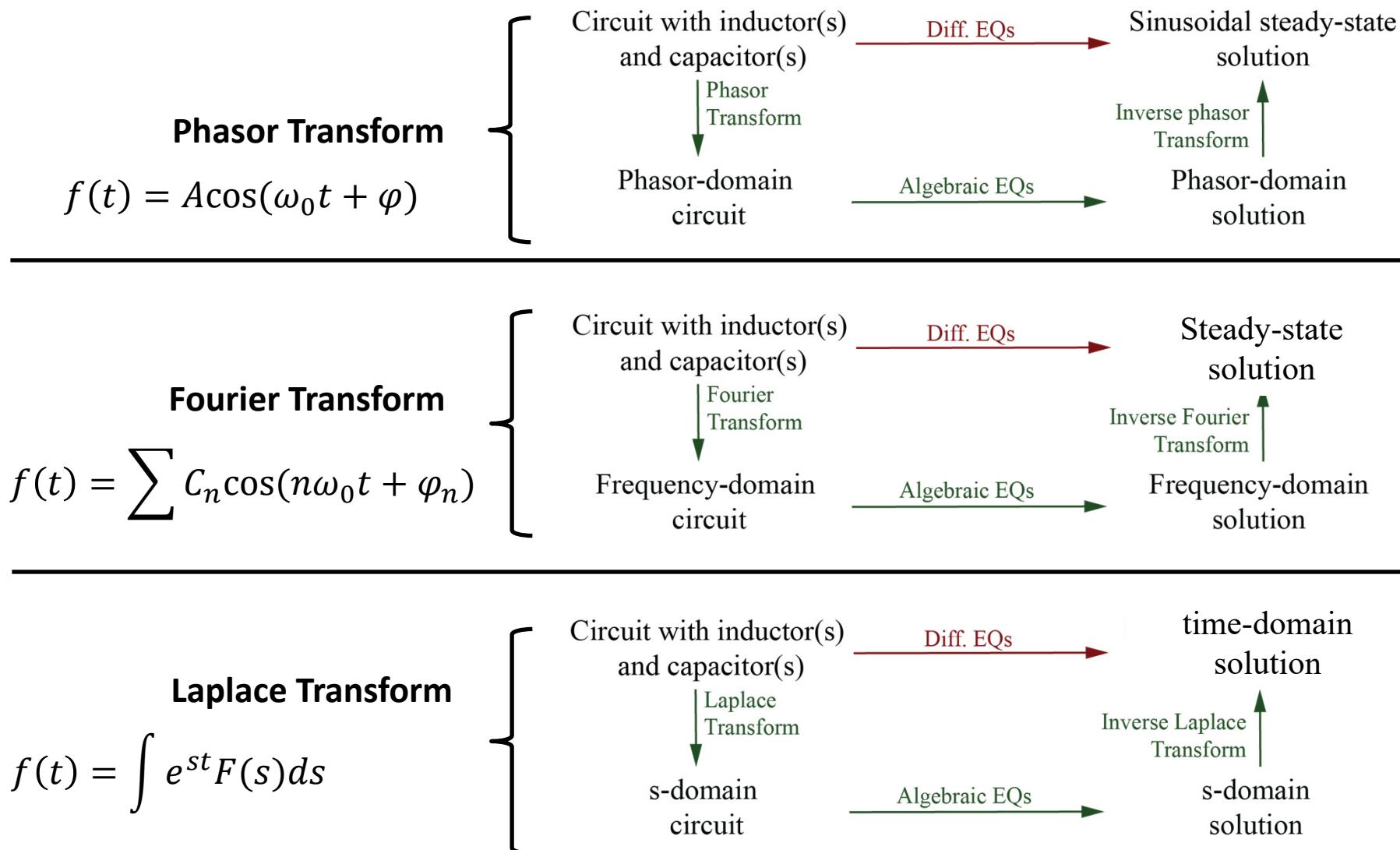
$$\begin{aligned} \frac{1}{L} &= \frac{1}{\omega} \\ \frac{1}{L} &= \frac{1}{\omega} \quad G \xrightarrow{\parallel} \frac{1}{\omega} \\ \frac{1}{L} &= \frac{1}{\omega} \quad jB \xrightarrow{\parallel} \frac{1}{\omega} \end{aligned}$$

COURSE REVIEW

Course Content

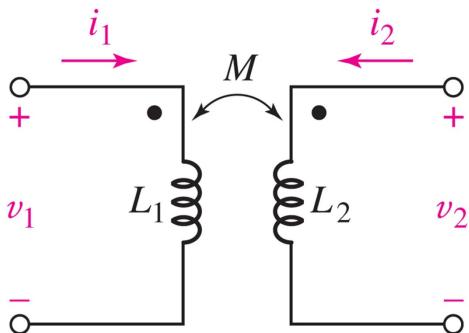
- Magnetically Coupled Circuits (Ch 13)
- Sinusoidal Steady-State Analysis (Ch 10)
- AC Circuit Power Analysis (Ch 11)
- Circuit An Analysis in the s-Domain (Ch 14)
- Frequency Response (Ch 15)
- Fourier Circuit Analysis (Ch 17)
- Polyphase Circuits (Ch 12)
- Two-Port Networks (Ch 16)

Transform Domains



Ch 13 – Magnetically Coupled Circuits

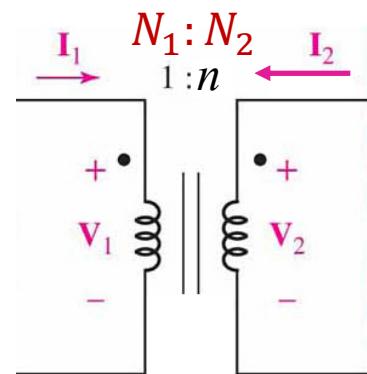
Coupled Inductors



Defining Equations

$$v_1(t) = L_1 \frac{di_1}{dt} + M \frac{di_2}{dt}$$
$$v_2(t) = M \frac{di_1}{dt} + L_2 \frac{di_2}{dt}$$

Ideal Transformer



Defining Equations

$$\frac{V_1}{N_1} = \frac{V_2}{N_2} = \dots$$

$$0 = N_1 I_1 + N_2 I_2 + \dots$$

Dot convention

- Current into the dot on one terminal produces a positive open circuit voltage w.r.t. the dot on the other

Recall

- Equivalent circuits

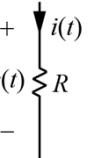
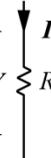
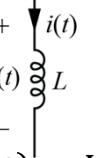
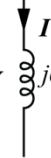
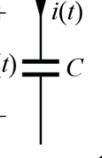
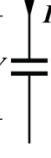
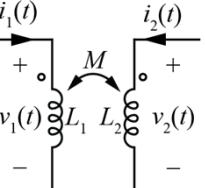
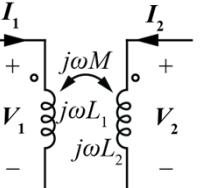
Coupled inductors with:

- no energy storage ($L \rightarrow \infty$)
- Perfect coupling ($k=1$)

Recall

- Z/V/I reflection

Ch 10 – Sinusoidal Steady State

<u>Time Domain</u>	<u>Phasor Domain</u>
 $v(t) = i(t)R$	 $V = IR$
 $v(t) = L \frac{di}{dt}$	 $V = j\omega LI$
 $i(t) = C \frac{dv}{dt}$	 $V = \frac{-j}{\omega C} I$
 $v_1(t) = L_1 \frac{di_1}{dt} + M \frac{di_2}{dt}$ $v_2(t) = M \frac{di_1}{dt} + L_2 \frac{di_2}{dt}$	 $V_1 = j\omega L_1 I_1 + j\omega M I_2$ $V_2 = j\omega M I_1 + j\omega L_2 I_2$

Phasor Notation

$$\begin{aligned} \text{Acos}(\omega t + \varphi) &\Leftrightarrow A\angle\varphi \\ &= \text{Re}\{Ae^{j(\omega t+\varphi)}\} \\ &= \text{Re}\{\text{Acos}(\omega t + \varphi) + j\text{Asin}(\omega t + \varphi)\} \end{aligned}$$

Impedance and Admittance

$$\begin{array}{ccc} Z = R + jX & & \\ \uparrow & \nearrow & \\ \text{Impedance} & \text{Resistance} & \text{Reactance} \\ \uparrow & \nearrow & \\ Y = \frac{1}{Z} = G + jB & & \\ \uparrow & \nearrow & \\ \text{Admittance} & \text{Conductance} & \text{Susceptance} \end{array}$$

Circuit Analysis

- Real circuits always have all real signals in the time domain
- All 201 analysis techniques apply
- Gives only forced/steady-state/particular response, for single sinusoidal source
- Phasor superposition

Ch 11 – AC Power Analysis

Average (DC) Power: $P = \int_{-\infty}^{\infty} p(t)dt$

For periodic signals: $P = \int_{t_0}^{t_0+T} p(t)dt$

Average power in a resistor: $P_R = \left[\underbrace{\sqrt{\int i(t)^2 dt}}_{I_{rms} = I_{eff}} \right]^2 R$

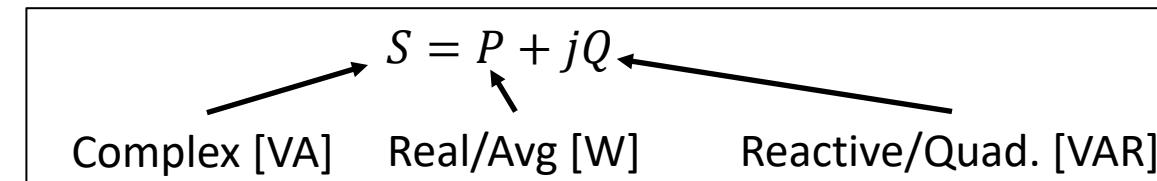
Sinusoidal Power

$$p(t) = [V_A \cos(\omega t + \varphi_V)][I_A \cos(\omega t + \varphi_I)]$$

$$= \underbrace{\frac{V_A I_A}{2} \cos(2\omega t + \varphi_V + \varphi_I)}_{\text{Double-frequency}} + \underbrace{\frac{V_A I_A}{2} \cos(\varphi_V - \varphi_I)}_{\text{DC = average}}$$
$$\frac{V_A I_A}{2} = V_{rms} I_{rms}$$

Complex Power

$$S = \frac{\mathbf{V}\mathbf{I}^*}{2} = \mathbf{V}_{rms}\mathbf{I}_{rms}$$



Apparent Power: $|S| = \frac{V_A I_A}{2} = V_{rms} I_{rms}$

Power Factor: $PF = \frac{P}{|S|}$ (leading/lagging)

Impedance match for max power transfer: $Z_L = Z_{th}^*$

Ch 14 – Laplace Transform

Unilateral Laplace Transform:

$$F(s) = \mathcal{L}\{f(t)\} = \int_{0^-}^{\infty} e^{-st} f(t) dt$$

Inverse Laplace Transform:

$$f(t) = \mathcal{L}^{-1}\{F(s)\} = \frac{1}{2\pi j} \text{ (circled)} \int_{\sigma_0 - j\infty}^{\sigma_0 + j\infty} F(s) e^{st} ds$$

, σ_0 in ROC
(to the right of all poles in complex plane)

Complex frequency = Laplace variable = $s = \sigma + j\omega$

Laplace transform is a **linear transformation**. Other properties and transforms in tables

Inverse Transforms: *Long Division → Factor → PFE → Tables*

PFE Special cases:

Repeated: $\frac{N(s)}{(s+5)^2} = \frac{k_1}{s+5} + \frac{k_2}{(s+5)^2}$ (Differentiation or coefficient matching)

Complex: $\frac{N(s)}{s^2 + 4} = \frac{k_1 s + k_2}{s^2 + 4} = \frac{k_1}{s - j2} + \frac{k_1^*}{s + j2}$

Other properties from tables including delay and time periodicity

Ch 14 – Laplace Circuit Analysis

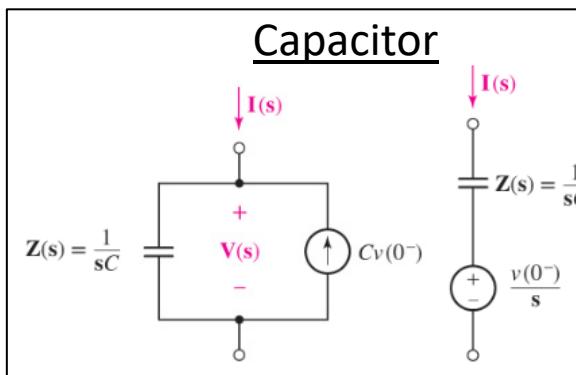
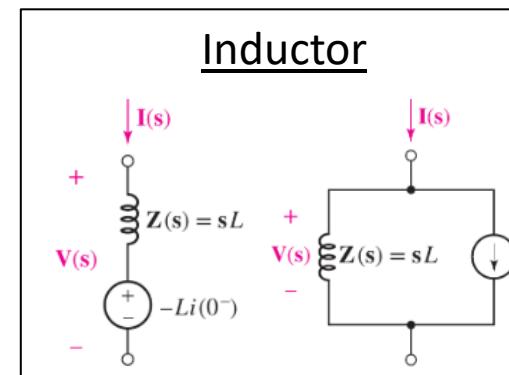
Poles and Zeros:

$$F(s) = \frac{N(s)}{D(s)}$$

Zeros: roots of $N(s)$

Poles: roots of $D(s)$

Circuit Transformation:



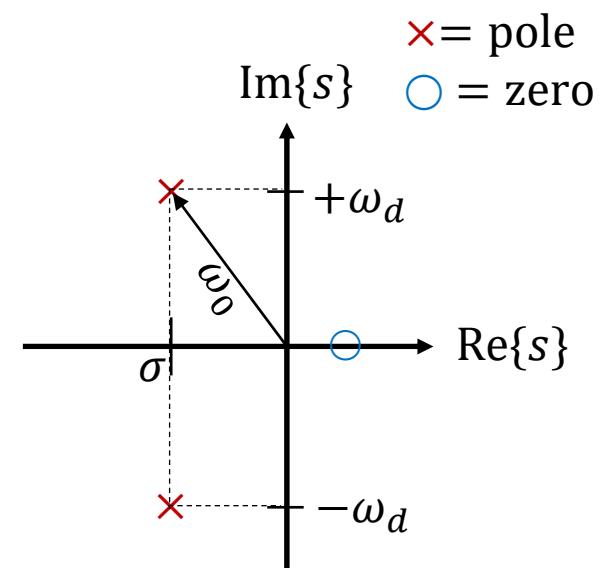
Transfer Functions:

$$H(s) = \frac{V_o(s)}{V_i(s)}$$

Poles of $H(s)$ define “form” of terms in natural response of the circuit

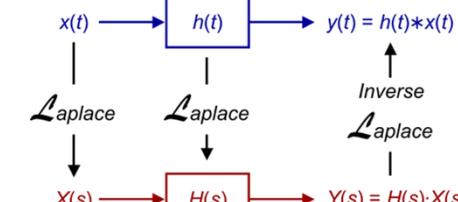
Poles of $V_i(s)$ define “form” of terms in forced response of the circuit

$$V_o(s) = V_I(s)H(s) = \left(\frac{\sum_{i=0}^{M_I} c_i s^i}{\sum_{i=0}^{N_I} d_i s^i} \right) \left(\frac{\sum_{i=0}^{M_H} a_i s^i}{\sum_{i=0}^{N_H} b_i s^i} \right) = \frac{(s - z_1)(s - z_2) \dots (s - z_{M_H+M_I})}{(s - p_1)(s - p_2) \dots (s - p_{N_H+N_I})} = \frac{k_1}{(s - p_1)} + \frac{k_2}{(s - p_2)} + \dots + \frac{k_x}{(s - p_x)}$$

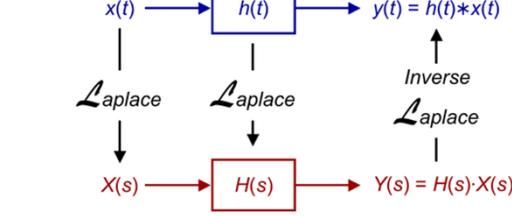


Convolution:

Time domain

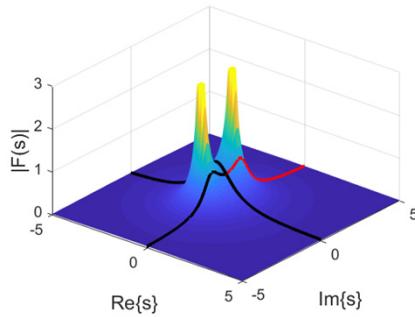


Frequency domain



$$v_o(t) = v_i(t) * h(t) = \int_{-\infty}^{\infty} v_i(t - \tau)h(\tau)d\tau$$

Ch 15 – Frequency Response



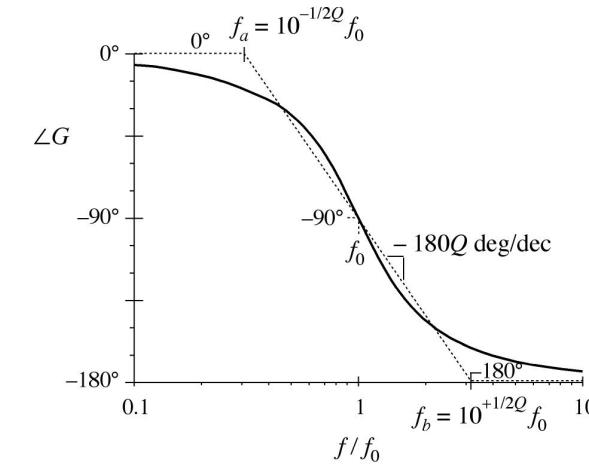
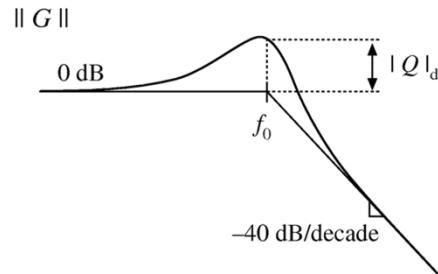
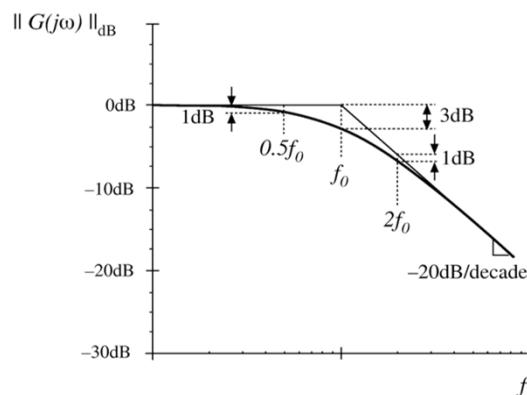
Frequency Response: $H(s \rightarrow j\omega)$

- Circuit response to sinusoidal inputs
- Valid if all poles in LHP

Bode plot: mag-phase plots on log-log axes

- $\|H(j\omega)\|_{dB} = 20 \log(|H(j\omega)|)$
- $\angle H(j\omega)$

Templates and Approximations:



Filter Design

- Graphical analysis, Chebyshev and Butterworth, Sallen-Key Amplifier
- Resonant circuits

Ch 17 – Fourier Series and Transform

Fourier Series:



For periodic $f(t)$ with period $T_0 = \frac{2\pi}{\omega_0}$

$$f(t) = a_0 + \sum_{k=1}^{\infty} a_k \cos(k\omega_0 t) + b_k \sin(k\omega_0 t)$$

$$a_k = \frac{2}{T_0} \int_{t_0}^{t_0+T_0} f(t) \cos(k\omega_0 t) dt$$

$$b_k = \frac{2}{T_0} \int_{t_0}^{t_0+T_0} f(t) \sin(k\omega_0 t) dt$$

https://en.wikipedia.org/wiki/Fourier_transform

Fourier Transform:

For periodic or non-periodic $f(t)$

$$F(\omega) = \mathcal{F}\{f(t)\} = \int_{-\infty}^{\infty} e^{-j\omega t} f(t) dt$$

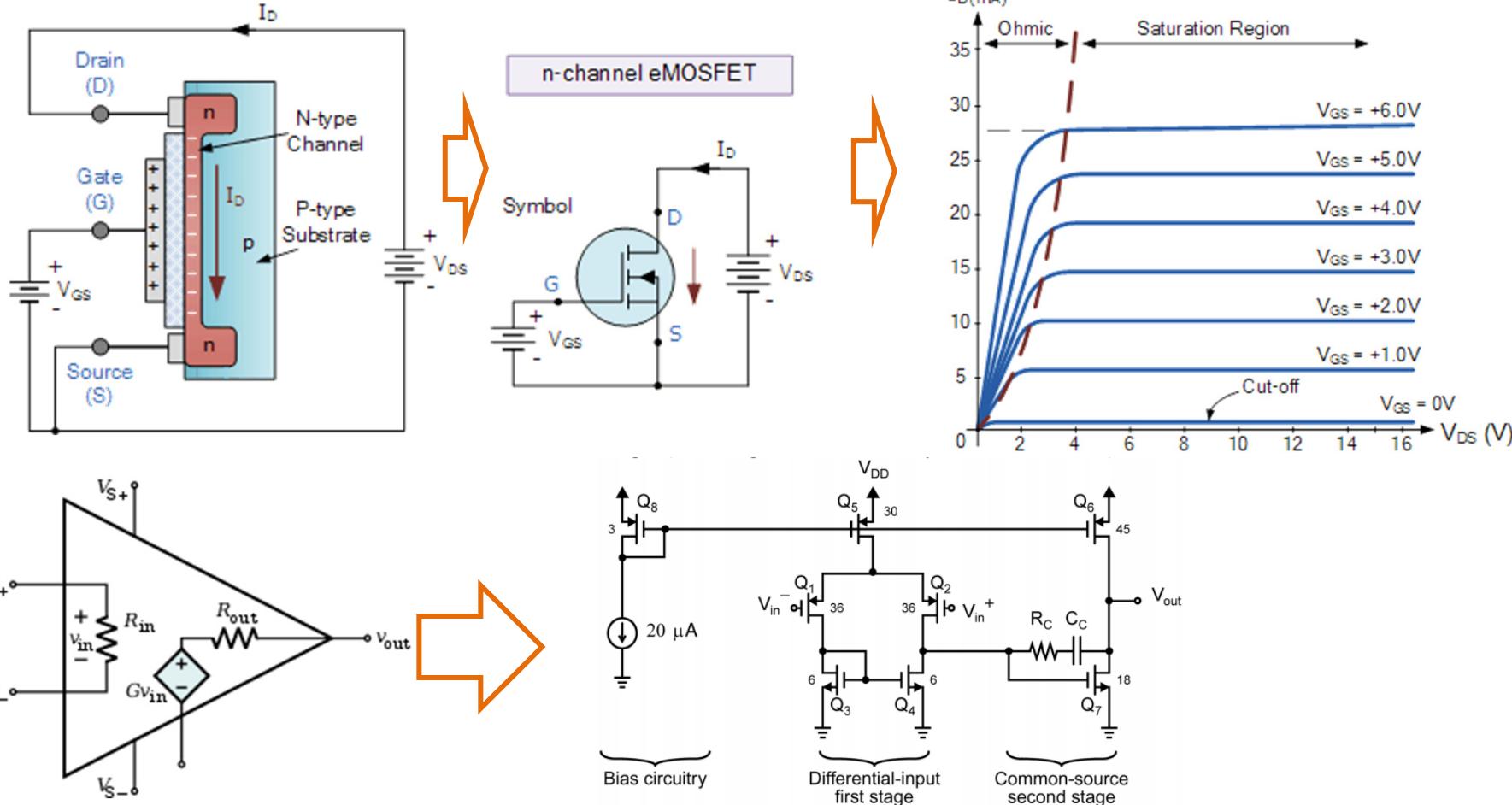
$$f(t) = \mathcal{F}^{-1}\{F(\omega)\} = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{j\omega t} F(\omega) d\omega$$

- Frequency content of a signal
- Gives mag/phase of sinusoids that add up to original signal
- Symmetry can speed up calculations

FUTURE TOPICS

Nonlinear Circuits

- ECE 335 & 336 – Electronic Devices

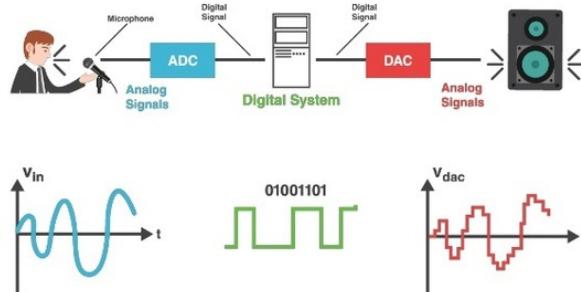


Digital / Discrete Time Signals

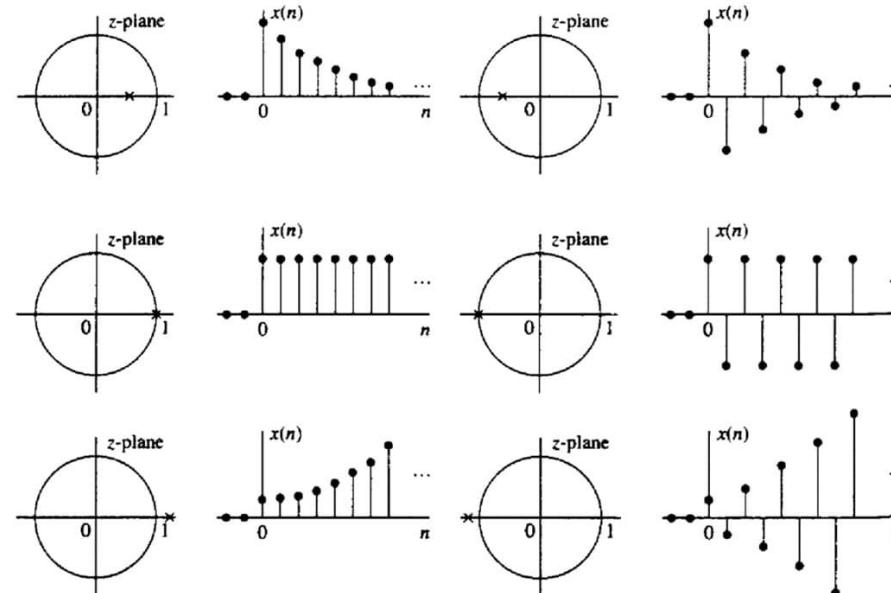
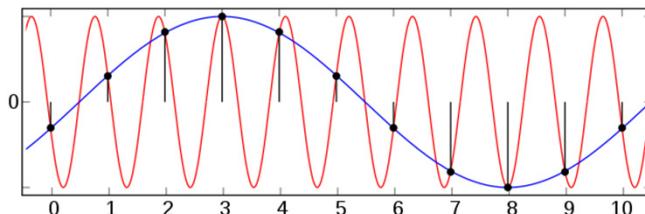
- ECE 315 – Signals and Systems

Cont. time $\sum_n A_n \frac{d^n}{dt^n} v_o(t) = \sum_m B_m \frac{d^m}{dt^m} v_i(t) \xrightarrow{\mathcal{L}} \sum_n A_n s^n V_o(s) = \sum_m B_m s^m V_i(s)$

Discrete time $\sum_n A_n y[k-n] = \sum_m B_m u[k-m] \xrightarrow{z} \sum_n A_n z^{-n} Y(z) = \sum_m B_m z^{-m} U(z)$



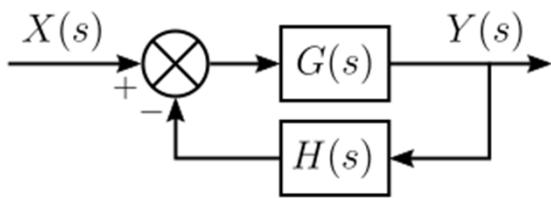
Sampling and aliasing:



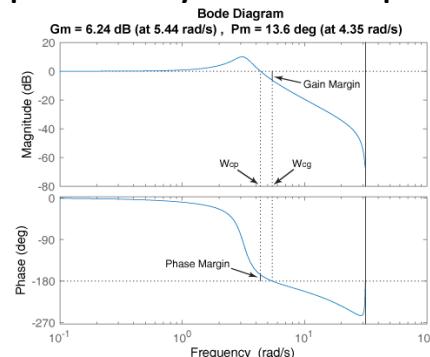
Closed-Loop Control

- ECE 316 – Signals and Systems

Classic Control



Margin Test: Examine closed-loop stability on bode plot

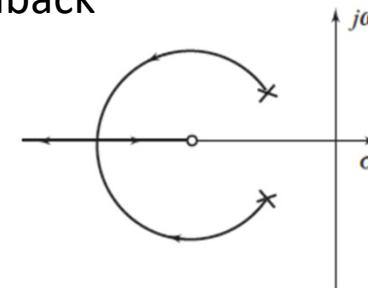


Modern Control

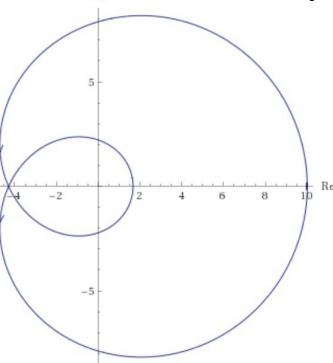
$$\begin{aligned}\dot{\mathbf{x}}(t) &= \mathbf{A}(t)\mathbf{x}(t) + \mathbf{B}(t)\mathbf{u}(t) \\ \mathbf{y}(t) &= \mathbf{C}(t)\mathbf{x}(t) + \mathbf{D}(t)\mathbf{u}(t)\end{aligned}$$

$$H(s) = \mathbf{C}(s\mathbf{I} - \mathbf{A})^{-1}\mathbf{B} + \mathbf{D}$$

Root Locus: How poles and zeros move as you change feedback

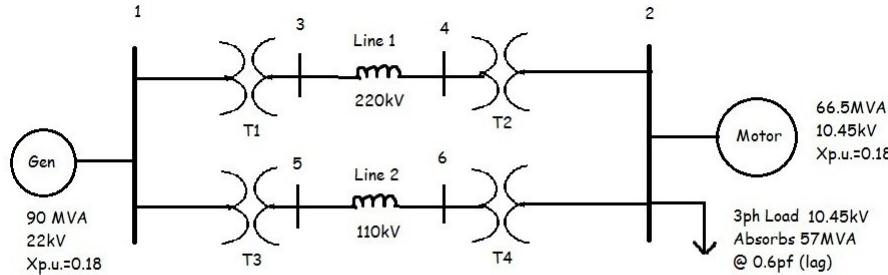


Nyquist Plots: Frequency response in the complex plane



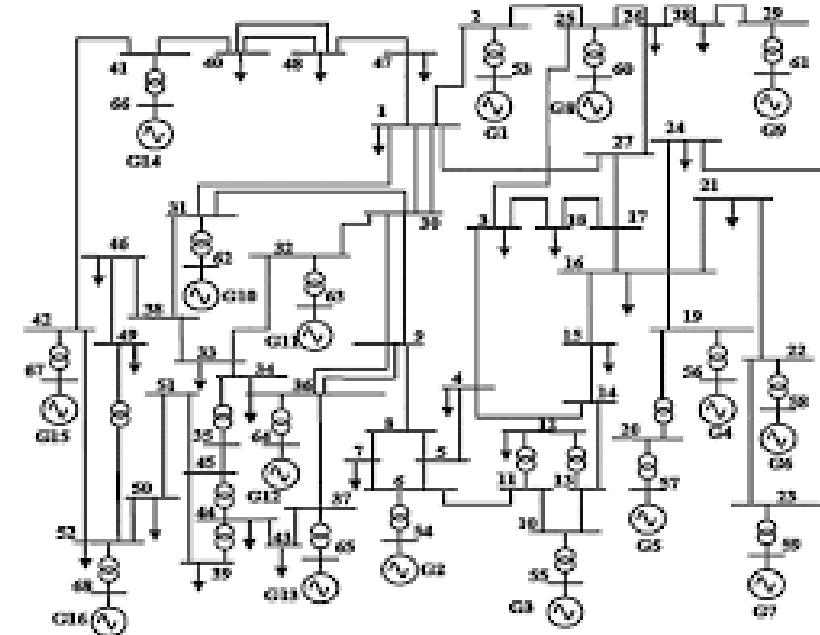
Power Systems

- ECE 325 -- Electric Energy System Components



T1: 50MVA 22/220kV Xp.u. = 0.10
T2: 40MVA 220/11kV Xp.u. = 0.06
T3: 40MVA 22/110kV Xp.u. = 0.064
T4: 40MVA 110/11kV Xp.u.=0.08
Line 1: 48.4Ohms (total)
Line 2: 65.43Ohms (total)

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FINAL REMARKS

Thank you for all your hard work

Good luck with all your finals



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