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# Lecture 17: Converter Bode Plots

ECE 481: Power Electronics  
Prof. Daniel Costinett  
Department of Electrical Engineering and Computer Science  
University of Tennessee Knoxville  
Fall 2013

## Announcements

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- HW #7 due Tuesday, 11/5

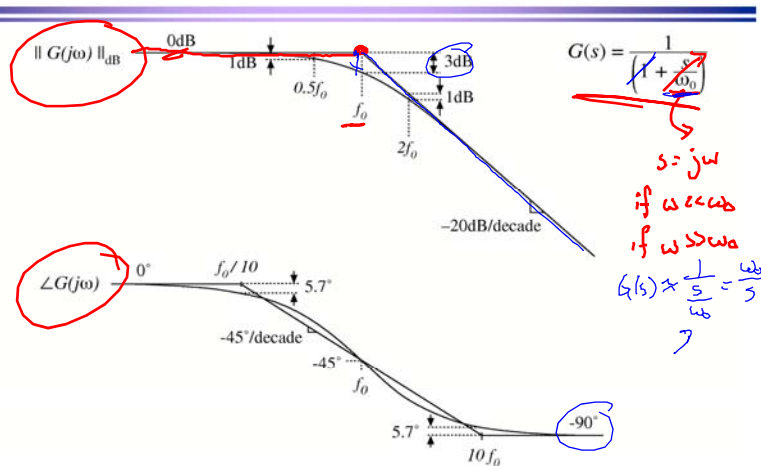
# The 1st IEEE Workshop on Wide Bandgap Power Devices and Applications



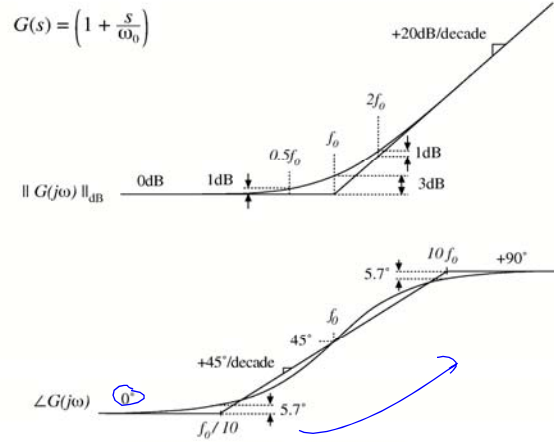
TABLE I  
PHYSICAL PROPERTIES AT 300 K OF Si, 4H-SiC, GAN AND DIAMOND  
AND RELATED FIGURES OF MERIT (JOHNSON, KEYES AND BALIGA)

[unit]	Si	4H-SiC	GaN	Diamond
$E_G$ [eV]	1.12 <i>i</i>	3.23 <i>i</i>	3.39 <i>d</i>	5.47 <i>i</i>
$\epsilon_r$	11.7	9.66	8.9	5.7
$E_B$ [MV/cm]	0.3	3	5	10
$\lambda$ [W/cm.K]	1.3	3.7	1.3	22
$v_s$ [ $10^7$ cm/s]	1.0	2.0	2.2	1
$\mu_e$ [ $\text{cm}^2/\text{V.s}$ ]	1400	900	1000	1000
$\mu_h$ [ $\text{cm}^2/\text{V.s}$ ]	450	100	350	2000
$JFM$ [ $10^{23}$ $\Omega.W/s^2$ ]	2.3	900	490	2530
$KFM$ [ $10^7$ W/K.s]	10	53	17	218
$BFM$ [Si=1]	1	554	188	23068

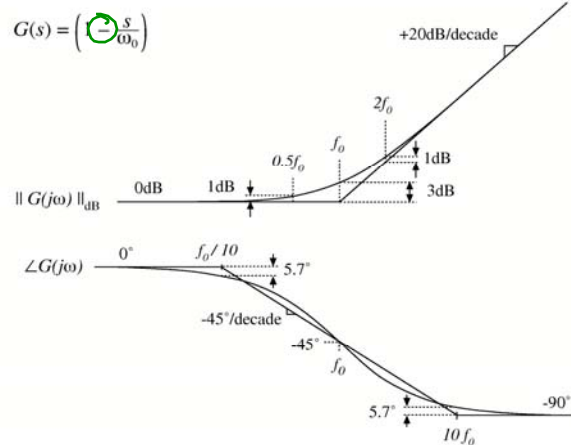
## Summary: Bode plot of real pole



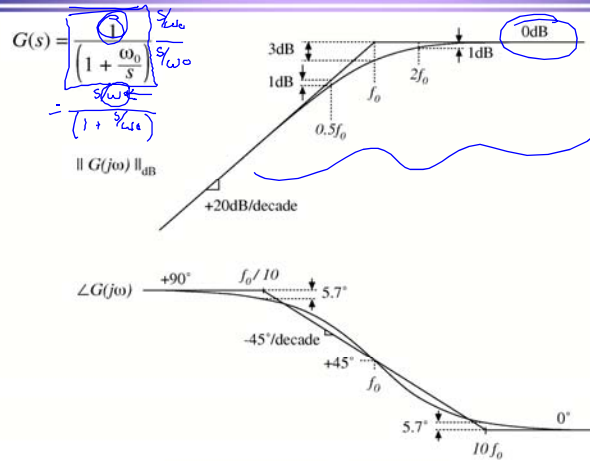
## Summary: Bode plot, real zero



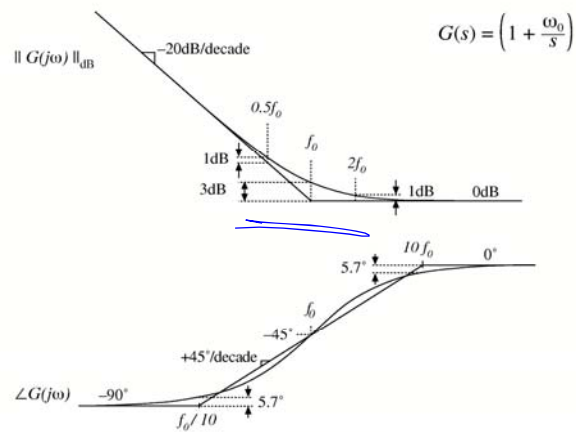
## Summary: Bode plot, RHP zero



## Asymptotes, inverted pole

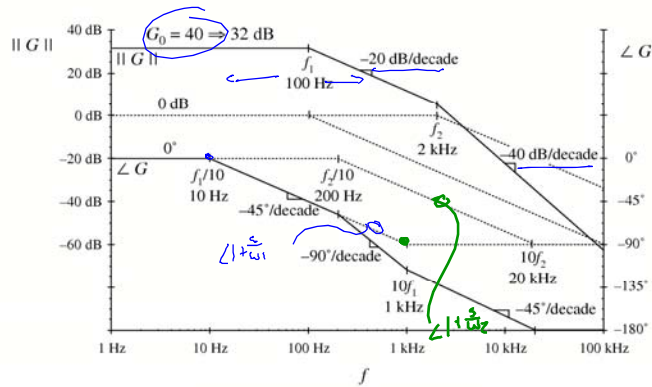


## Asymptotes, inverted zero



Example 1:  $G(s) = \frac{G_0}{\left(1 + \frac{s}{\omega_1}\right)\left(1 + \frac{s}{\omega_2}\right)}$

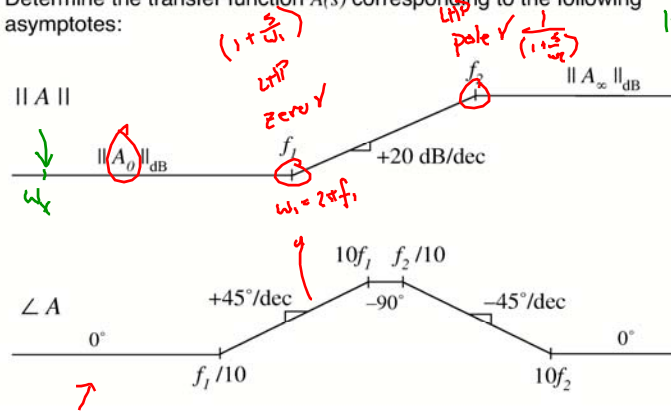
with  $G_0 = 40 \Rightarrow 32 \text{ dB}$ ,  $f_1 = \omega_1/2\pi = 100 \text{ Hz}$ ,  $f_2 = \omega_2/2\pi = 2 \text{ kHz}$



Example 2

$A(s) = A_0 \frac{(1 + \frac{s}{\omega_1})}{(1 + \frac{s}{\omega_2})}$   
 for  $\omega_x \ll \omega_1, \omega_2$   $|A(s)| = A_0 \frac{(1 + \frac{j\omega_x}{\omega_1})}{(1 + \frac{j\omega_x}{\omega_2})} \approx A_0$

Determine the transfer function  $A(s)$  corresponding to the following asymptotes:



## Example 2, continued

One solution:

$$A(s) = A_0 \frac{\left(1 + \frac{s}{\omega_1}\right)}{\left(1 + \frac{s}{\omega_2}\right)}$$

Analytical expressions for asymptotes:

$$\text{For } f < f_1 \quad \left| A_0 \frac{\left(1 + \frac{s}{\omega_1}\right)}{\left(1 + \frac{s}{\omega_2}\right)} \right|_{s=j\omega} = A_0 \frac{1}{1} = A_0$$

$$\text{For } f_1 < f < f_2 \quad \left| A_0 \frac{\left(\frac{s}{\omega_1} + 1\right)}{\left(1 + \frac{s}{\omega_2}\right)} \right|_{s=j\omega} = A_0 \frac{\left|\frac{s}{\omega_1}\right|_{s=j\omega}}{1} = A_0 \frac{\omega}{\omega_1} = A_0 \frac{f}{f_1}$$

## Example 2, continued

For  $f > f_2$

$$\left| A_0 \frac{\left(\frac{s}{\omega_1} + 1\right)}{\left(\frac{s}{\omega_2} + 1\right)} \right|_{s=j\omega} = A_0 \frac{\left|\frac{s}{\omega_1}\right|_{s=j\omega}}{\left|\frac{s}{\omega_2}\right|_{s=j\omega}} = A_0 \frac{\omega_2}{\omega_1} = A_0 \frac{f_2}{f_1}$$

So the high-frequency asymptote is

$$A_\infty = A_0 \frac{f_2}{f_1}$$

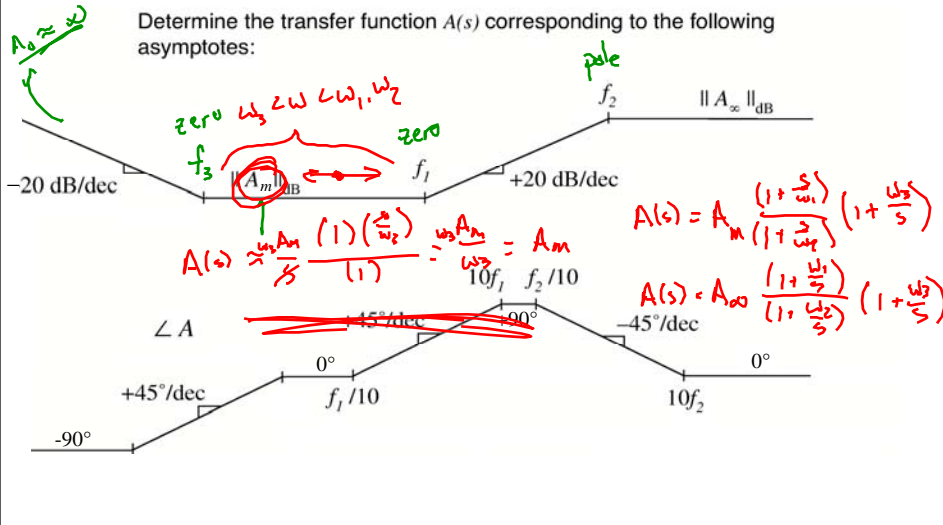
Another way to express  $A(s)$ : use inverted poles and zeroes, and express  $A(s)$  directly in terms of  $A_\infty$

$$\rightarrow A(s) = A_\infty \frac{\left(1 + \frac{\omega_1}{s}\right)}{\left(1 + \frac{\omega_2}{s}\right)}$$

pole:  $\frac{1}{1 + \frac{s}{\omega}}$  for  $\omega \rightarrow \infty$

$A(s) = \frac{A_m}{s} \frac{(1 + \frac{s^2}{\omega_1^2})(1 + \frac{s^2}{\omega_2^2})}{(1 + \frac{s}{\omega_3})}$

### Example 2b



### 8.1.6 Quadratic pole response: resonance

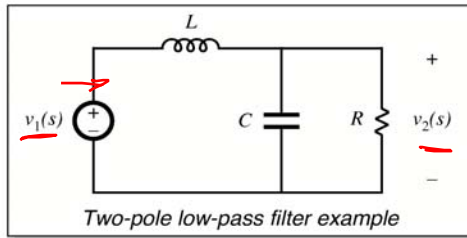
Example

$G(s) = \frac{v_2(s)}{v_1(s)} = \frac{1}{1 + \frac{L}{R}s + s^2 LC}$

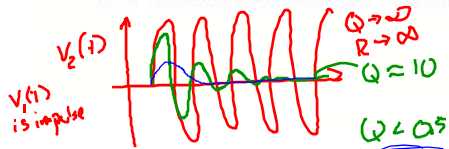
Second-order denominator, of the form

$G(s) = \frac{1}{1 + a_1 s + a_2 s^2}$

with  $a_1 = L/R$  and  $a_2 = LC$



How should we construct the Bode diagram?



$V_2(s) < V_1(s)$   $R \parallel \frac{1}{sL}$   $R \parallel \frac{1}{sC} + sL$

## Approach 1: factor denominator

$$G(s) = \frac{1}{1 + a_1 s + a_2 s^2} = \frac{1}{1 + \frac{\zeta}{\omega_0} s + \left(\frac{s}{\omega_0}\right)^2}$$

We might factor the denominator using the quadratic formula, then construct Bode diagram as the combination of two real poles:

$$G(s) = \frac{1}{\left(1 - \frac{s}{s_1}\right)\left(1 - \frac{s}{s_2}\right)} \quad \text{with} \quad s_1 = -\frac{a_1}{2a_2} \left[1 - \sqrt{1 - \frac{4a_2}{a_1^2}}\right]$$

$$s_2 = -\frac{a_1}{2a_2} \left[1 + \sqrt{1 - \frac{4a_2}{a_1^2}}\right]$$

for real poles

$$4a_2 \leq a_1^2$$

$$4 \frac{1}{\omega_0^2} \leq \left(\frac{1}{\omega_0}\right)^2$$

$Q \leq 0.5$

- If  $4a_2 \leq a_1^2$ , then the roots  $s_1$  and  $s_2$  are real. We can construct Bode diagram as the combination of two real poles.
- If  $4a_2 > a_1^2$ , then the roots are complex. In Section 8.1.1, the assumption was made that  $\omega_0$  is real; hence, the results of that section cannot be applied and we need to do some additional work.

## Approach 2: Define a standard normalized form for the quadratic case

$$G(s) = \frac{1}{1 + 2\zeta \frac{s}{\omega_0} + \left(\frac{s}{\omega_0}\right)^2}$$

or

$$G(s) = \frac{1}{1 + \frac{s}{Q\omega_0} + \left(\frac{s}{\omega_0}\right)^2}$$

- When the coefficients of  $s$  are real and positive, then the parameters  $\zeta$ ,  $\omega_0$ , and  $Q$  are also real and positive
- The parameters  $\zeta$ ,  $\omega_0$ , and  $Q$  are found by equating the coefficients of  $s$
- The parameter  $\omega_0$  is the angular corner frequency, and we can define  $f_0 = \omega_0/2\pi$
- The parameter  $\zeta$  is called the damping factor.  $\zeta$  controls the shape of the exact curve in the vicinity of  $f = f_0$ . The roots are complex when  $\zeta < 1$ .
- In the alternative form, the parameter  $Q$  is called the quality factor.  $Q$  also controls the shape of the exact curve in the vicinity of  $f = f_0$ . The roots are complex when  $Q > 0.5$ .



## The Q-factor

In a second-order system,  $\zeta$  and  $Q$  are related according to

$$Q = \frac{1}{2\zeta}$$

$Q$  is a measure of the dissipation in the system. A more general definition of  $Q$ , for sinusoidal excitation of a passive element or system is

$$Q = 2\pi \frac{\text{(peak stored energy)}}{\text{(energy dissipated per cycle)}}$$

For a second-order passive system, the two equations above are equivalent. We will see that  $Q$  has a simple interpretation in the Bode diagrams of second-order transfer functions.

## Analytical expressions for $f_0$ and $Q$

Two-pole low-pass filter  
example: we found that

$$G(s) = \frac{v_2(s)}{v_1(s)} = \frac{1}{1 + s\frac{L}{R} + s^2 LC}$$

Equate coefficients of like  
powers of  $s$  with the  
standard form

$$G(s) = \frac{1}{1 + \frac{s}{Q\omega_0} + \left(\frac{s}{\omega_0}\right)^2}$$

Result:

$$f_0 = \frac{\omega_0}{2\pi} = \frac{1}{2\pi\sqrt{LC}}$$
$$Q = R\sqrt{\frac{C}{L}}$$

## Magnitude asymptotes, quadratic form

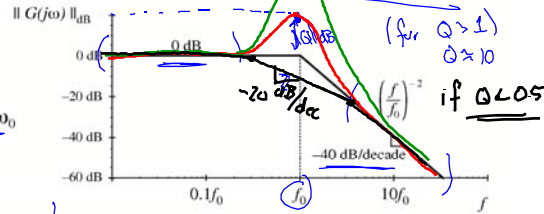
In the form  $G(s) = \frac{1}{1 + \frac{s}{Q\omega_0} + \left(\frac{s}{\omega_0}\right)^2}$

let  $s = j\omega$  and find magnitude:  $|G(j\omega)| = \frac{1}{\sqrt{\left(1 - \left(\frac{\omega}{\omega_0}\right)^2\right)^2 + \frac{1}{Q^2} \left(\frac{\omega}{\omega_0}\right)^2}}$

Asymptotes are

$|G| \rightarrow 1$  for  $\omega \ll \omega_0$

$|G| \rightarrow \left(\frac{f}{f_0}\right)^{-2}$  for  $\omega \gg \omega_0$



$\omega = \omega_0 \quad |G(j\omega_0)| = \frac{1}{\sqrt{(1-1)^2 + \frac{1}{Q^2}(1)^2}} = \frac{1}{1/Q} = Q$

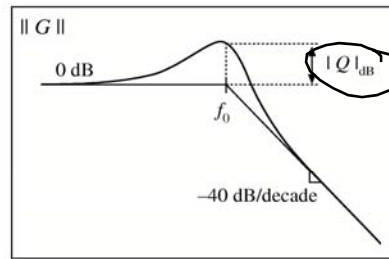
## Deviation of exact curve from magnitude asymptotes

$$|G(j\omega)| = \frac{1}{\sqrt{\left(1 - \left(\frac{\omega}{\omega_0}\right)^2\right)^2 + \frac{1}{Q^2} \left(\frac{\omega}{\omega_0}\right)^2}}$$

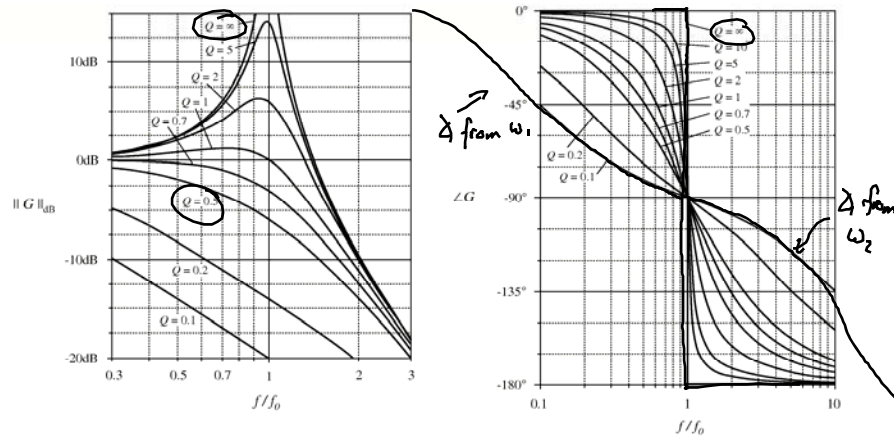
At  $\omega = \omega_0$ , the exact magnitude is

$|G(j\omega_0)| = Q$  or, in dB:  $|G(j\omega_0)|_{dB} = |Q|_{dB}$

The exact curve has magnitude  $Q$  at  $f = f_0$ . The deviation of the exact curve from the asymptotes is  $|Q|_{dB}$



## Two-pole response: exact curves



## 8.1.7. The low- $Q$ approximation

Given a second-order denominator polynomial, of the form

$$G(s) = \frac{1}{1 + a_1 s + a_2 s^2} \quad \text{or} \quad G(s) = \frac{1}{1 + \frac{s}{Q\omega_0} + \left(\frac{s}{\omega_0}\right)^2}$$

When the roots are real, i.e., when  $Q < 0.5$ , then we can factor the denominator, and construct the Bode diagram using the asymptotes for real poles. We would then use the following normalized form:

$$G(s) = \frac{1}{\left(1 + \frac{s}{\omega_1}\right)\left(1 + \frac{s}{\omega_2}\right)}$$

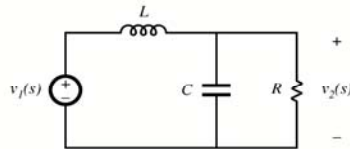
This is a particularly desirable approach when  $Q \ll 0.5$ , i.e., when the corner frequencies  $\omega_1$  and  $\omega_2$  are well separated.

## An example

A problem with this procedure is the complexity of the quadratic formula used to find the corner frequencies.

R-L-C network example:

$$G(s) = \frac{v_2(s)}{v_1(s)} = \frac{1}{1 + s\frac{L}{R} + s^2 LC}$$



Use quadratic formula to factor denominator. Corner frequencies are:

$$\omega_1, \omega_2 = \frac{L/R \pm \sqrt{(L/R)^2 - 4LC}}{2LC}$$

## Factoring the denominator

$$\omega_1, \omega_2 = \frac{L/R \pm \sqrt{(L/R)^2 - 4LC}}{2LC}$$

This complicated expression yields little insight into how the corner frequencies  $\omega_1$  and  $\omega_2$  depend on  $R$ ,  $L$ , and  $C$ .

When the corner frequencies are well separated in value, it can be shown that they are given by the much simpler (approximate) expressions

$$\omega_1 = \frac{R}{L}, \quad \omega_2 = \frac{1}{RC}$$

$\omega_1$  is then independent of  $C$ , and  $\omega_2$  is independent of  $L$ .

These simpler expressions can be derived via the Low- $Q$  Approximation.

## Derivation of the Low-Q Approximation

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Given

$$G(s) = \frac{1}{1 + \frac{s}{Q\omega_0} + \left(\frac{s}{\omega_0}\right)^2}$$

Use quadratic formula to express corner frequencies  $\omega_1$  and  $\omega_2$  in terms of  $Q$  and  $\omega_0$  as:

$$\omega_1 = \frac{\omega_0}{Q} \frac{1 - \sqrt{1 - 4Q^2}}{2} \qquad \omega_2 = \frac{\omega_0}{Q} \frac{1 + \sqrt{1 - 4Q^2}}{2}$$

## Corner frequency $\omega_2$

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$$\omega_2 = \frac{\omega_0}{Q} \frac{1 + \sqrt{1 - 4Q^2}}{2}$$

can be written in the form

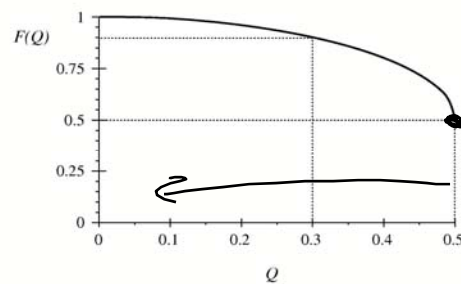
$$\omega_2 = \frac{\omega_0}{Q} F(Q)$$

where

$$F(Q) = \frac{1}{2} \left( 1 + \sqrt{1 - 4Q^2} \right)$$

For small  $Q$ ,  $F(Q)$  tends to 1.  
We then obtain

$$\omega_2 \approx \frac{\omega_0}{Q} \text{ for } Q \ll \frac{1}{2}$$



For  $Q < 0.3$ , the approximation  $F(Q) = 1$  is within 10% of the exact value.

## Corner frequency $\omega_1$

$$\omega_1 = \frac{\omega_0}{Q} \frac{1 - \sqrt{1 - 4Q^2}}{2}$$

can be written in the form

$$\omega_1 = \frac{Q \omega_0}{F(Q)}$$

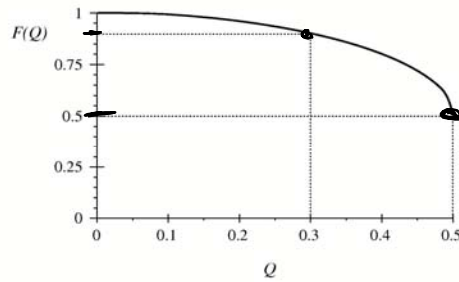
where

$$F(Q) = \frac{1}{2} (1 + \sqrt{1 - 4Q^2})$$

For small  $Q$ ,  $F(Q)$  tends to 1.

We then obtain

$$\omega_1 \approx Q \omega_0 \quad \text{for } Q \ll \frac{1}{2}$$



For  $Q < 0.3$ , the approximation  $F(Q) = 1$  is within 10% of the exact value.

## The Low-Q Approximation

$\|G\|_{dB}$

0dB

$$f_1 = \frac{Q f_0}{F(Q)}$$

$$\approx Q f_0$$

$f_1$

$f_0$

$$f_2 = \frac{f_0 F(Q)}{Q}$$

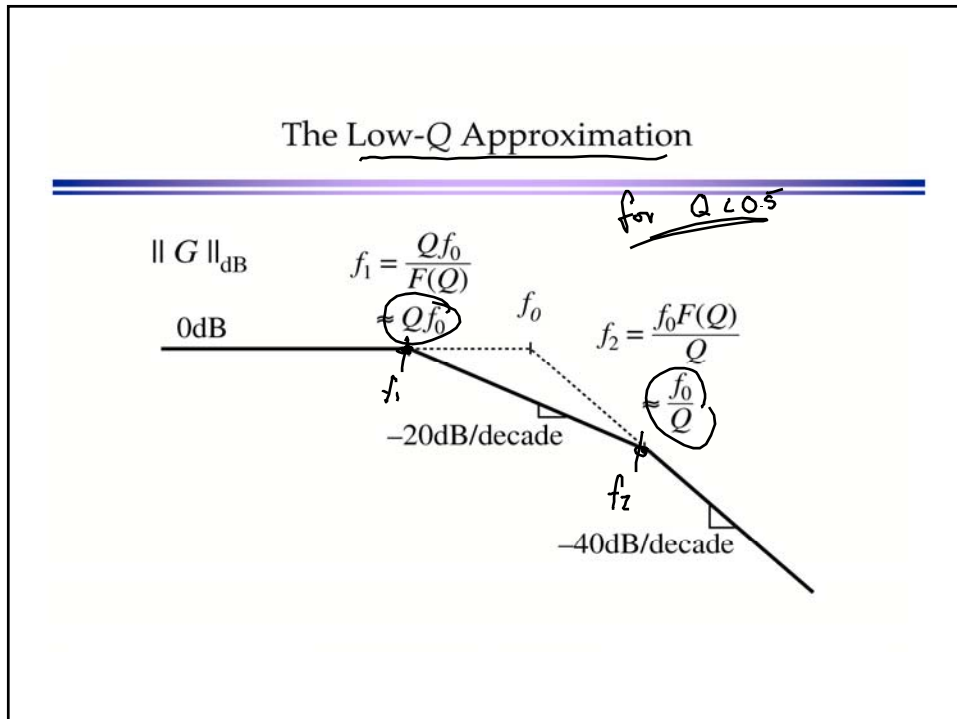
$$\approx \frac{f_0}{Q}$$

$f_2$

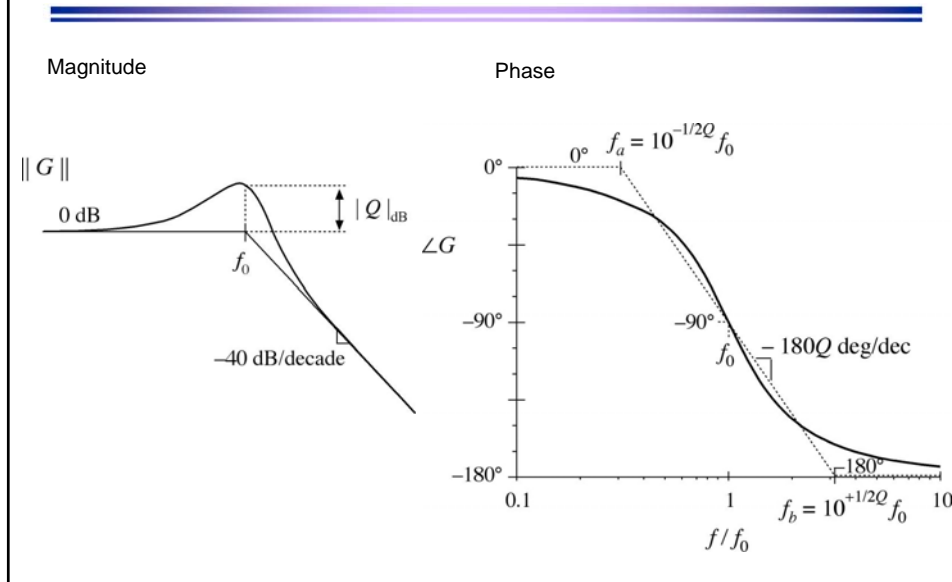
-20dB/decade

-40dB/decade

*for  $Q < 0.5$*



## Summary: Asymptotes for Complex Poles



## R-L-C Example

For the previous example:

$$G(s) = \frac{v_2(s)}{v_1(s)} = \frac{1}{1 + s\frac{L}{R} + s^2LC}$$

$$f_0 = \frac{\omega_0}{2\pi} = \frac{1}{2\pi\sqrt{LC}}$$

$$Q = R\sqrt{\frac{C}{L}}$$

Use of the Low- $Q$  Approximation leads to

$$\omega_1 \approx Q \omega_0 = R\sqrt{\frac{C}{L}} \frac{1}{\sqrt{LC}} = \frac{R}{L}$$

$$\omega_2 \approx \frac{\omega_0}{Q} = \frac{1}{\sqrt{LC}} \frac{1}{R\sqrt{C/L}} = \frac{1}{RC}$$

## 8.1.8. Approximate Roots of an Arbitrary-Degree Polynomial

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Generalize the low- $Q$  approximation to obtain approximate factorization of the  $n^{\text{th}}$ -order polynomial

$$P(s) = 1 + a_1 s + a_2 s^2 + \dots + a_n s^n$$

It is desired to factor this polynomial in the form

$$P(s) = (1 + \tau_1 s)(1 + \tau_2 s) \dots (1 + \tau_n s)$$

When the roots are real and well separated in value, then approximate analytical expressions for the time constants  $\tau_1, \tau_2, \dots, \tau_n$  can be found, that typically are simple functions of the circuit element values.

**Objective:** find a general method for deriving such expressions. Include the case of complex root pairs.

## Result

when roots are real and well separated

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If the following inequalities are satisfied

$$\left| a_1 \right| \gg \left| \frac{a_2}{a_1} \right| \gg \left| \frac{a_3}{a_2} \right| \gg \dots \gg \left| \frac{a_n}{a_{n-1}} \right|$$

Then the polynomial  $P(s)$  has the following approximate factorization

$$P(s) \approx (1 + a_1 s) \left( 1 + \frac{a_2}{a_1} s \right) \left( 1 + \frac{a_3}{a_2} s \right) \dots \left( 1 + \frac{a_n}{a_{n-1}} s \right)$$

- If the  $a_n$  coefficients are simple analytical functions of the element values  $L, C$ , etc., then the roots are similar simple analytical functions of  $L, C$ , etc.
- Numerical values are used to justify the approximation, but analytical expressions for the roots are obtained



## When two roots are not well separated then leave their terms in quadratic form

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Suppose inequality  $k$  is not satisfied:

$$|a_1| \gg \left| \frac{a_2}{a_1} \right| \gg \dots \gg \left| \frac{a_k}{a_{k-1}} \right| \not\gg \left| \frac{a_{k+1}}{a_k} \right| \gg \dots \gg \left| \frac{a_n}{a_{n-1}} \right|$$

↑  
not satisfied

Then leave the terms corresponding to roots  $k$  and  $(k+1)$  in quadratic form, as follows:

$$P(s) \approx \left(1 + a_1 s\right) \left(1 + \frac{a_2}{a_1} s\right) \dots \left(1 + \frac{a_k}{a_{k-1}} s + \frac{a_{k+1}}{a_{k-1}} s^2\right) \dots \left(1 + \frac{a_n}{a_{n-1}} s\right)$$

This approximation is accurate provided

$$|a_1| \gg \left| \frac{a_2}{a_1} \right| \gg \dots \gg \left| \frac{a_k}{a_{k-1}} \right| \gg \left| \frac{a_{k-2} a_{k+1}}{a_{k-1}^2} \right| \gg \left| \frac{a_{k+2}}{a_{k+1}} \right| \gg \dots \gg \left| \frac{a_n}{a_{n-1}} \right|$$

## When the first inequality is violated A special case for quadratic roots

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When inequality 1 is not satisfied:

$$|a_1| \not\gg \left| \frac{a_2}{a_1} \right| \gg \left| \frac{a_3}{a_2} \right| \gg \dots \gg \left| \frac{a_n}{a_{n-1}} \right|$$

↑  
not satisfied

Then leave the first two roots in quadratic form, as follows:

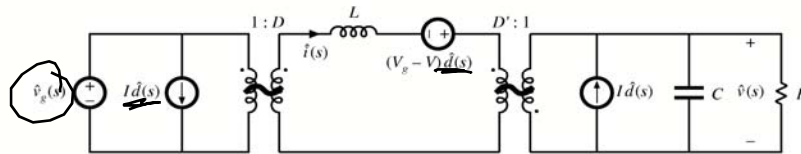
$$P(s) \approx \left(1 + a_1 s + a_2 s^2\right) \left(1 + \frac{a_3}{a_2} s\right) \dots \left(1 + \frac{a_n}{a_{n-1}} s\right)$$

This approximation is justified provided

$$\left| \frac{a_2^2}{a_3} \right| \gg |a_1| \gg \left| \frac{a_3}{a_2} \right| \gg \left| \frac{a_4}{a_3} \right| \gg \dots \gg \left| \frac{a_n}{a_{n-1}} \right|$$

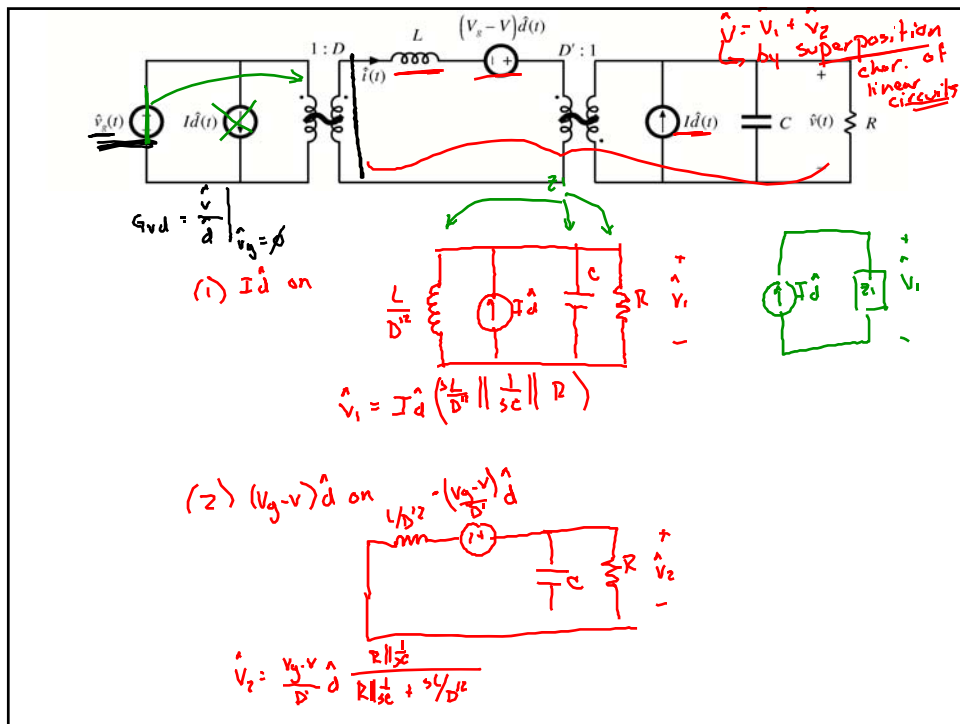
## 8.2.1. Example: transfer functions of the buck-boost converter

Small-signal ac model of the buck-boost converter, derived in Chapter 7:



## From Lecture 15

$$\begin{aligned}
 \hat{V} &= \frac{1}{sC \parallel R} \cdot \frac{-D}{D'} \hat{V}_g \\
 G_{Vg} = \frac{\hat{V}}{\hat{V}_g} \Big|_{d=0} &= \frac{D}{D'} \left( \frac{\frac{1}{sC + \frac{1}{R}}}{\frac{1}{sC + \frac{1}{R}} + s\frac{L}{D'}} \right) = \frac{-D}{D'} \left( \frac{1}{1 + s\frac{LC}{D'} + s\frac{L}{D'R}} \right) \\
 &\downarrow \\
 &= \frac{G_{Vg0}}{\left(\frac{s}{\omega_0}\right)^2 + \frac{s}{Q\omega_0} + 1}
 \end{aligned}$$



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$$\hat{v} = \hat{v}_1 + \hat{v}_2 = I_d \left( \frac{1}{sC} \parallel \frac{sL}{D^2} \parallel R \right) + \frac{(v_g - v)}{D} \hat{d} \frac{R \parallel \frac{1}{sC}}{R \parallel \frac{1}{sC} + sL/D^2}$$

$$\left( \frac{sL}{D^2} \right) \frac{1}{s \frac{LC}{D^2} + 1 + \frac{sL}{RD^2}}$$

$$\frac{\hat{v}}{\hat{d}} = \frac{I_d \frac{sL}{D^2} - \frac{v_g - v}{D}}{s \frac{LC}{D^2} + \frac{sL}{RD^2} + 1} = G_{vd}$$

## Derivation of transfer functions

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Divide numerator and denominator by  $R$ . Result: the line-to-output transfer function is

$$G_{vg}(s) = \frac{\hat{v}(s)}{\hat{v}_g(s)} \Big|_{\hat{d}(s)=0} = \left(-\frac{D}{D'}\right) \frac{1}{1 + s \frac{L}{D'^2 R} + s^2 \frac{LC}{D'^2}}$$

which is of the following standard form:

$$G_{vg}(s) = G_{s0} \frac{1}{1 + \frac{s}{Q\omega_0} + \left(\frac{s}{\omega_0}\right)^2}$$

## Salient features of the line-to-output transfer function

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Equate standard form to derived transfer function, to determine expressions for the salient features:

$$\left. \begin{aligned} G_{s0} &= -\frac{D}{D'} \\ \frac{1}{\omega_0^2} &= \frac{LC}{D'^2} \\ \frac{1}{Q\omega_0} &= \frac{L}{D'^2 R} \end{aligned} \right\} \begin{aligned} \omega_0 &= \frac{D'}{\sqrt{LC}} \\ Q &= D'R \sqrt{\frac{C}{L}} \end{aligned}$$

## Control-to-output transfer function

Express in normalized form:

$$G_{vd}(s) = \frac{\hat{v}(s)}{\hat{d}(s)} \Big|_{v_g(s)=0} = \left( -\frac{V_g - V}{D'^2} \right) \frac{\left( 1 - s \frac{LI}{V_g - V} \right)}{\left( 1 + s \frac{L}{D'^2 R} + s^2 \frac{LC}{D'^2} \right)}$$

This is of the following standard form:

$$G_{vd}(s) = G_{d0} \frac{\left( 1 - \frac{s}{\omega_z} \right)}{\left( 1 + \frac{s}{Q\omega_0} + \left( \frac{s}{\omega_0} \right)^2 \right)}$$

## Salient features of control-to-output transfer function

$$G_{d0} = -\frac{V_g - V}{D'} = -\frac{V_g}{D'^2} = \frac{V}{DD'}$$

$$\omega_z = \frac{V_g - V}{LI} = \frac{D'R}{DL} \quad (\text{RHP})$$

$$\omega_0 = \frac{D'}{\sqrt{LC}}$$

$$Q = D'R \sqrt{\frac{C}{L}}$$

— Simplified using the dc relations:  $\begin{cases} V = -\frac{D}{D'} V_g \\ I = -\frac{V}{D'R} \end{cases}$

## Plug in numerical values

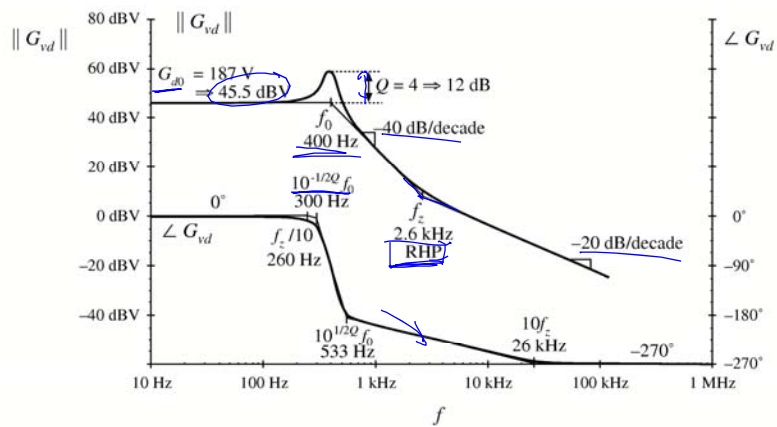
Suppose we are given the following numerical values:

$$\begin{cases} D = 0.6 \\ R = 10\Omega \\ V_g = 30V \\ L = 160\mu\text{H} \\ C = 160\mu\text{F} \end{cases}$$

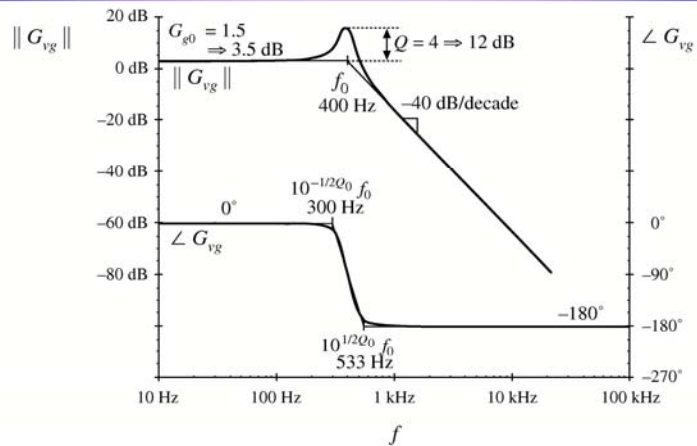
Then the salient features have the following numerical values:

$$\begin{cases} |G_{s0}| = \frac{D}{D'} = 1.5 \Rightarrow 3.5 \text{ dB} \\ |G_{d0}| = \frac{|V|}{DD'} = 187.5 \text{ V} \Rightarrow 45.5 \text{ dBV} \\ f_0 = \frac{\omega_0}{2\pi} = \frac{D'}{2\pi\sqrt{LC}} = 400 \text{ Hz} \\ Q = DR\sqrt{\frac{C}{L}} = 4 \Rightarrow 12 \text{ dB} \\ f_z = \frac{\omega_z}{2\pi} = \frac{D'^2 R}{2\pi DL} = 2.65 \text{ kHz} \end{cases}$$

## Bode plot: control-to-output transfer function

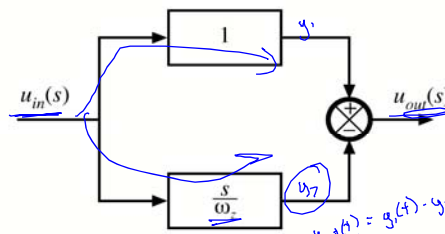


## Bode plot: line-to-output transfer function



### 8.2.3. Physical origins of the right half-plane zero

$$G(s) = 1 - \frac{s}{\omega_z}$$



- phase reversal at high frequency
- transient response: output initially tends in wrong direction

