

Chapter 6: Converter Circuits

6.1. Circuit manipulations

6.2. A short list of
converters

6.3. Transformer isolation

6.4. Converter evaluation
and design

6.5. Summary of key
points

- Where do the boost, buck-boost, and other converters originate?
- How can we obtain a converter having given desired properties?
- What converters are possible?
- How can we obtain transformer isolation in a converter?
- For a given application, which converter is best?

6.2 - A Short List of Converters

An infinite number of converters are possible, which contain switches embedded in a network of inductors and capacitors

Two simple classes of converters are listed here:

- Single-input single-output converters containing a single inductor. The switching period is divided into two subintervals. This class contains eight converters.
- Single-input single-output converters containing two inductors. The switching period is divided into two subintervals. Several of the more interesting members of this class are listed.

Single Input/Output/Inductor Converters

- Use switches to connect inductor between source and load, in one manner during first subinterval and in another during second subinterval
- There are a limited number of ways to do this, so all possible combinations can be found
- After elimination of degenerate and redundant cases, eight converters are found:

dc-dc converters

buck boost buck-boost noninverting buck-boost

dc-ac converters

bridge Watkins-Johnson

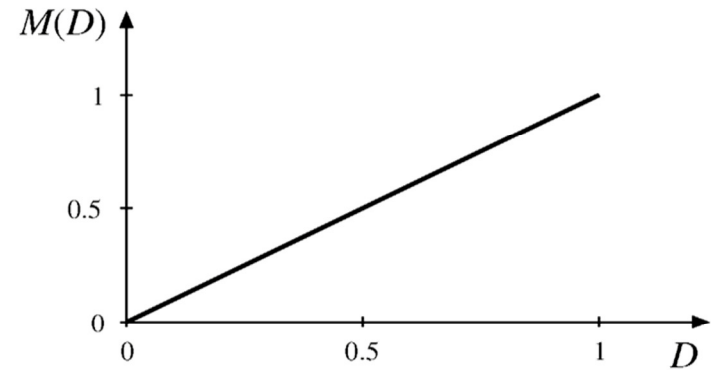
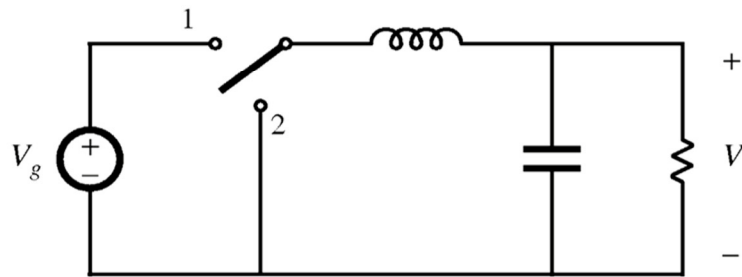
ac-dc converters

current-fed bridge inverse of Watkins-Johnson

Unipolar Output Converters

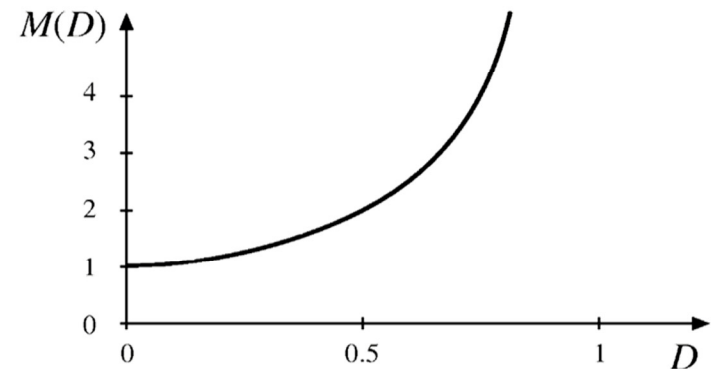
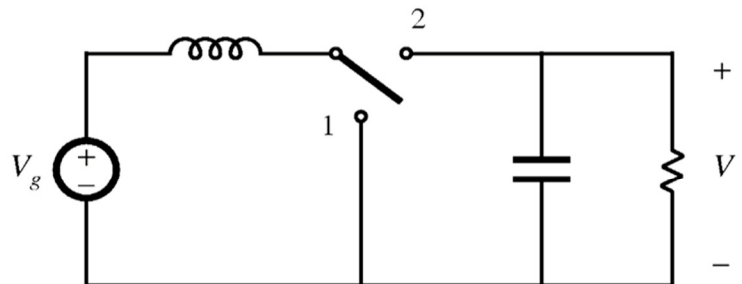
1. Buck

$$M(D) = D$$



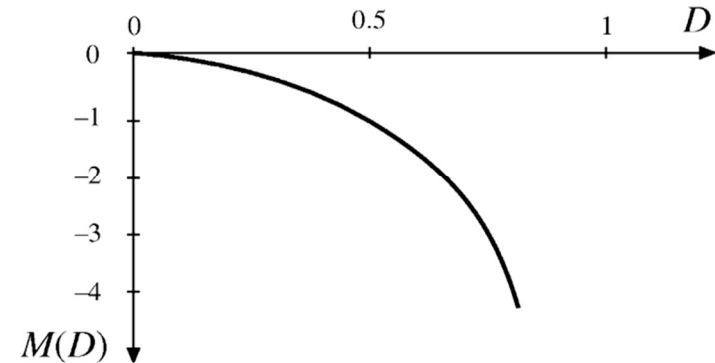
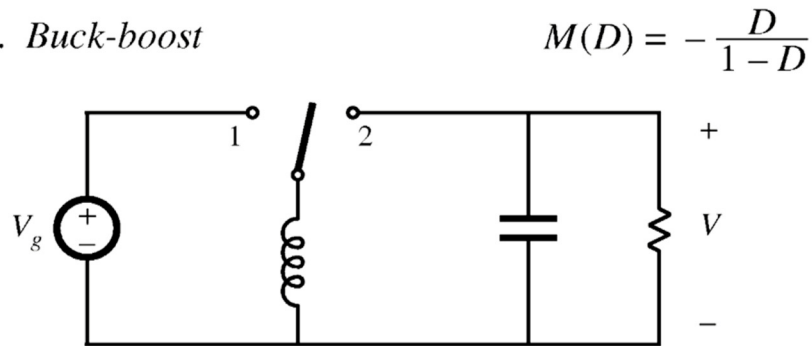
2. Boost

$$M(D) = \frac{1}{1-D}$$

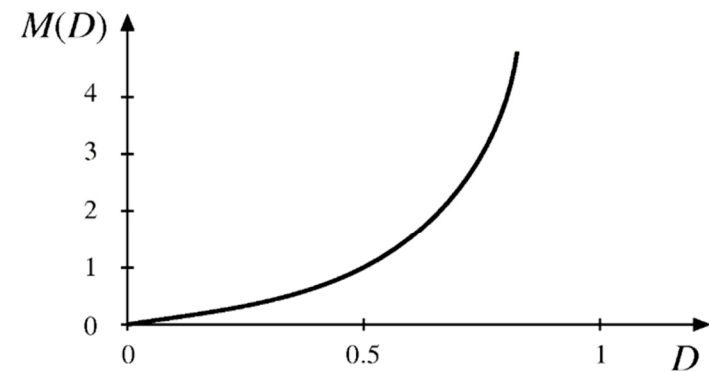
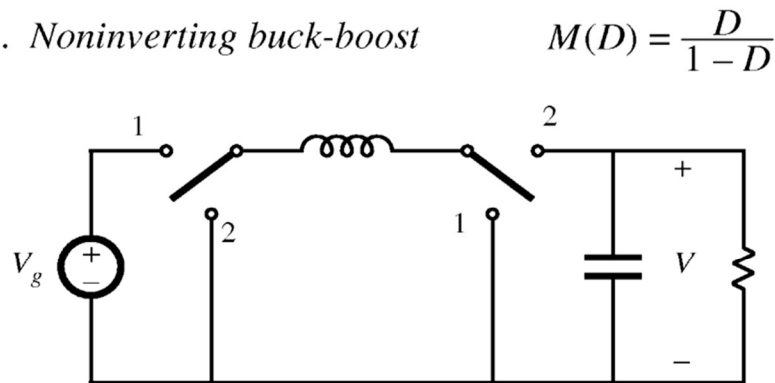


Unipolar Output Converters (cont.)

3. Buck-boost



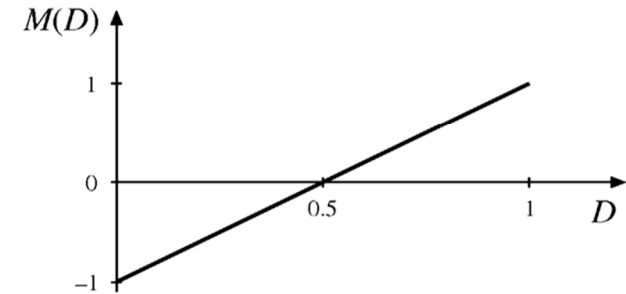
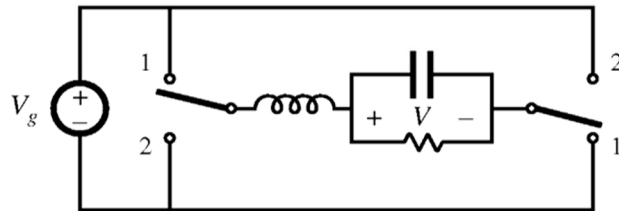
4. Noninverting buck-boost



Bipolar Output Converters

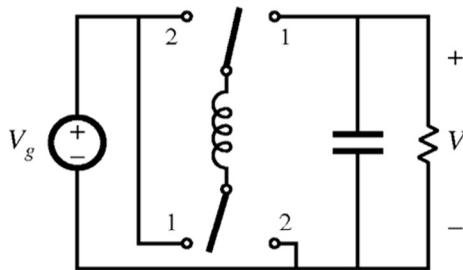
5. Bridge

$$M(D) = 2D - 1$$

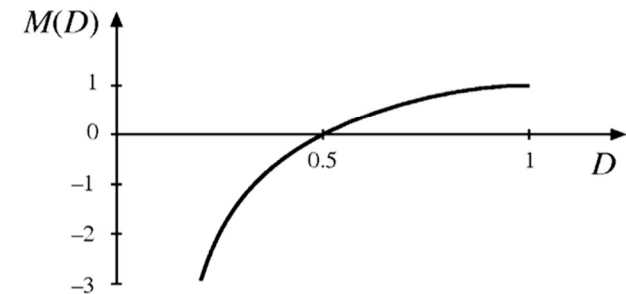
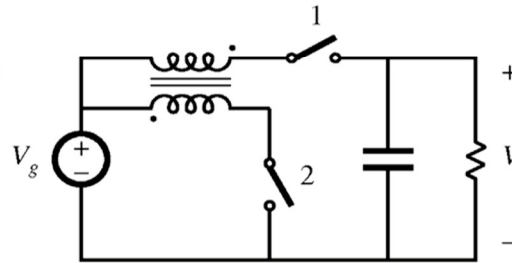


6. Watkins-Johnson

$$M(D) = \frac{2D - 1}{D}$$



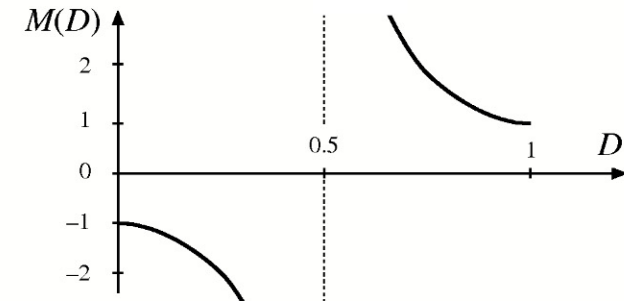
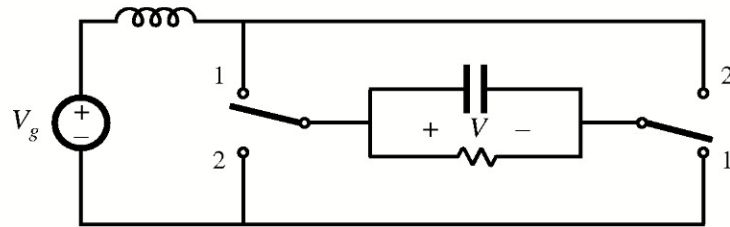
or



Bipolar Output Converters (cont.)

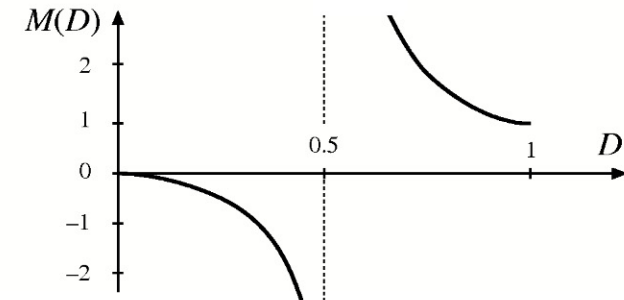
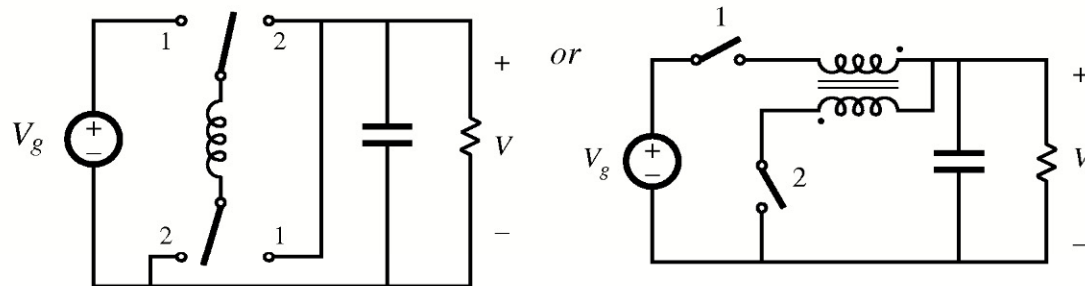
7. Current-fed bridge

$$M(D) = \frac{1}{2D - 1}$$



8. Inverse of Watkins-Johnson

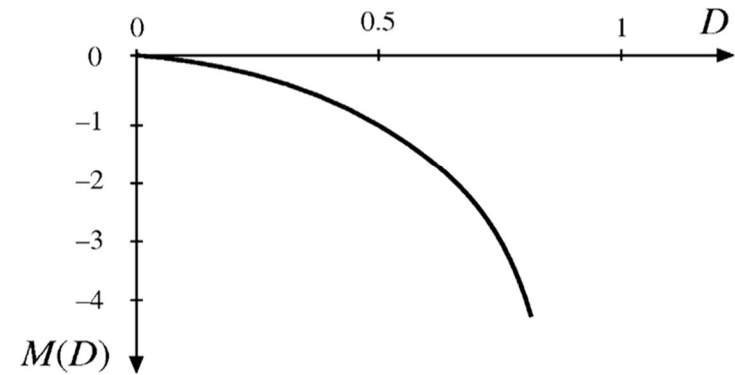
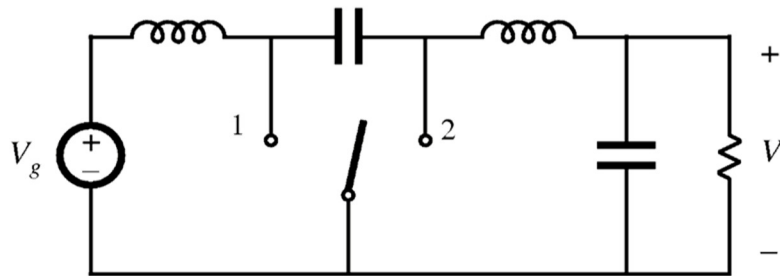
$$M(D) = \frac{D}{2D - 1}$$



Example Two-Inductor Converters

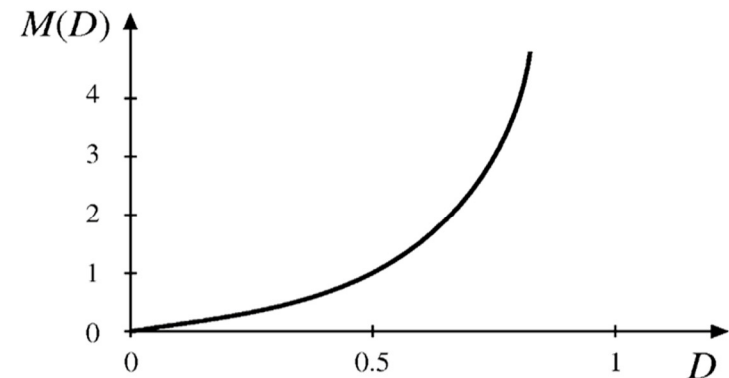
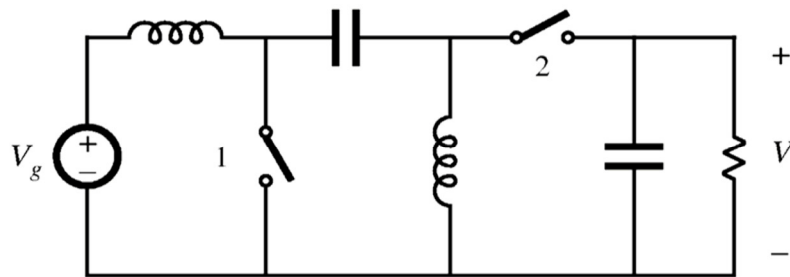
1. *Ćuk*

$$M(D) = -\frac{D}{1-D}$$



2. *SEPIC*

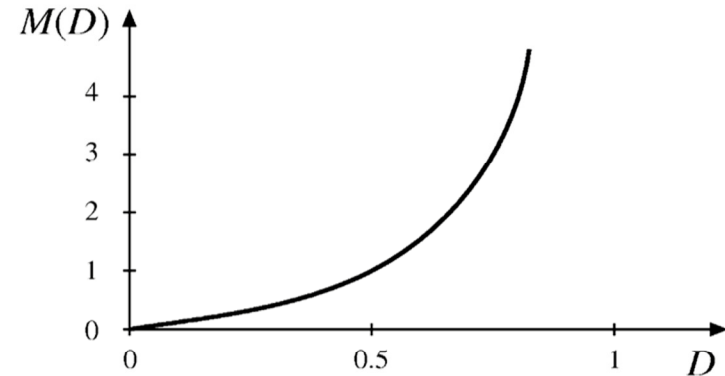
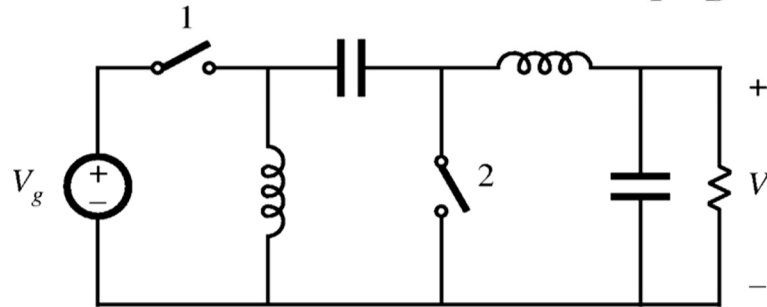
$$M(D) = \frac{D}{1-D}$$



Example Two-Inductor Converters (cont.)

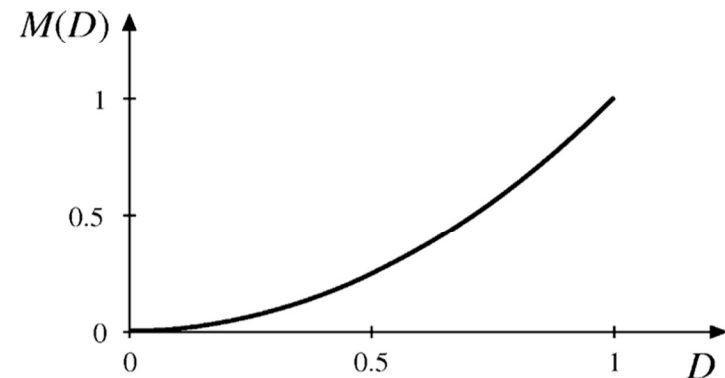
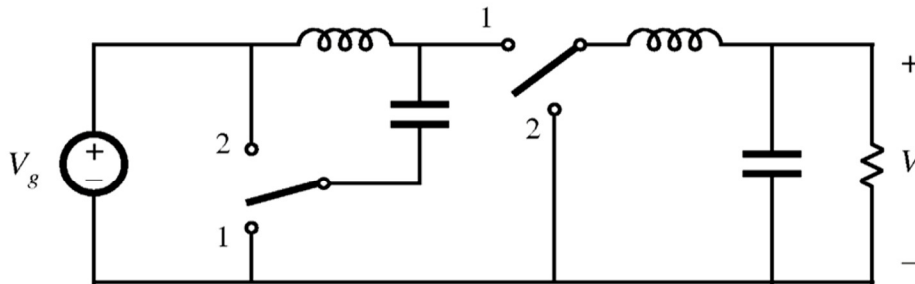
3. Inverse of SEPIC

$$M(D) = \frac{D}{1-D}$$



4. Buck²

$$M(D) = D^2$$

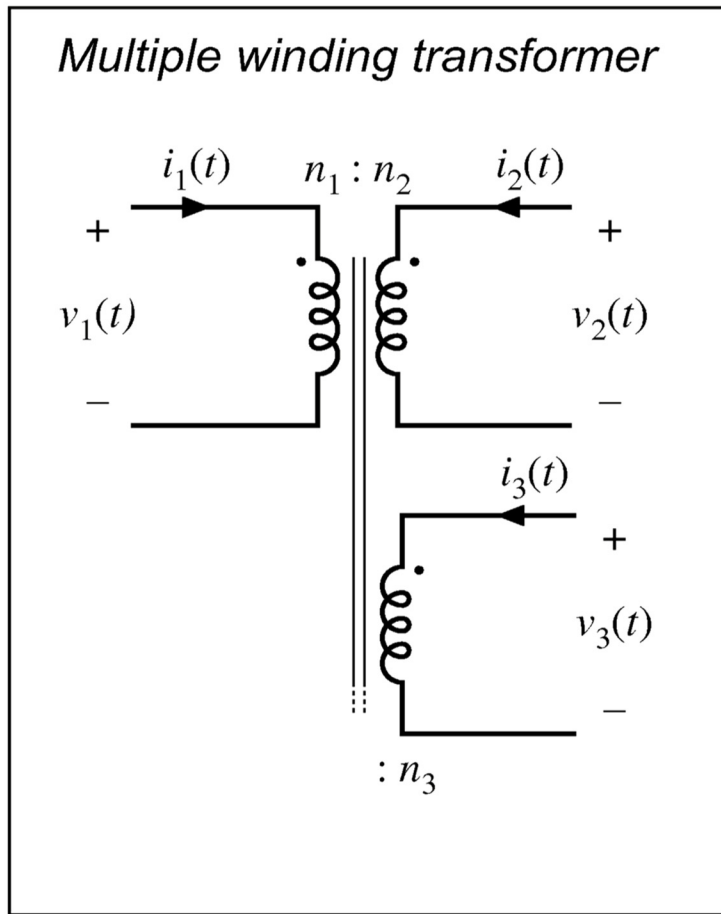


6.3 - Transformer Isolation

Objectives:

- Isolation of input and output ground connections, to meet safety requirements
- Reduction of transformer size by incorporating high frequency isolation transformer inside converter
- Minimization of current and voltage stresses when a large step-up or step-down conversion ratio is needed —use transformer turns ratio
- Obtain multiple output voltages via multiple transformer secondary windings and multiple converter secondary circuits

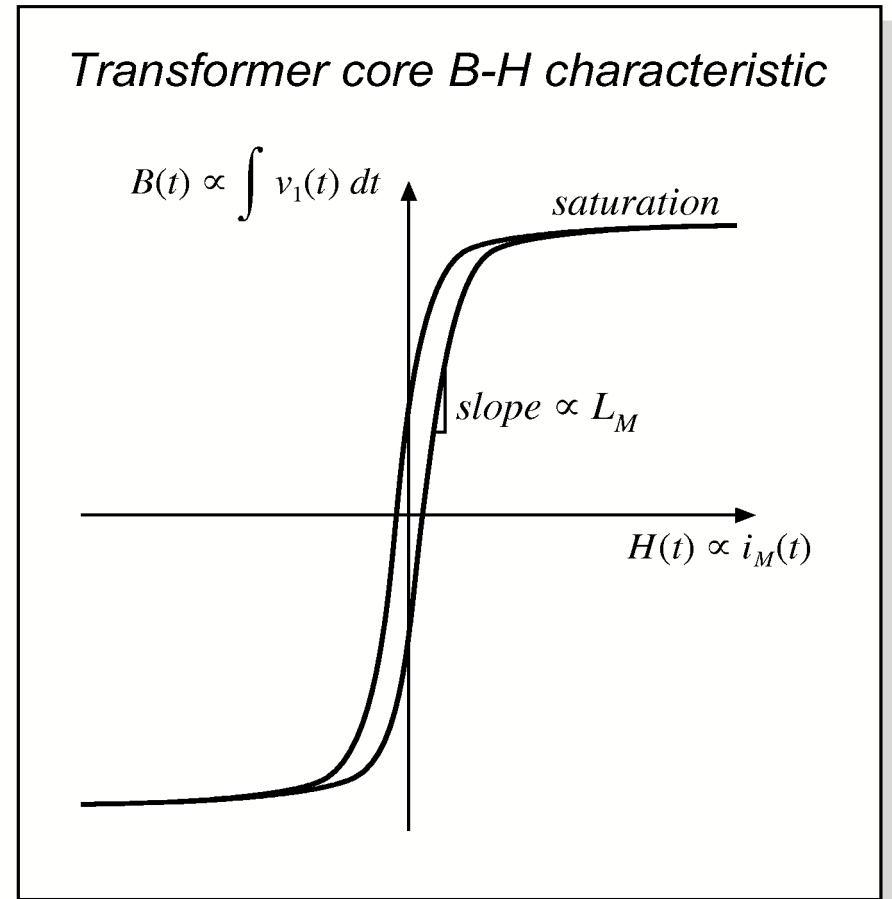
Ideal Transformer Model



$$\frac{v_1(t)}{n_1} = \frac{v_2(t)}{n_2} = \frac{v_3(t)}{n_3} = \dots$$

$$0 = n_1 i_1'(t) + n_2 i_2(t) + n_3 i_3(t) + \dots$$

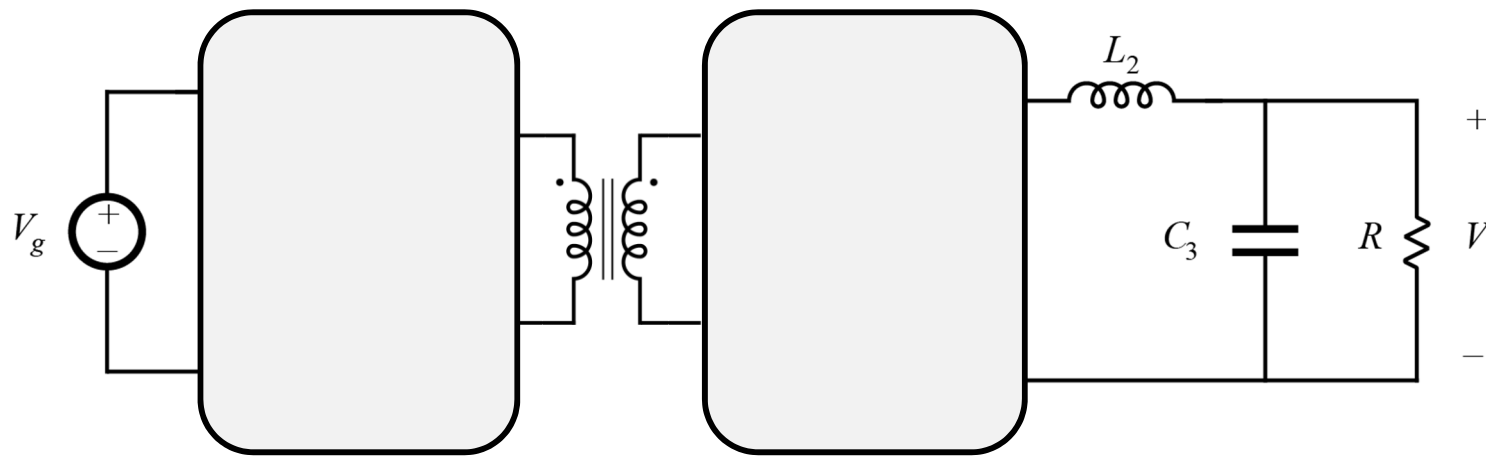
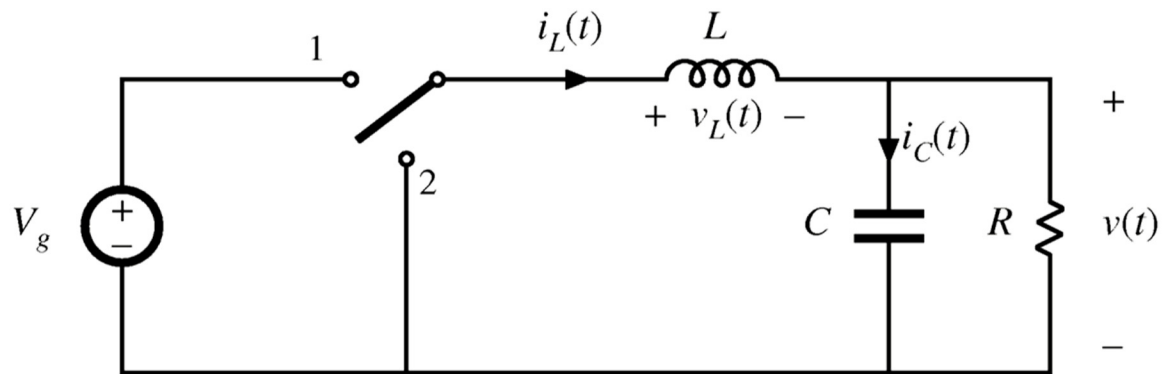
Transformer Saturation



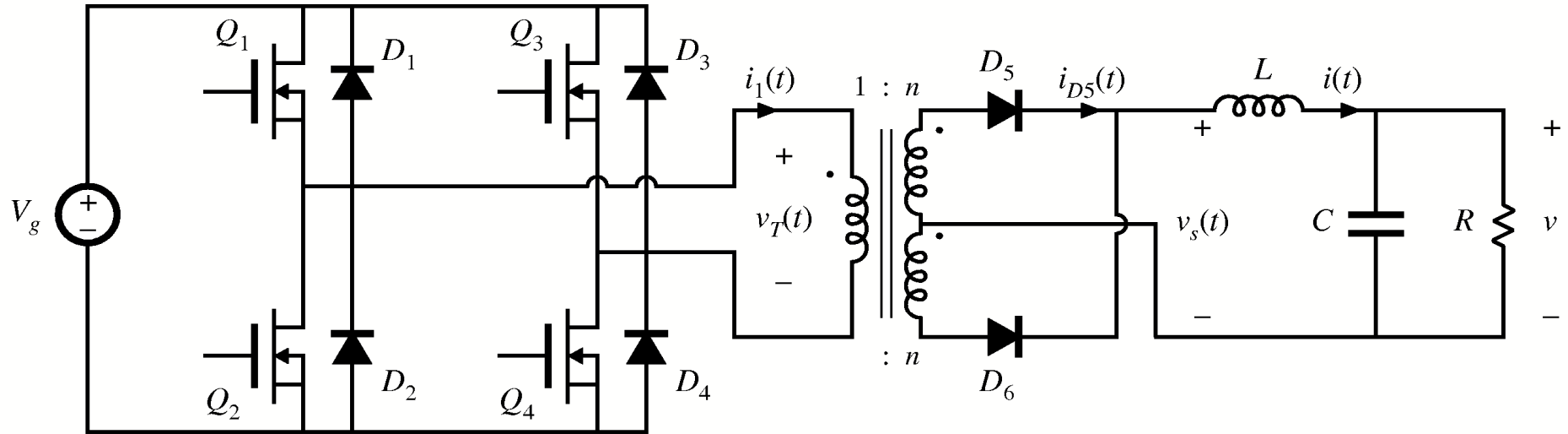
Transformer Reset

- “Transformer reset” is the mechanism by which magnetizing inductance volt-second balance is obtained
- The need to reset the transformer volt-seconds to zero by the end of each switching period adds considerable complexity to converters
- To understand operation of transformer-isolated converters:
 - replace transformer by equivalent circuit model containing magnetizing inductance
 - analyze converter as usual, treating magnetizing inductance as any other inductor
 - apply volt-second balance to all converter inductors, including magnetizing inductance

Buck-derived Isolated Converters



Full Bridge Converter



Full Bridge Converter

