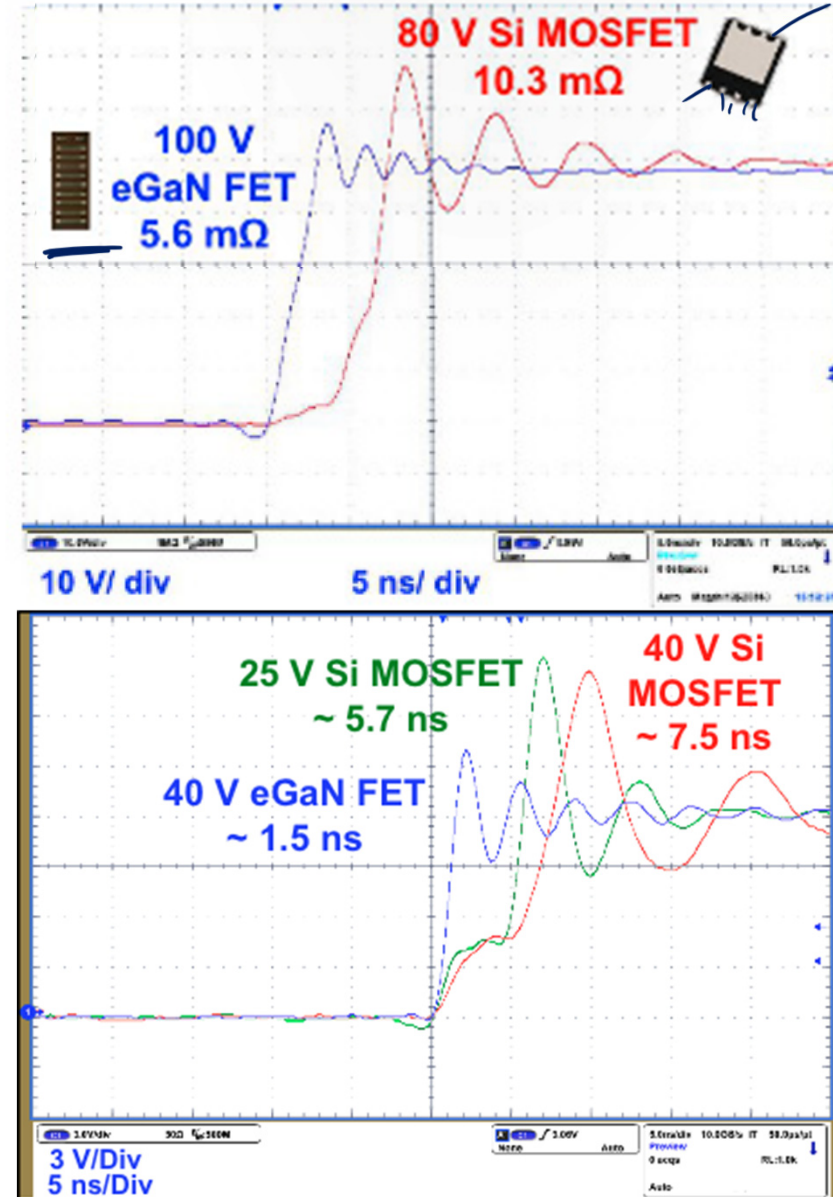


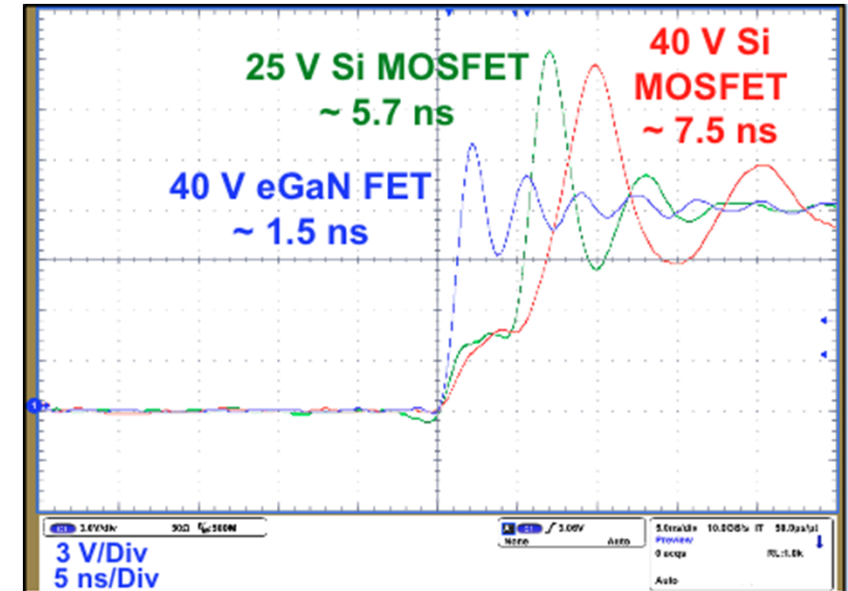
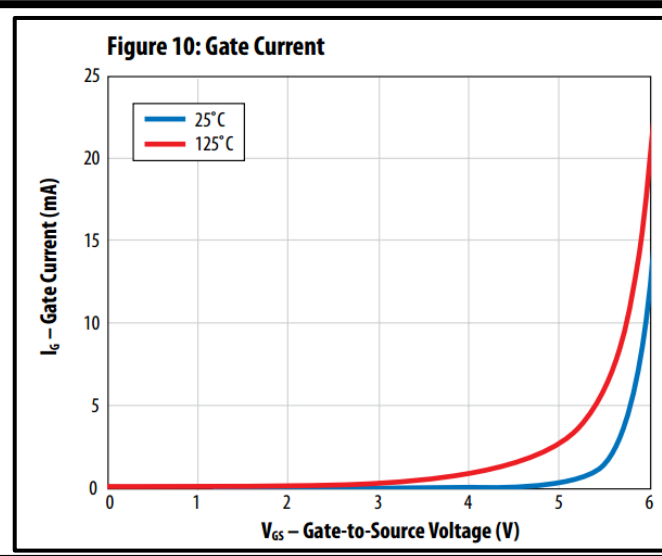
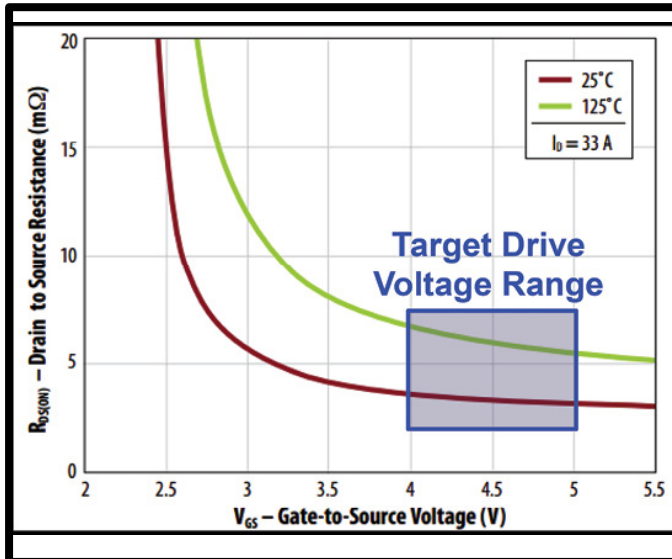
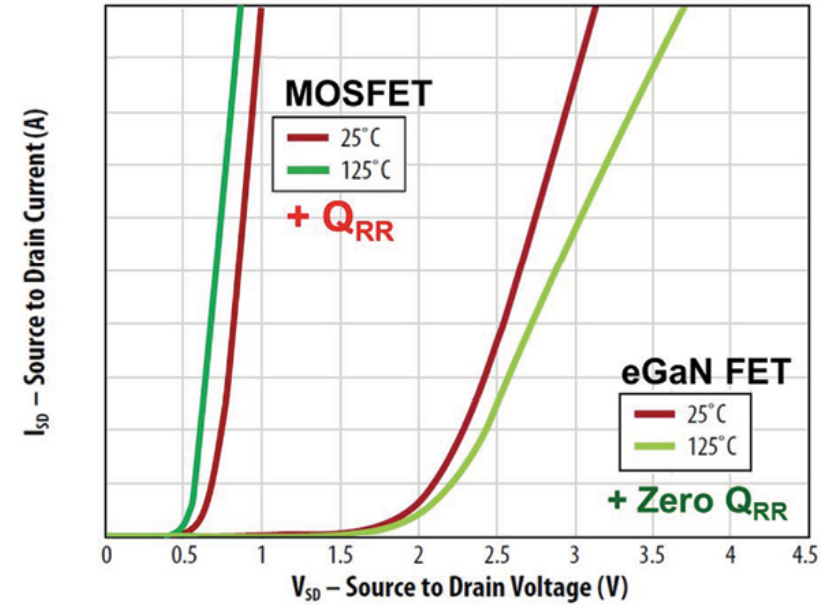
Designing with GaN

- Because of high electric breakdown field and high electron velocity, GaN devices with comparable R_{on} can be significantly smaller and switch must faster.
- Need **very** good layout to prevent ringing from causing overvoltage and device failure.



GaN Design Issues

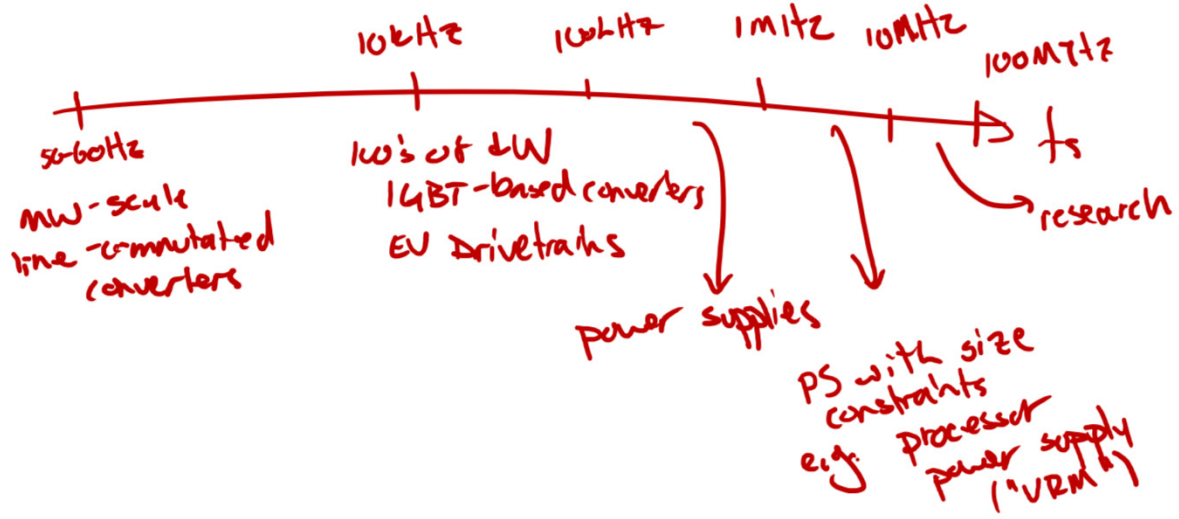
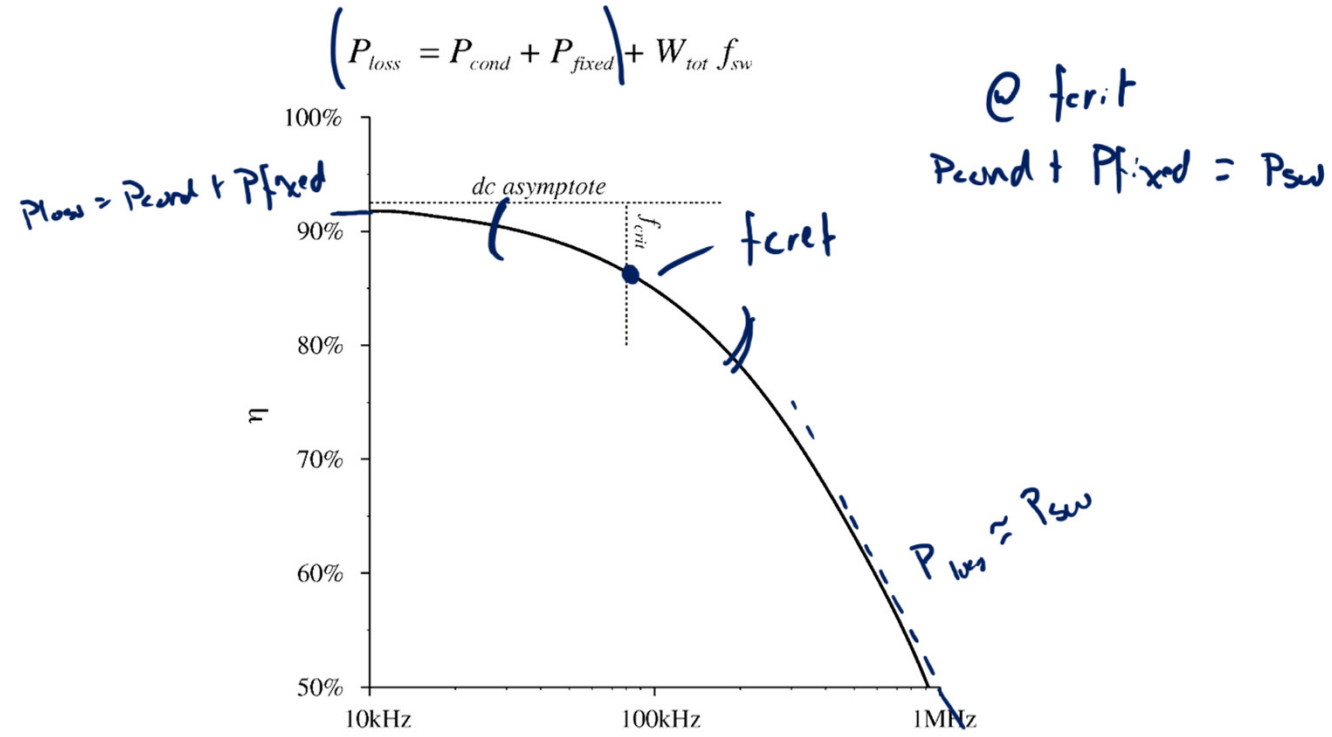
1. Reverse conduction mechanism
2. Sensitivity to parasitics
3. Gate robustness
4. Small size -> Thermal limitations



Converter Efficiency Vs. f_s

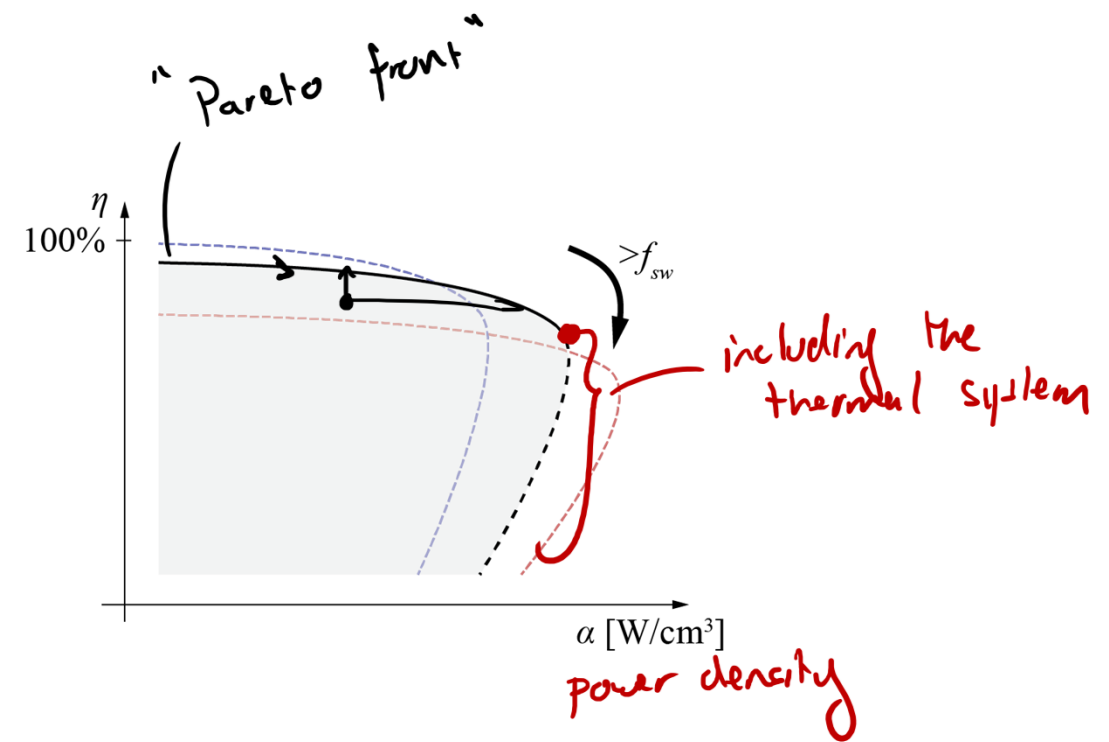
$$P_{loss} = P_{cond} + P_{sw} + P_{fixed}$$

$P_{cond} \propto I \text{ or } I^2$
 $P_{sw} \propto f_s$

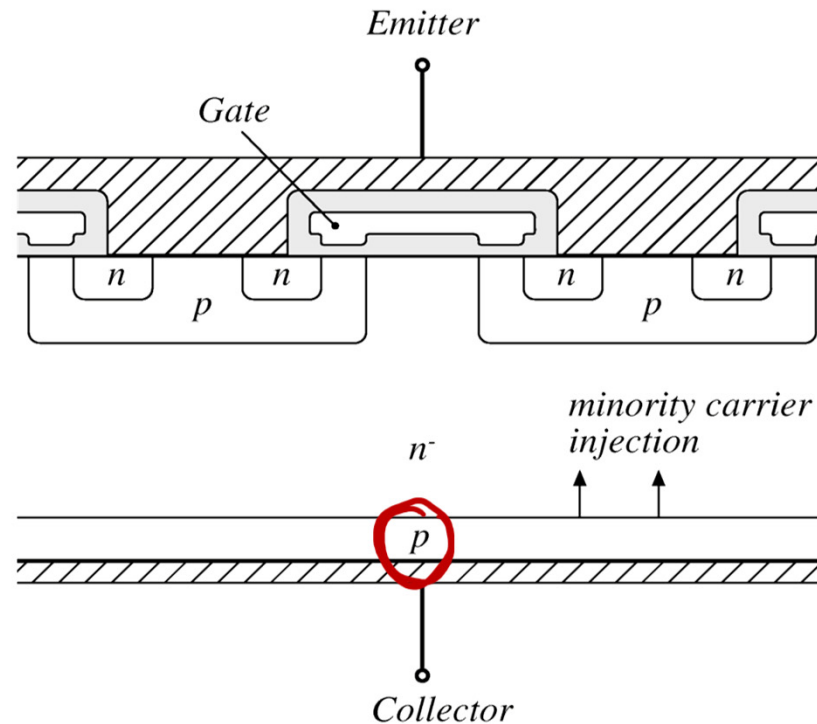


- lower P_{sw} ←
- lower "high" frequency EMI
- - less ripple
- smaller passives
- faster control bandwidth

Converter Optimization

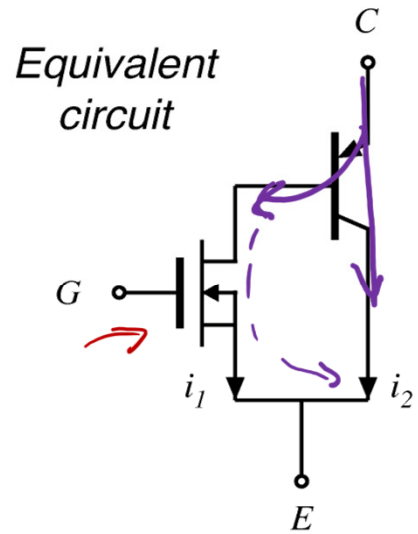
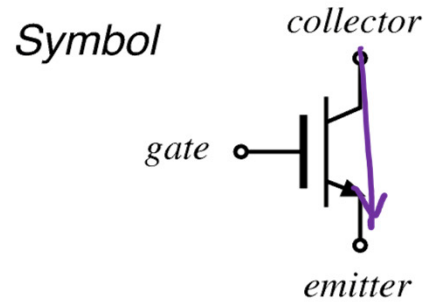


Insulated Gate Bipolar Transistor

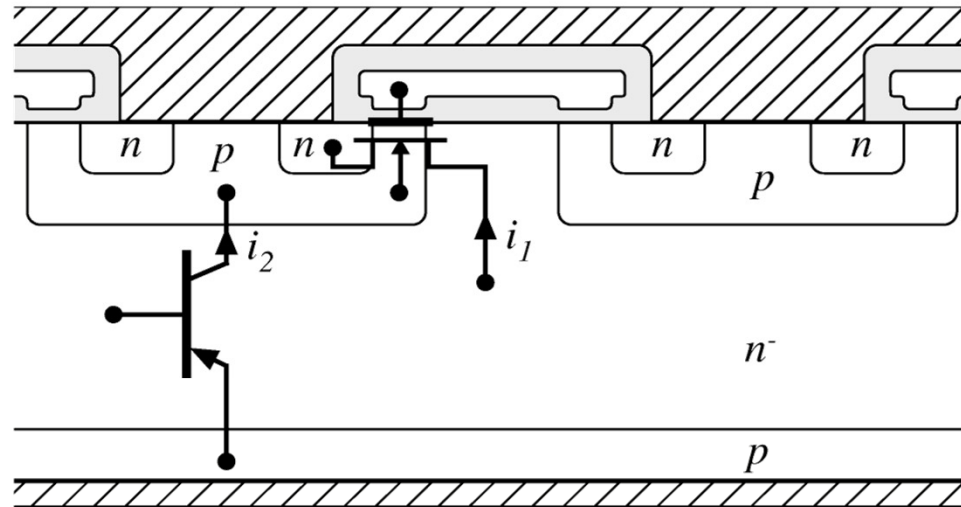


- A four-layer device
- Similar in construction to MOSFET, except extra p region
- On-state: minority carriers are injected into n region, leading to conductivity modulation
- compared with ^{Si}MOSFET: slower switching times, lower on-resistance, useful at higher voltages (up to 1700V)

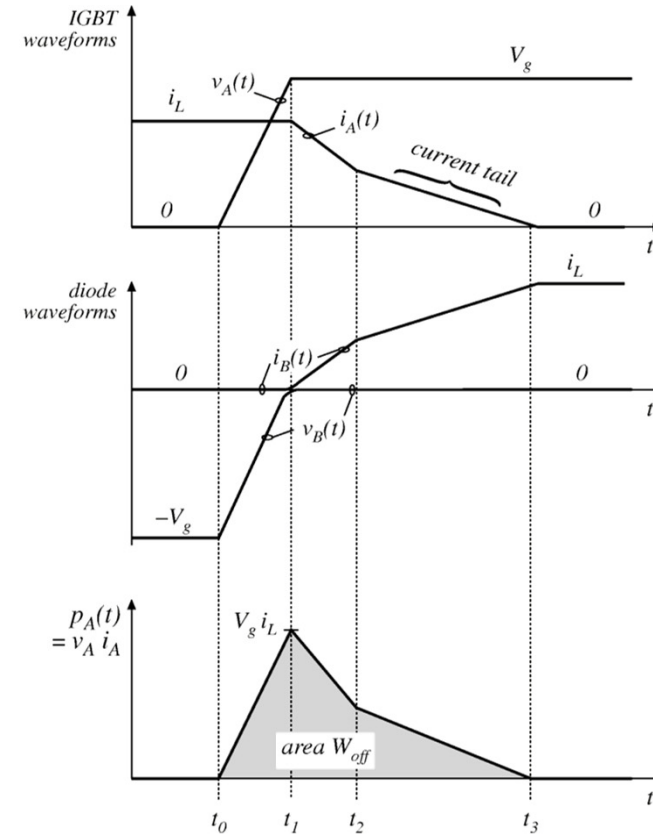
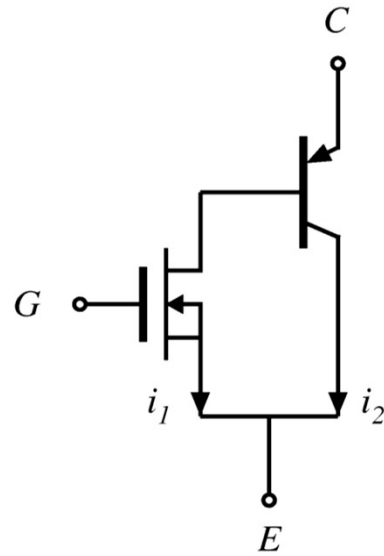
The IGBT



Location of equivalent devices



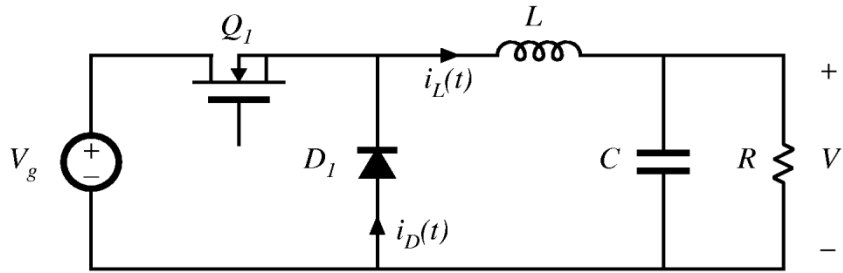
IGBT: Current Tailing



Chapter 5

THE DISCONTINUOUS CONDUCTION MODE

Buck Converter Example

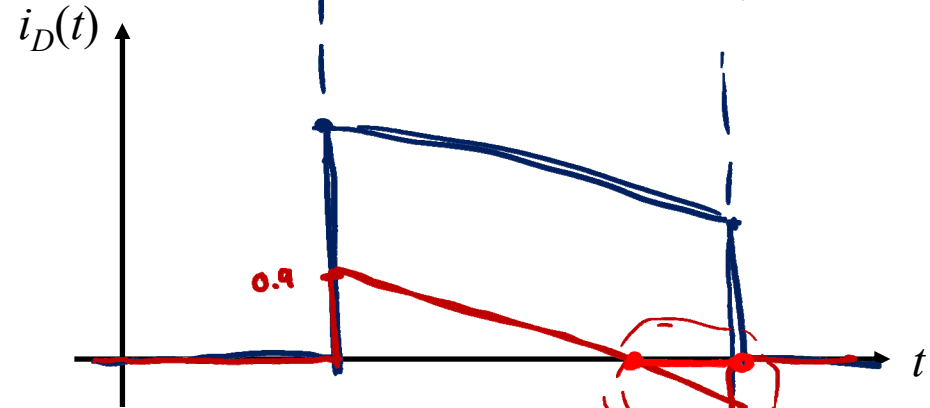
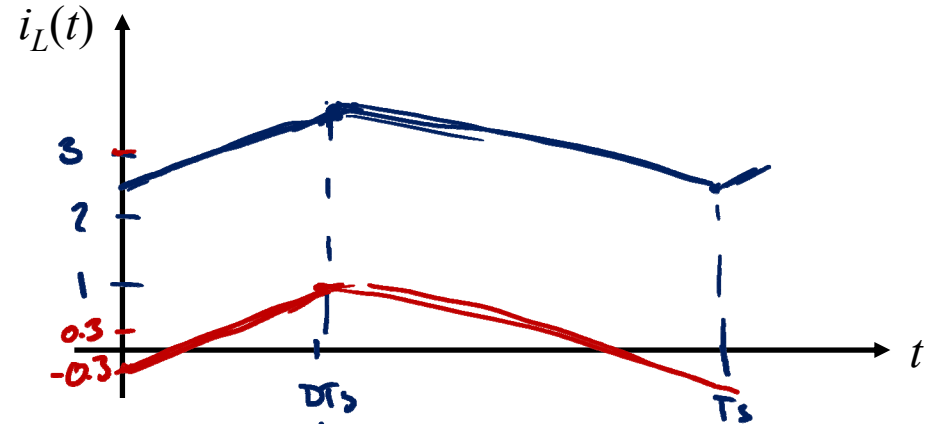


Ideal
 $V = DV_g$
 $I_L = \frac{V}{R}$
 $2\Delta i_L = \frac{V_g - V}{L} \Delta T_s$

ex $V_g = 12V$, $V = 3V$, $L = 100\mu H$, $f_s = 20kHz$
 $T_s = 50ns$

① $R = 1\Omega \rightarrow D = \frac{1}{4}$, $I_L = 3A$, $\Delta i_L = 0.6A$

② $R = 10\Omega \rightarrow D = \frac{1}{4}$, $I_L = 0.3A$, $\Delta i_L = 0.6A$



X current happen