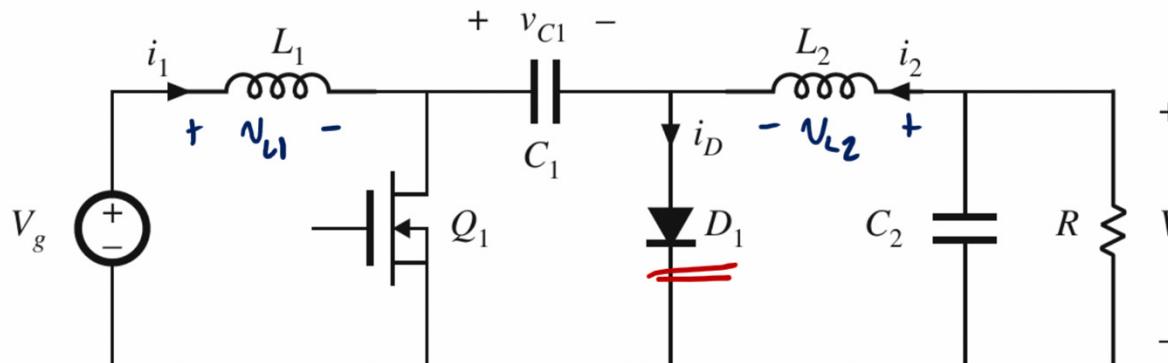


Cuk Converter in CCM



Recall CCM:

$$\langle N_{L1} \rangle = \phi = V_g - D'V_{L1} \rightarrow V_{C1} = \frac{V_g}{D'} \quad \left. \begin{array}{l} \\ \end{array} \right\} V = V_g \left(\frac{-D}{D'} \right), \quad m = \frac{V}{V_g} = -\frac{D}{D'}$$

$$\langle V_{L2} \rangle = \phi = DV_{L1} + V \rightarrow V_{L2} = -\frac{V}{D}$$

$$\langle i_{L1} \rangle = \phi = D(-I_2) + D'I_1 \rightarrow I_1 = \frac{D}{D'} I_2$$

$$\langle i_{L2} \rangle = \phi = -I_2 - \frac{V}{R} \rightarrow I_2 = -\frac{V}{R}$$

when diode is on, $i_D = I_1 + I_2$

$$\Delta i_{L1} = \frac{1}{2} \frac{V_g}{L} DT_s$$

CCM when $I_1 + I_2 > \Delta i_{L1} + \Delta i_{L2}$

$$\Delta i_{L2} = \frac{1}{2} \left(-\frac{V}{L} \right) DT_s$$

Cuk Converter DCM Boundary

$$I_1 + I_2 = \frac{(-v)}{2} \left(1 + \frac{D}{D'} \right) \rightarrow D_{iL1} + D_{iL2} = \frac{I_s}{2} \left(\frac{V_g}{L_1} D + \frac{-v}{L_2} D' \right)$$

$$\cancel{\frac{V_g}{L_1} D} \left(1 + \frac{D}{D'} \right) \rightarrow \frac{I_s}{2} \left(\cancel{\frac{V_g}{L_1} D} + \cancel{\frac{D}{L_2} \frac{V_g}{L_2} D'} \right)$$

$$\frac{1}{RD'} \left(\frac{1}{D'} \right) \rightarrow \frac{T_s}{2} \left(\frac{1}{L_1} + \frac{1}{L_2} \right)$$

$$\frac{2}{R T_s} \left(\frac{1}{L_1} + \frac{1}{L_2} \right) \rightarrow (D')^2$$

$$\frac{1}{L_1} + \frac{1}{L_2} = L_{eq} = L_1 \parallel L_2$$

$$K_c = \boxed{\frac{2 L_{eq}}{R T_s} \rightarrow (D')^2} = k_{crit}(D)$$

Cuk Converter in DCM

$$v_u = v_g$$

$$\textcircled{1} \quad v_{L_2} = v(t) + v_{C_1}(t)$$

$v + v_{C_1}$

$$i_{C_1} = -i_2(t)$$

$$i_{C_2} = -i_2(t) - \frac{v(t)}{R}$$

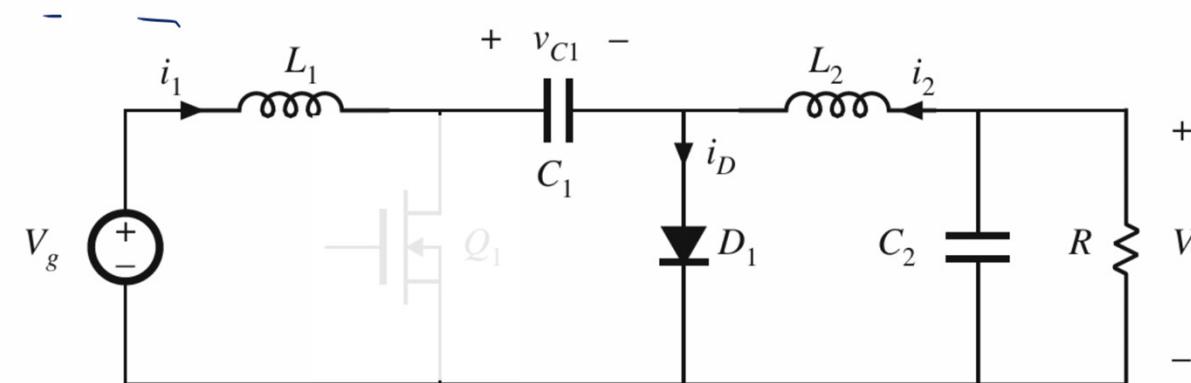
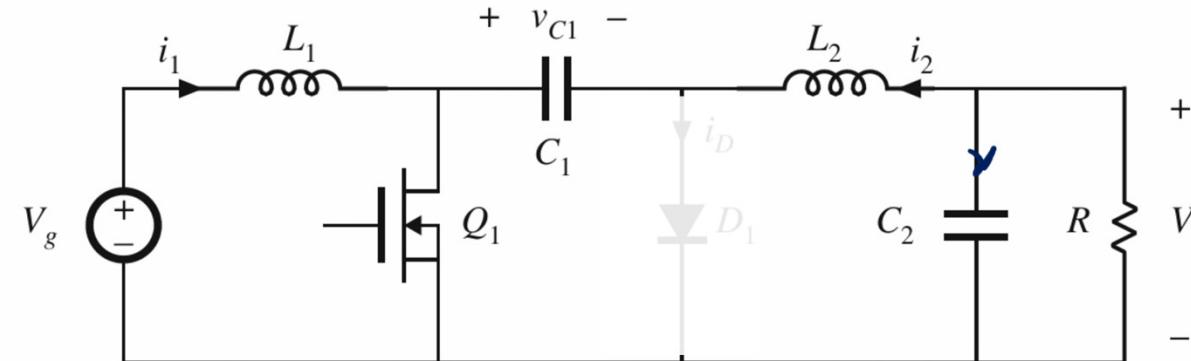
$$i_{C_1} = i_1(t)$$

$$i_{C_2} = -i_2(t) - \frac{v}{R}$$

\textcircled{2}

$$v_{U_1} = v_g - v_{C_1}$$

$$v_{L_2} = V$$



\textcircled{3}

$$v_{U_1} = \phi$$

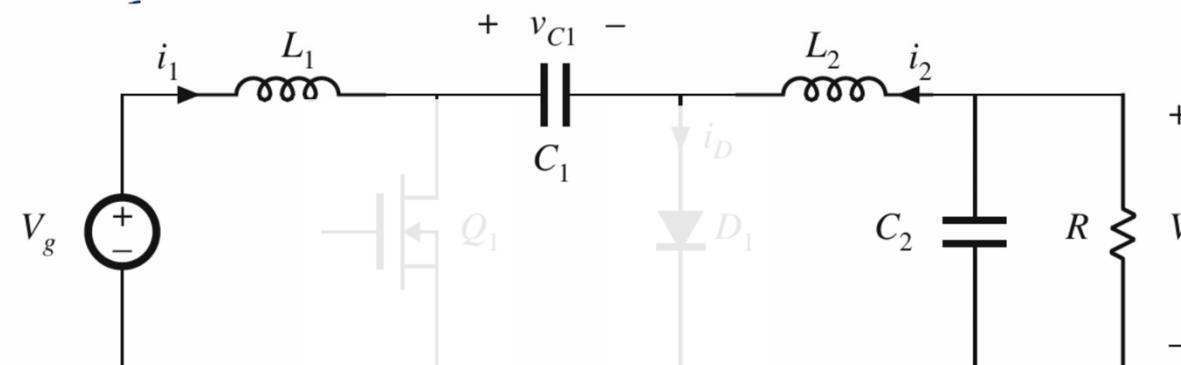
$$v_{L_2} = \phi$$

↓

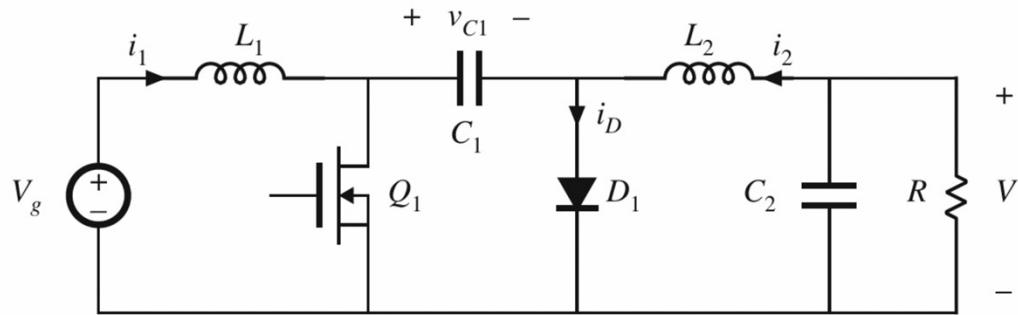
$$v_{C_1} = v_g - V$$

$$i_{C_1} = i_1 = -i_2 = I_x$$

$$i_{C_2} = -i_2(t) - \frac{v}{R}$$



Cuk Waveforms in DCM



$$\langle N_{L1} \rangle = \phi = D_1 V_g + D_2 (V_g - V_{C1})$$

$$\phi = (D_1 + D_2) V_g - D_2 V_{C1}$$

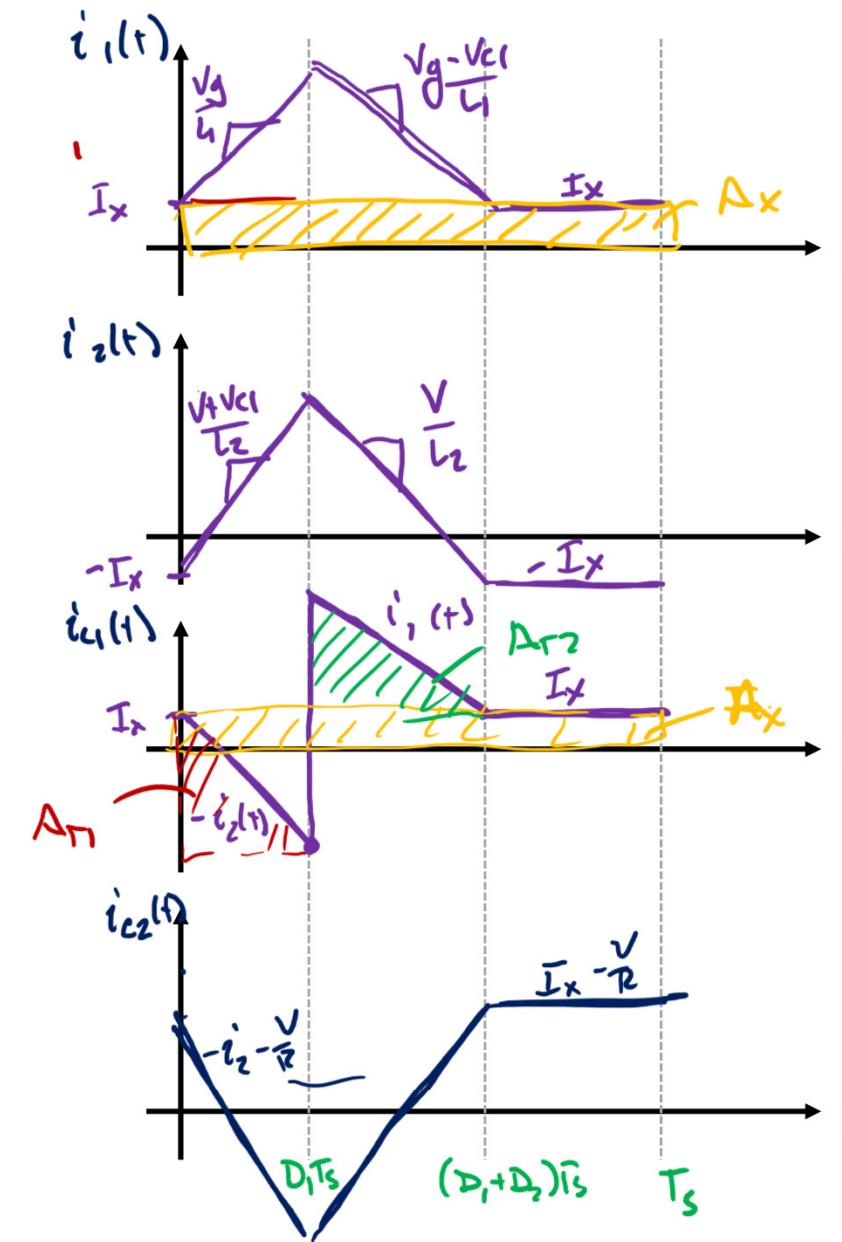
$$V_{C1} = V_g \frac{D_1 + D_2}{D_2}$$

$$\langle N_{L2} \rangle = \phi = V(D_1 + D_2) + V_{C1}(D_1)$$

$$V_{C1} = -V \frac{D_1 + D_2}{D_1}$$

$$V = -V_g \frac{D_1}{D_2}$$

$$\rightarrow D_2 = -\frac{V_g}{V} D_1$$



Cuk Conversion Ratio

$$\langle i_{ca} \rangle = \phi = \frac{1}{T_s} \int_0^{T_s} i_{ca}(t) dt = \frac{1}{T_s} [A_{T1} + A_{T2} + A_x]$$

$$\phi = \cancel{\frac{1}{T_s}} \left[\frac{1}{2} D_1 T_s \cancel{\frac{V}{L_2}} D_2 T_s + \frac{1}{2} D_2 T_s \cancel{\frac{V_g}{L_1}} D_1 T_s + I_x T_s \right]$$

$$-I_x = \frac{1}{2} D_1 D_2 T_s \left(\frac{V}{L_2} + \frac{V_g}{L_1} \right)$$

$$\langle i_{c2} \rangle = \phi = \frac{1}{T_s} \int_0^{T_s} i_{c2}(t) dt = \frac{1}{T_s} \int_0^{T_s} -i_2 - \frac{V}{R} dt = -\frac{1}{T_s} \int_0^{T_s} i_2 dt - \frac{V}{R}$$

$$\phi = -\frac{1}{T_s} \left[\frac{1}{2} (D_1 + D_2) T_s \cancel{\frac{V}{L_2}} D_2 T_s - I_x T_s \right] - \frac{V}{R}$$

$$\phi = -\frac{1}{T_s} \left[\frac{1}{2} (D_1 + D_2) T_s \cancel{\frac{V}{L_2}} D_2 T_s + T_s \frac{1}{2} D_1 D_2 T_s \left(\frac{V}{L_2} + \frac{V_g}{L_1} \right) \right] - \frac{V}{R}$$