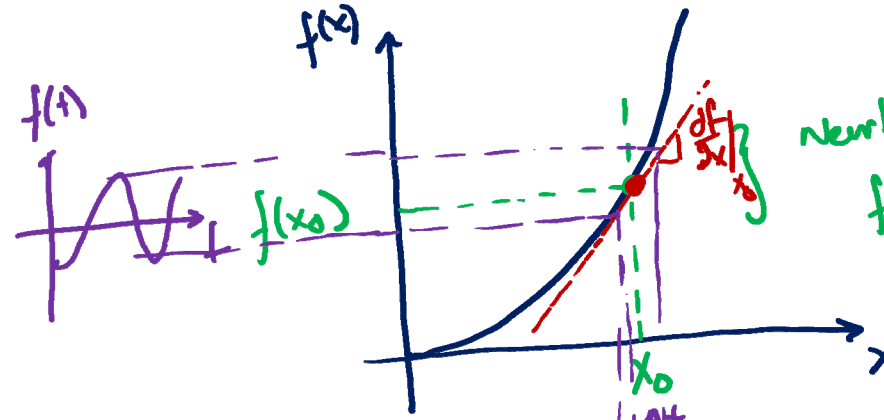


Small Signal Modeling: Linearization



nearby $f(x) \approx f(x_0) + \left. \frac{\partial f}{\partial x} \right|_{x_0} (x - x_0) + \frac{1}{2!} \left. \frac{\partial^2 f}{\partial x^2} \right|_{x_0} (x - x_0)^2 + \dots$

neglect higher order terms

if we have a multivariate function
linearize

$$f(x, y, z) \approx \underbrace{f(x_0, y_0, z_0)}_{F_0} + \left. \frac{\partial f}{\partial x} \right|_{F_0} (x - x_0) + \left. \frac{\partial f}{\partial y} \right|_{F_0} (y - y_0) + \left. \frac{\partial f}{\partial z} \right|_{F_0} (z - z_0) + \underbrace{\dots}_{\text{higher order terms}}$$

Notation

$(x - x_0) \rightarrow \hat{x}$
small-signal $\hat{x} \ll x_0 = X$ (capital)

(1) Perturb and Linearize

$$d'(t) \rightarrow D' - \hat{d}$$

$$L \frac{d\langle i_L \rangle}{dt} = \langle v_g \rangle - \frac{d'(t) \langle v \rangle}{(1-d'(t))}$$

① Replace all time-varying terms $(\langle x \rangle \& d(t))$ with DC + small signal
 $\langle x \rangle \rightarrow X + \hat{x}$

② Neglect higher order terms \rightarrow anything with a product of two
small-signal variables $\&$ separate DC \neq AC equations

$$L \frac{d}{dt} (I_L + \hat{i}_L) = V_g + \hat{v}_g - (1 - D - \hat{d}) (V + \hat{v})$$

$$L \frac{d}{dt} I_L + L \frac{d}{dt} \hat{i}_L = \underbrace{V_g - D'V}_{DC} + \underbrace{\hat{v}_g + \hat{d}V - D'\hat{v}}_{AC} + \hat{d}\hat{v}$$

neglect (linearization)

$$\left\{ \begin{array}{l} \text{DC (same as steady-state model)} \\ \boxed{L \frac{d}{dt} \hat{i}_L = \hat{v}_g + \hat{d}V - \hat{v}D'} \rightarrow AC \end{array} \right.$$

(2) 1st order Taylor Series Expansion

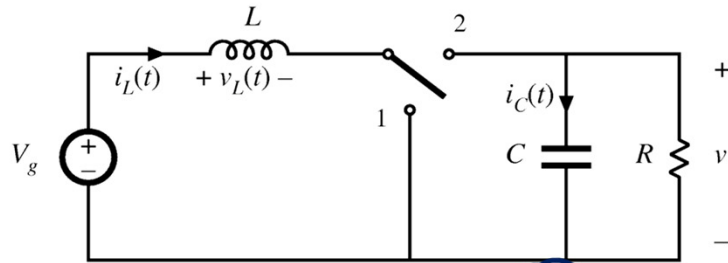
$$\mathcal{L} \frac{d\langle i_i \rangle}{dt} = \frac{\langle v_g \rangle - d'(t) \langle v \rangle}{f(v_g, d, v)}$$

$$\mathcal{L} \frac{d\hat{i}_i}{dt} = \left. \frac{\partial f}{\partial v_g} \right|_{\hat{v}_g} + \left. \frac{\partial f}{\partial d} \right|_{\hat{d}} + \left. \frac{\partial f}{\partial v} \right|_{\hat{v}}$$

$\begin{matrix} x \\ y \rightarrow v_g \\ d \rightarrow d \\ v \rightarrow v \end{matrix}$

$$\mathcal{L} \frac{d\hat{i}_i}{dt} = 1 \cdot \hat{v}_g + V \hat{d} - D' \hat{v}$$

Equivalent Circuit Modeling: Boost Example



①

$$v_L(t) = V_g(t) - v(t)$$

$$i_C(t) = -\frac{v(t)}{R}$$

②

$$v_L(t) = V_g(t) - v(t)$$

$$i_L(t) = i_C(t) - \frac{v(t)}{R}$$

Average

$$\langle v_L \rangle = L \frac{d\langle i_L \rangle}{dt} = \langle V_g \rangle d'(t) \langle v \rangle$$

$$\langle i_C \rangle = C \frac{d\langle v \rangle}{dt} = d'(t) \langle i_L \rangle - \frac{\langle v \rangle}{R}$$

Process:

solve converter equations for all v_L, i_C & (if necessary) $i_L(t)$ in each subinterval

① Average over one switching period (w/out assuming/enforcing steady-state)

Averaged, nonlinear circuit

② Linearize all equations by } Perturb & linearize
1st or Taylor Series

Averaged, linearized equations

③ Sketch & solve ac-equivalent averaged circuit

Linearization

Volt-second balance

$$L \frac{d\hat{i}_L}{dt} = \hat{V}_g - D\hat{v} + V_d\hat{d}$$

Cap-charge balance :

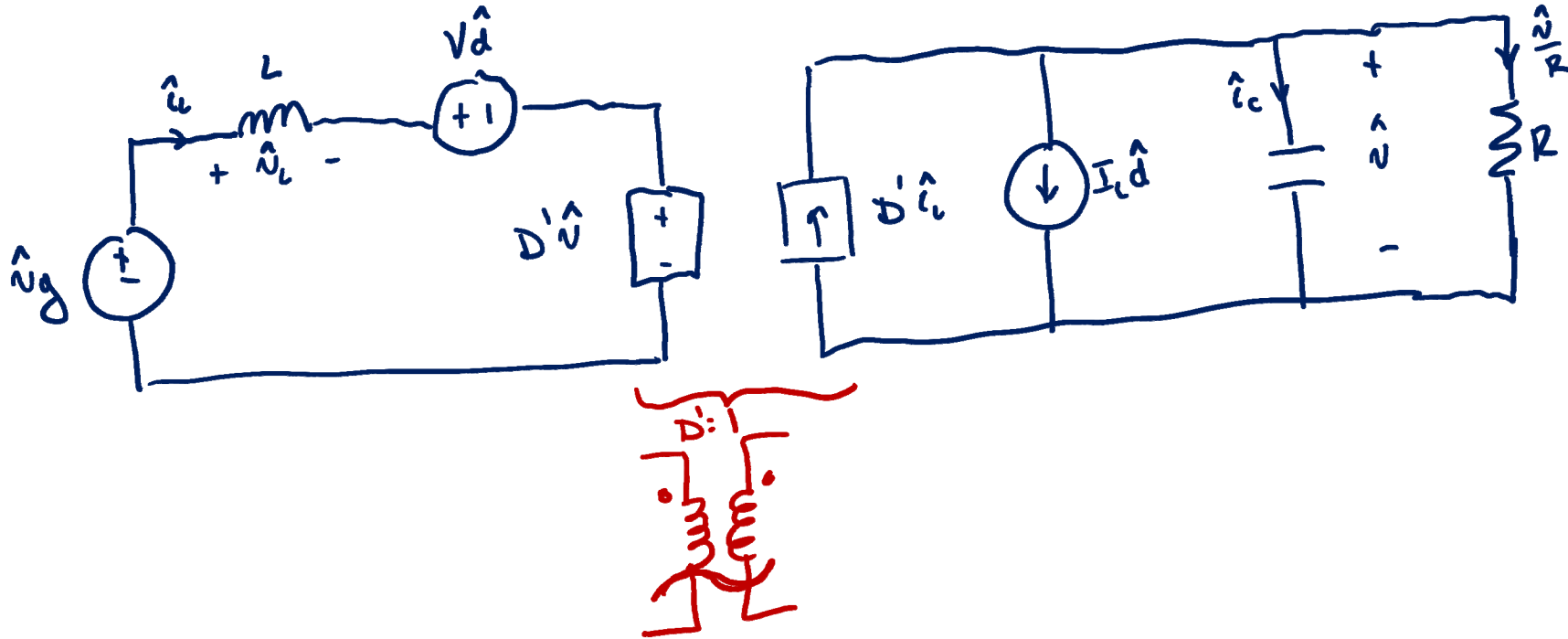
$$C \frac{d\langle v \rangle}{dt} = d'(t)\langle i_L \rangle - \frac{\langle v \rangle}{R}$$

$$C \frac{d\hat{v}}{dt} = D'\hat{i}_L - I_L\hat{d} - \frac{\hat{v}}{R}$$

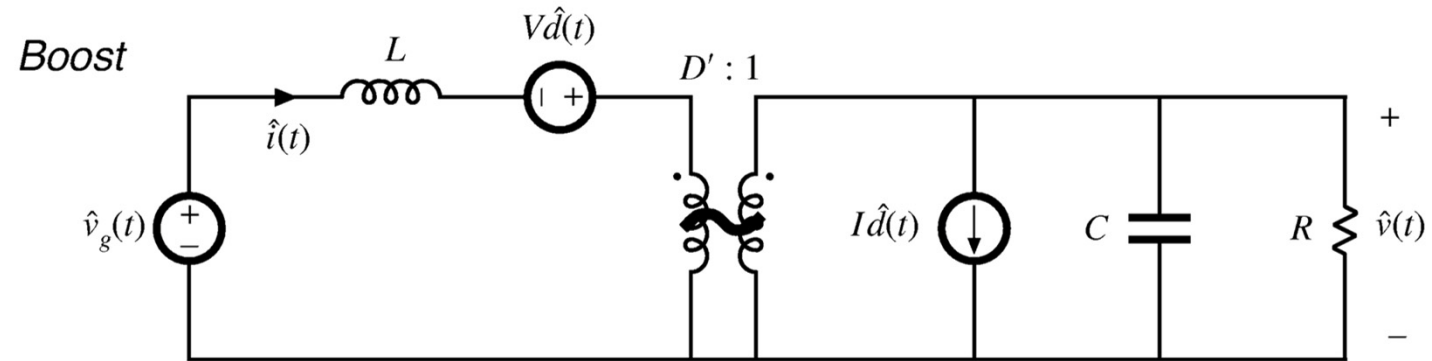
Equivalent Circuit Model

$$\hat{N}_L = L \frac{d\hat{i}_L}{dt} = \hat{N}_g - D'\hat{v} + v_d$$

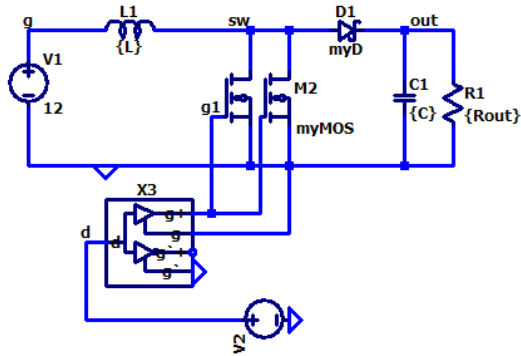
$$\hat{i}_c = C \frac{d\hat{v}}{dt} = D'\hat{i}_L - I_d \hat{d} - \frac{R}{L} \hat{v}$$



Boost Converter Averaged, AC, Linear Circuit Model



Model Simulation

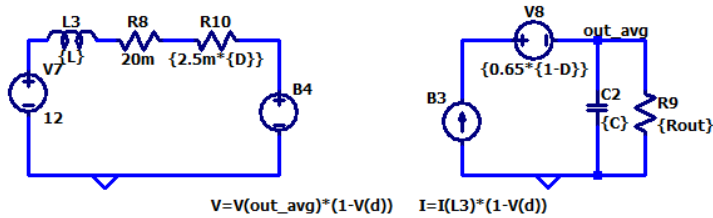


```
.param
+ L = 22u
+ C = 22u
+ Rout = 48
+ D = .755
```

```
.ic V(out)=48 I(L1)=3.1A
```

```
.tran 0 {1500/202k} {800/202k} startup
.lib myParts.lib
```

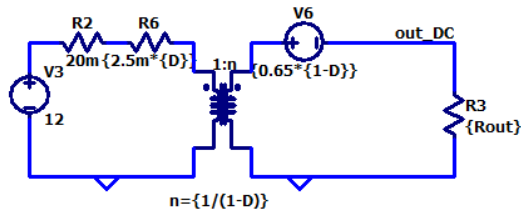
Full Switching Model



```
.ic V(out_avg)=48 I(L3)=4A
```

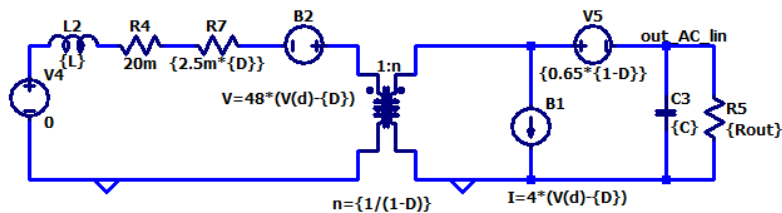
$$V = V(\text{out_avg}) * (1 - V(d)) \quad I = I(L3) * (1 - V(d))$$

Averaged, Nonlinear



$$n = \{1/(1-D)\}$$

DC Averaged Model



```
.ic V(out_AC_lin)=0 I(L2)=0
```

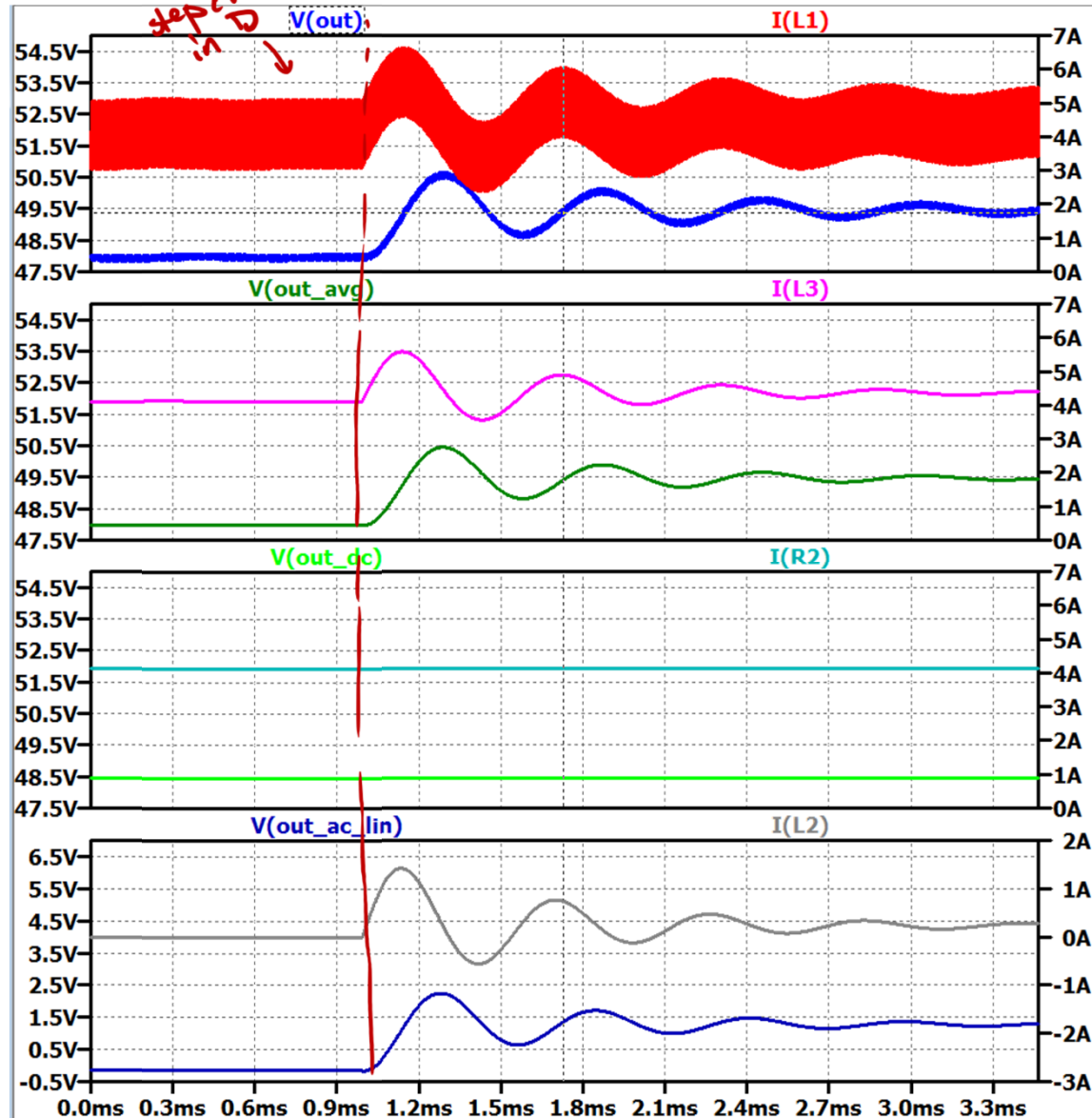
$$V = 48 * (V(d) - D) \quad I = 4 * (V(d) - D)$$

$$n = \{1/(1-D)\}$$

$$I = 4 * (V(d) - D)$$

AC Averaged, Linearized Model

Model Comparison



Full Switching Model

Averaged, Nonlinear

DC Averaged Model

AC Averaged,
Linearized Model

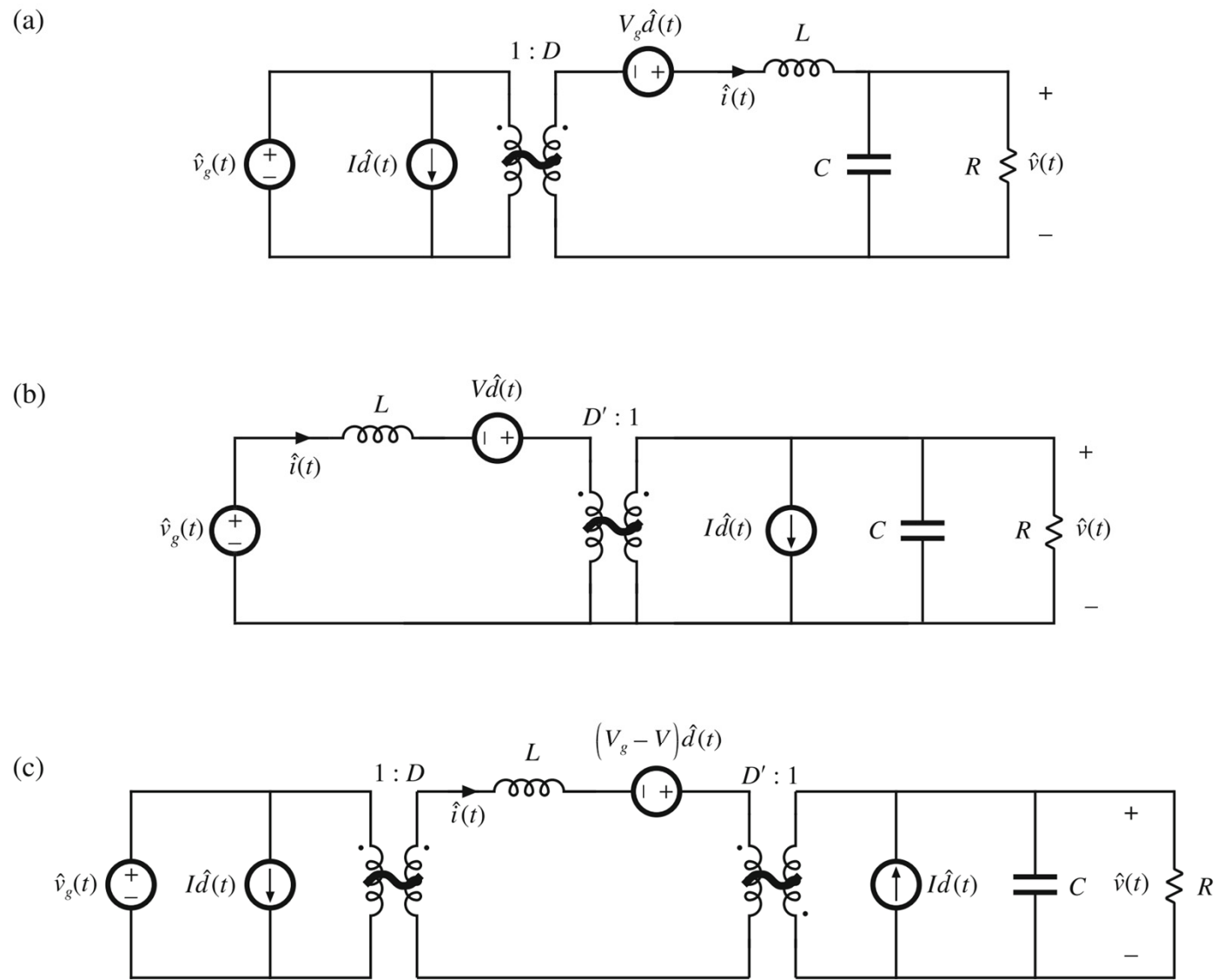


Fig. 7.18 Averaged small-signal ac models for several basic converters operating in continuous conduction mode: (a) buck, (b) boost, (c) buck–boost