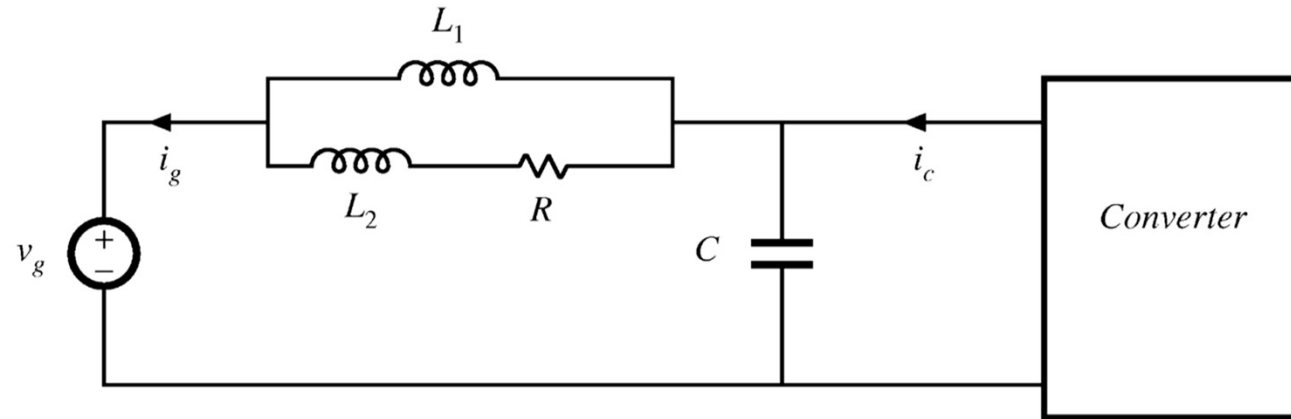


Example: Damped Input EMI Filter

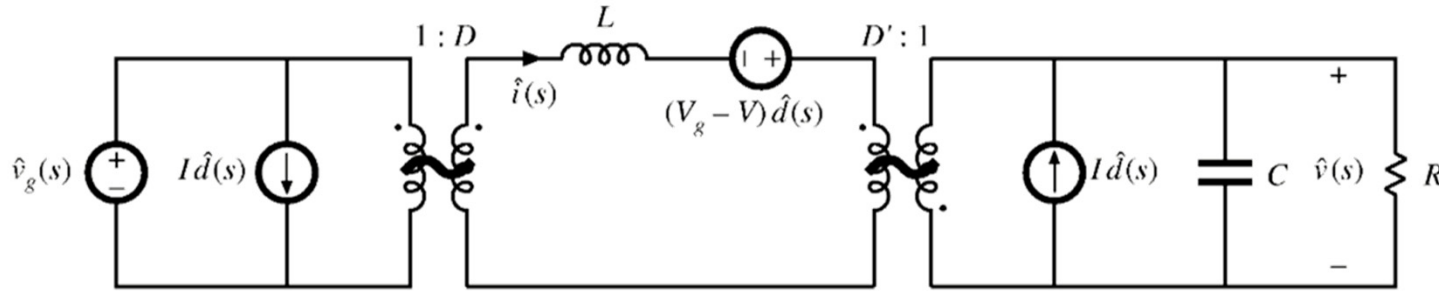


$$G(s) = \frac{i_g(s)}{i_c(s)} = \frac{1 + s \frac{L_1 + L_2}{R}}{1 + s \frac{L_1 + L_2}{R} + s^2 L_1 C + s^3 \frac{L_1 L_2 C}{R}}$$

Approximate Roots of High-Order Polynomial



Graphical Construction: Output Impedance



$$G_{vd}(s) = \left(- \frac{V_g - V}{D'} \right) \frac{1 - sL \frac{I}{D'(V_g - V)}}{1 + \frac{sL}{D'^2 R} + s^2 \frac{LC}{D'^2}}$$

Numerical Example

$$L = 160 \mu\text{H}$$

$$D = 0.6$$

$$R = 10 \Omega$$

$$C = 160 \mu\text{F}$$

$$V_g = 30 \text{ V}$$

$$V = -45 \text{ V}$$

$$L/D'^2 = 1 \text{ mH}$$

$$\omega_0 = \sqrt{\frac{D'^2}{LC}} = 2.5 \text{ krad/s}$$

$$Q = \frac{D'R}{\sqrt{L/C}} = 4$$

$$\omega_z = \frac{LI}{(Vg-V)} = 16.7 \text{ krad/s}$$

$$G_{d0} = \frac{V_a - V}{D'} = 187.5 \text{ V}$$

$$G_{g0} = \frac{-D}{D'} = 1.5$$

$$\rightarrow f_0 = 400 \text{ Hz}$$

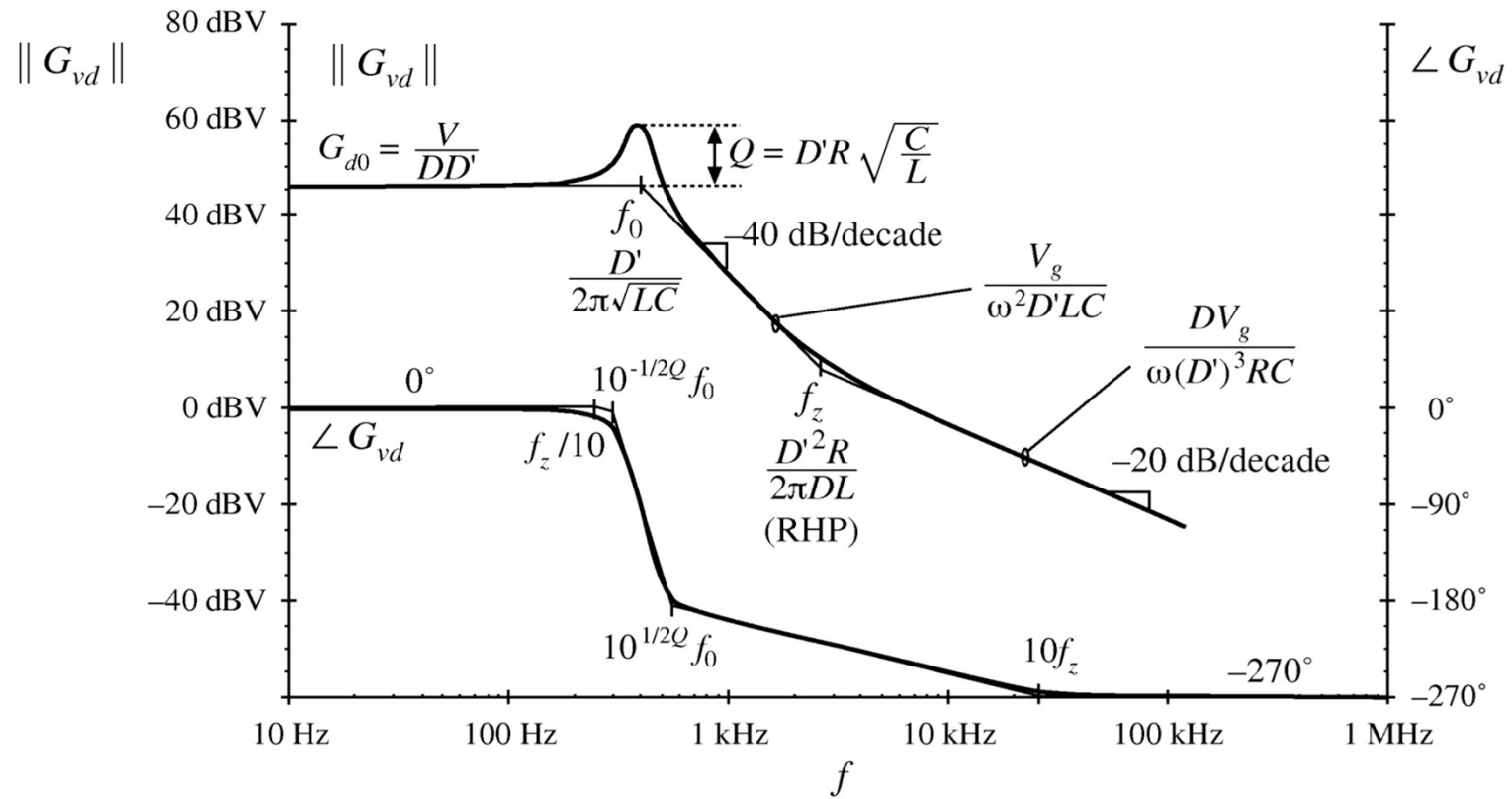
$$\rightarrow \|Q\|_{\text{dB}} = 12 \text{ dB}$$

$$\rightarrow f_z = 2.7 \text{ kHz}$$

$$\rightarrow \|G_{d0}\|_{\text{dB}} = 45.5 \text{ dBV}$$

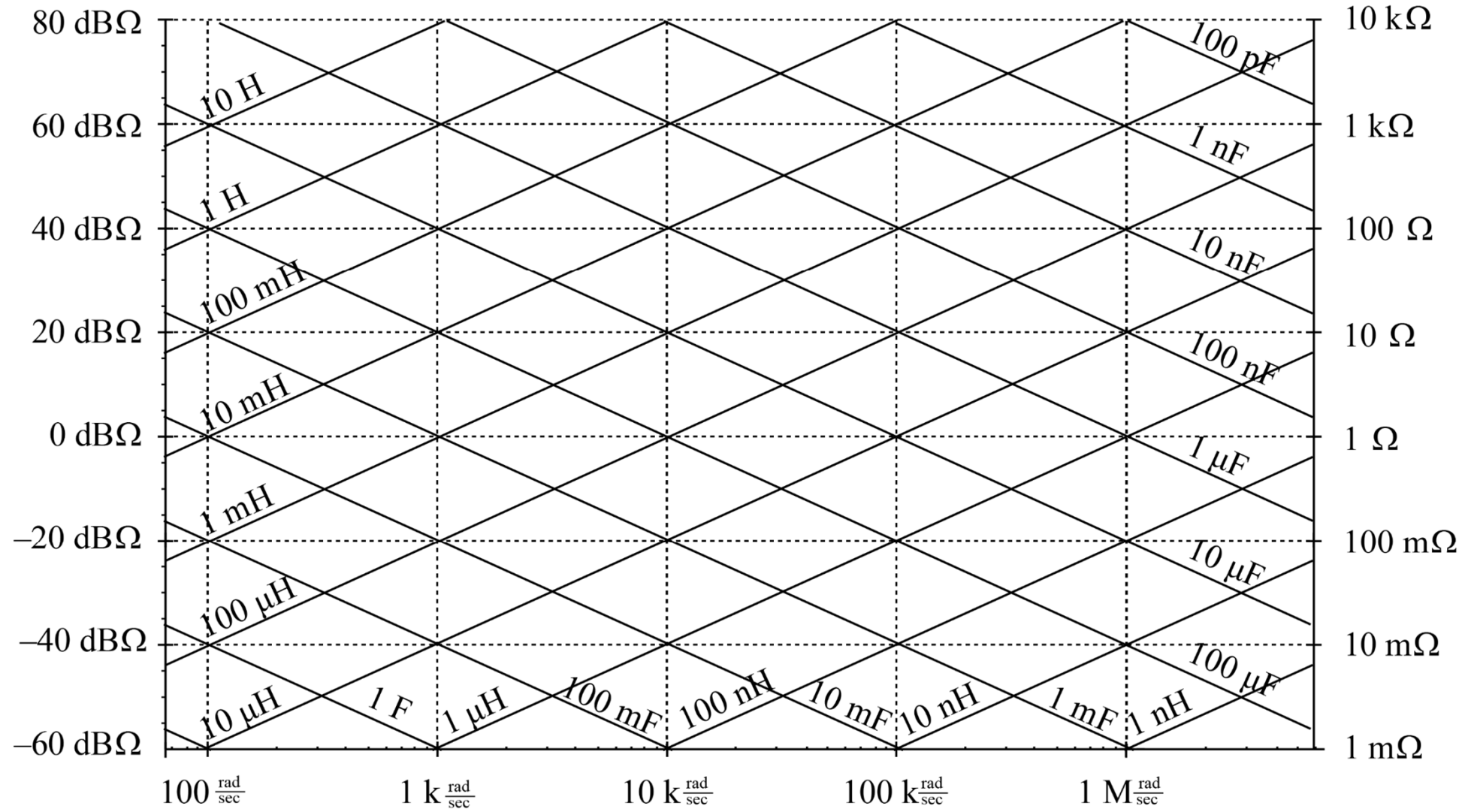
$$\rightarrow \|G_{g0}\|_{\text{dB}} = 3.5 \text{ dBV}$$

Control-to-output Transfer Function



Graphical Construction

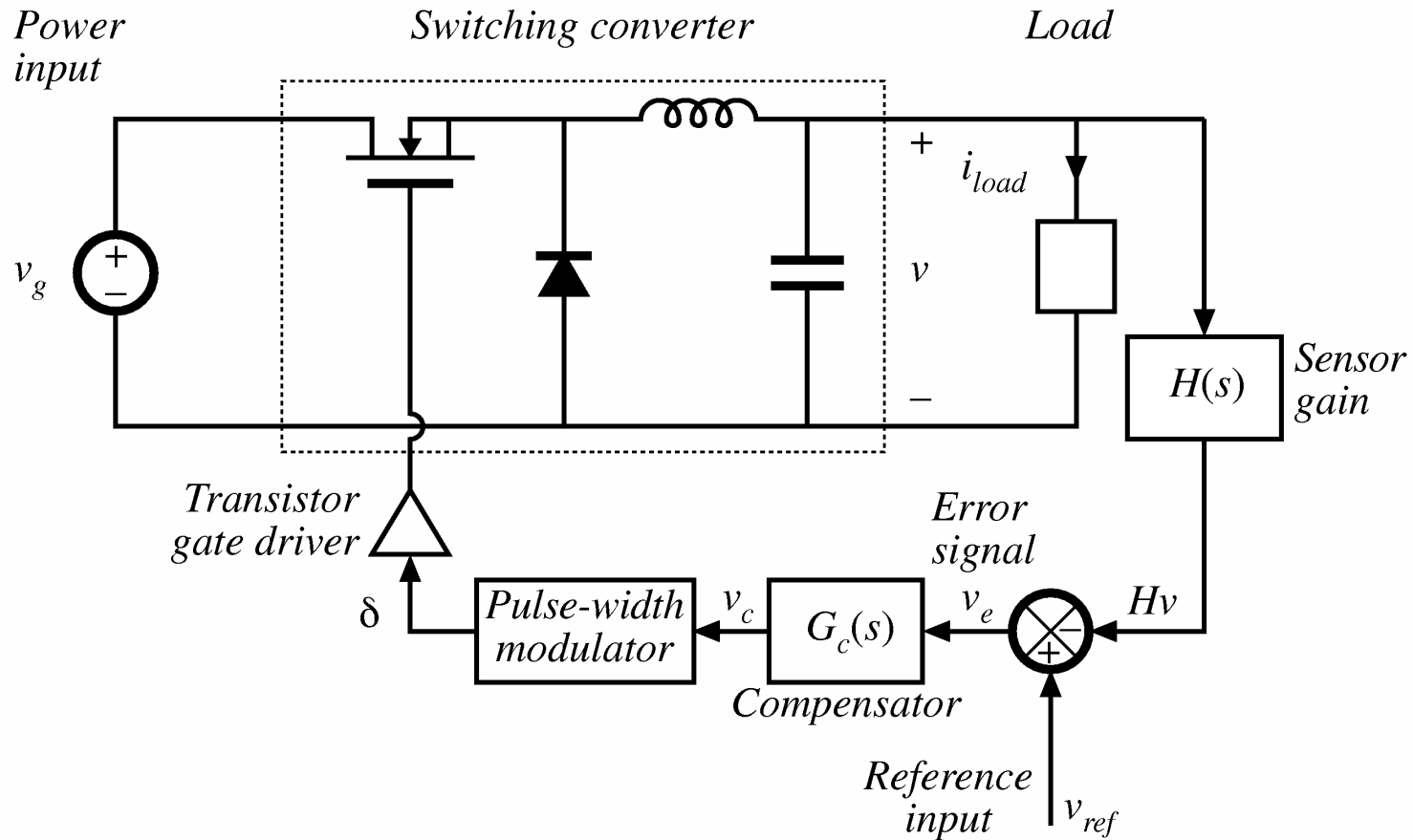
Reactance Paper



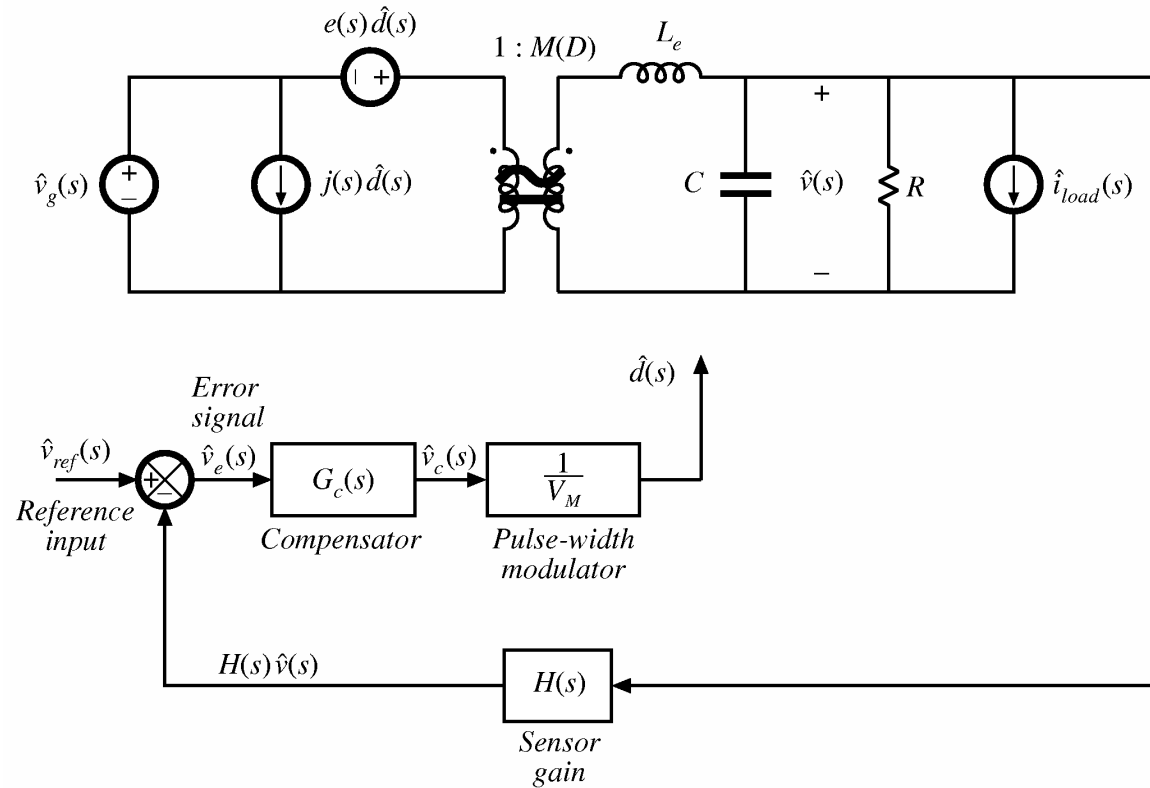
Chapter 9

CONTROLLER DESIGN

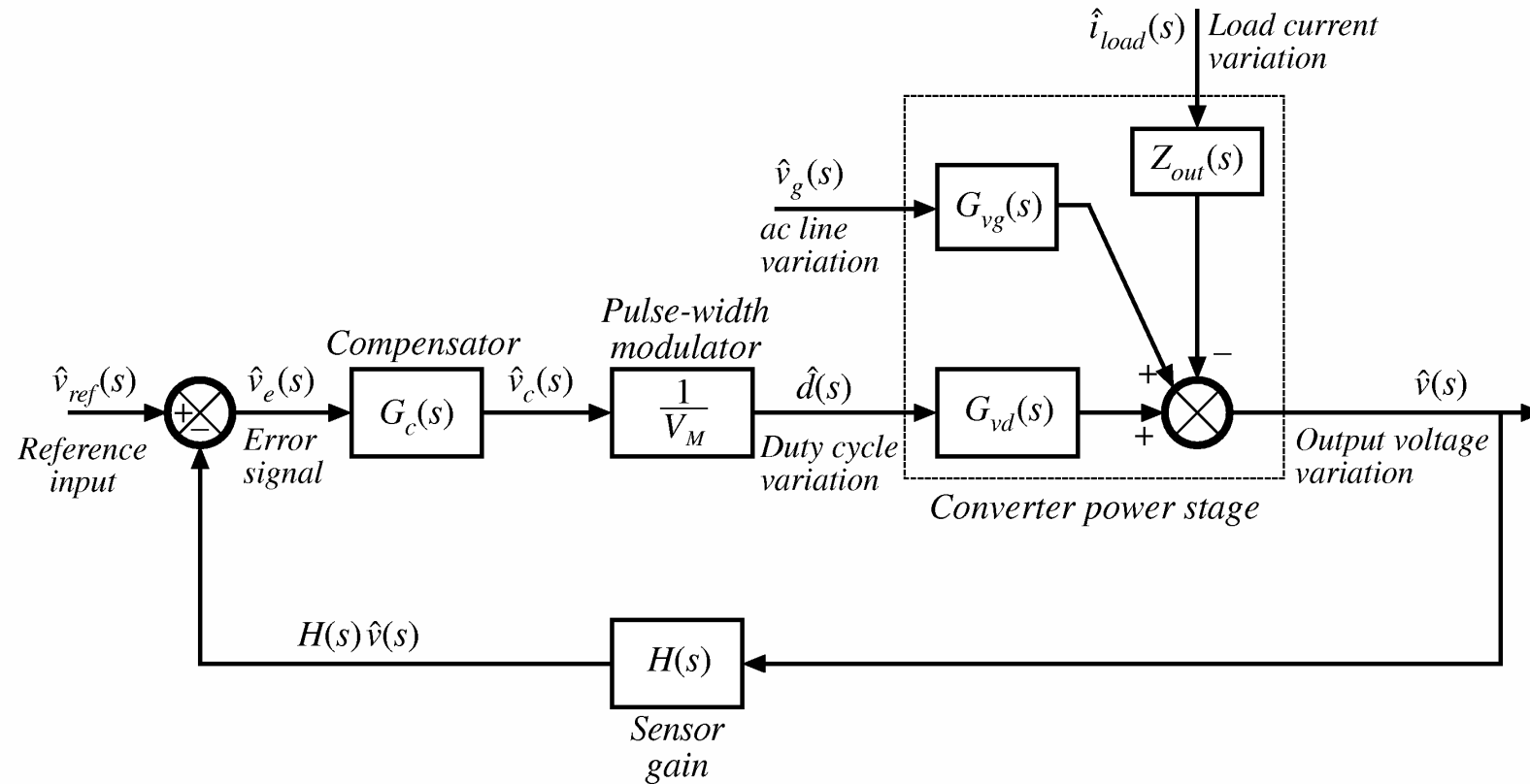
Closed-Loop Regulation



Small-Signal Closed-Loop Model



Block Diagram



Closed-Loop Transfer Functions