



Motor and Battery Characterization

ECE 482 Lecture 2
January 13, 2015



Lab 1



10Ah Li-ion ~26V
battery



500W Hub PM Motor



Introduction to Battery Modeling



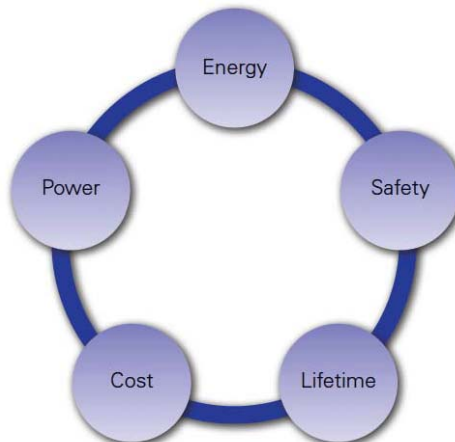
Battery Performance Metrics

Energy

- Available energy storage between charging cycles
- A*hr rating
- Specific energy, Wh/kg, energy density Wh/L

Power

- Instantaneous power available
- "C" rating: peak discharge current
- Specific power, W/kg, W/L



Cost

- Initial investment
- Total energy cost over life of battery

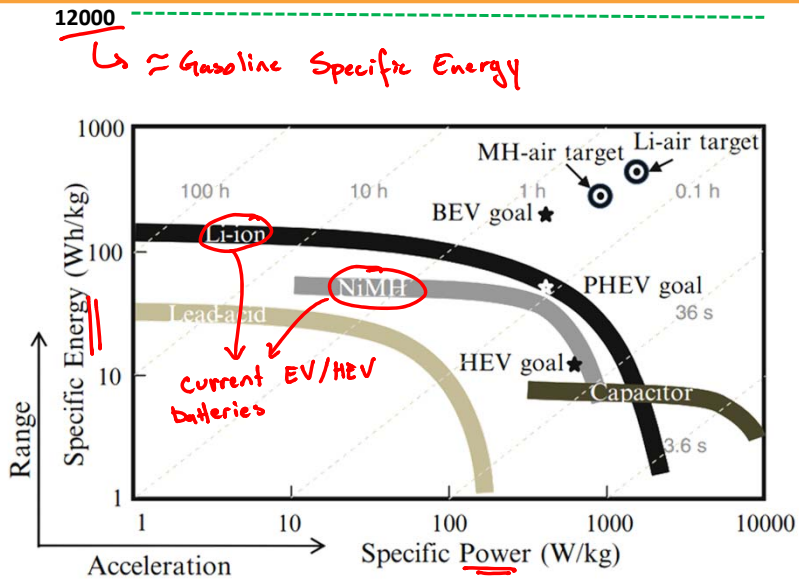
Safety

- Hazardous chemical content
- Outgassing
- Risk of fire from damage or heating

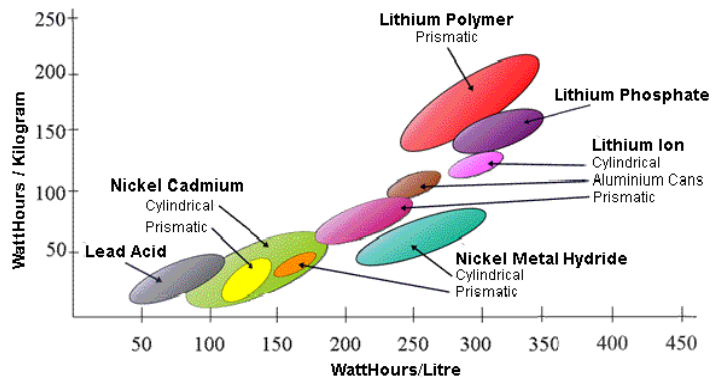
Lifetime

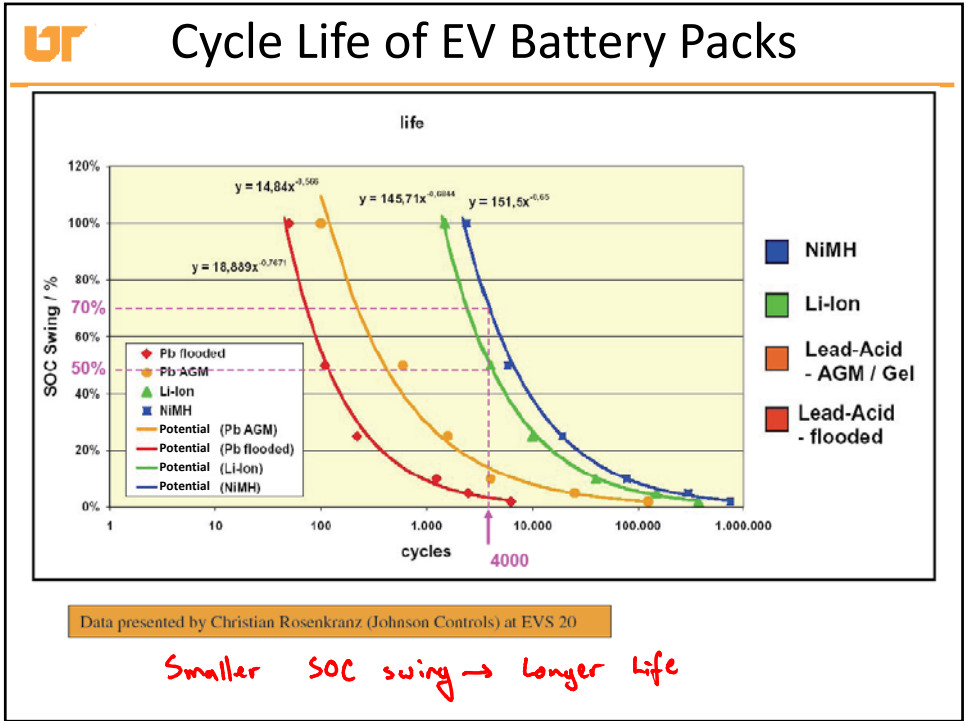
- Number of charge / discharge cycles to 80% capacity
- Dependence on % discharge and peak currents

Energy and Power Density of Storage



Energy Density and Specific Energy





Li-ion Advantages and Disadvantages

Advantages

- Higher energy density, 150-200 Wh/kg, 250-500 Wh/l
- High power density, can be optimized for energy or power
- Higher voltage, approx. 3.2 V to 3.8 V
- Low self-discharge rate, retain charge for months
- No liquid electrolyte
- Relatively long cycle life (1,000-3,000 deep cycles)

Disadvantages

- More complex to manufacture, more expensive (0.5-1 \$/Wh)
- Safety concerns: require circuitry to protect against overcharging or over-discharging

Lithium Ion Cathode Chemistry Comparison (Used With Carbon Anodes)				
Cathode Material	Typical Voltage (V)	Energy Density		Thermal Stability
		Gravimetric (Wh/Kg)	Volumetric (Wh/L)	
Cobalt Oxide	3.7	195	560	Poor
Nickel Cobalt Aluminum Oxide (NCA)	3.6	220	600	Fair
Nickel Cobalt Manganese Oxide (NCM)	3.6	205	580	Fair
Manganese Oxide (Spinel)	3.9	150	420	Good
Iron Phosphate (LFP)	3.2	90-130	333	Very Good



Example EV Batteries



Cutaway battery of Nissan Leaf electric vehicle. The Leaf includes a 24kWh lithium-ion battery with a city driving range of 160km (100 miles). The battery fits under the floor of the car, weighs 272kg (600lb) and is estimated to cost \$15,600 (2010).



Tesla Model S frame-integrated battery. The Model S includes a 60-85kWh lithium-ion battery with a city driving range of 480km (300miles). The battery weighs 544kg (1200lb) and is estimated to cost \$24-34,000.



Toyota Prius HEV Battery. The 2004 Prius included a 1.3 kWh NiMH battery consisting of 168 cells and with a \$3K retail replacement cost



Cell Equivalent-Circuit Models

Objective:

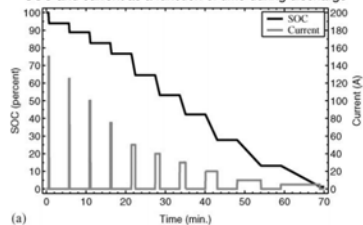
- Dynamic circuit model capable of predicting cell voltage in response to charge/discharge current, temperature

Further key techniques discussed in [Plett 2004-Part 2] and [Plett 2004-Part 3]

- Model parameters found using least-square estimation or Kalman filter techniques based on experimental test data
- Run-time estimation of state of charge (SOC)

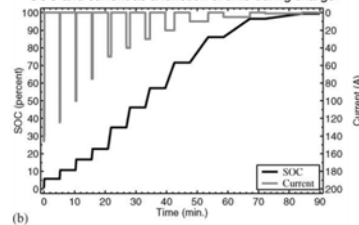
Approach: Pulsed current tests

SOC and current as a function of time during discharge



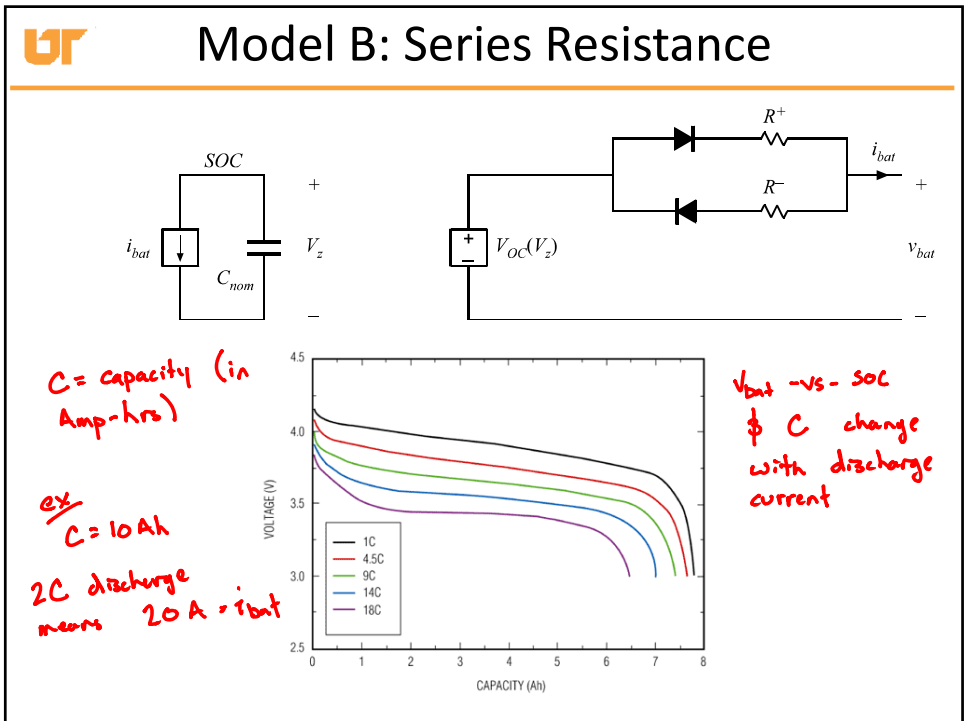
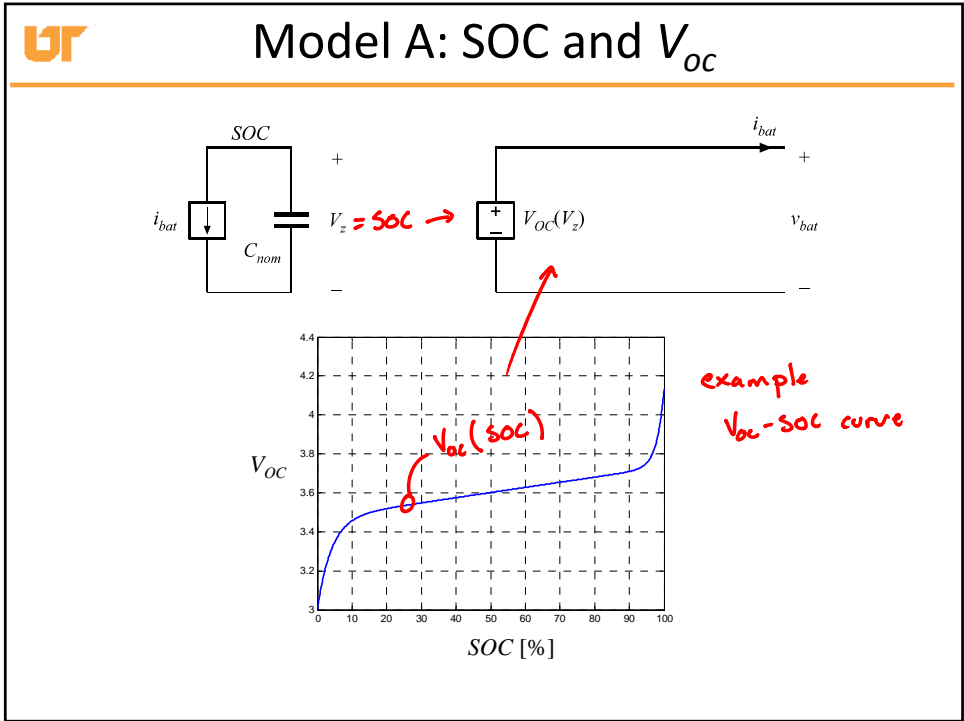
(a)

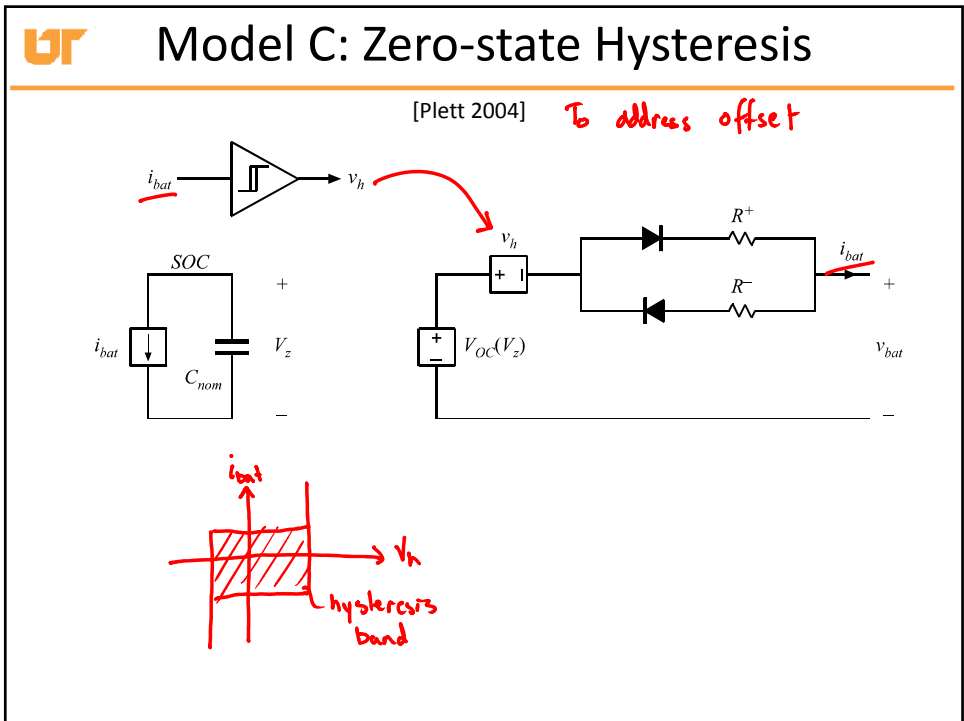
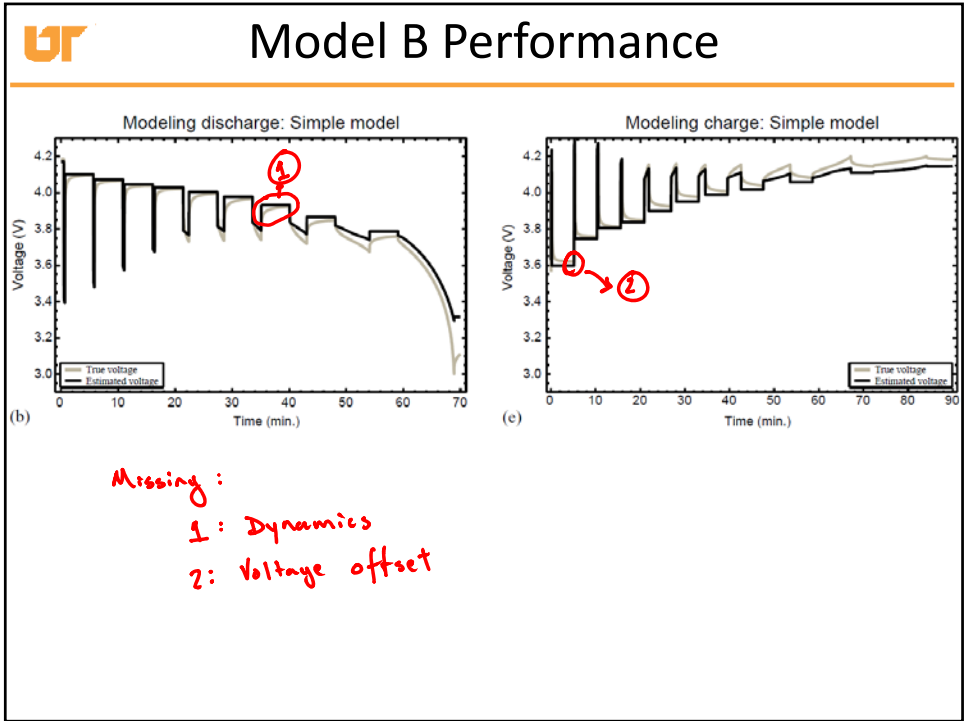
SOC and current as a function of time during charge

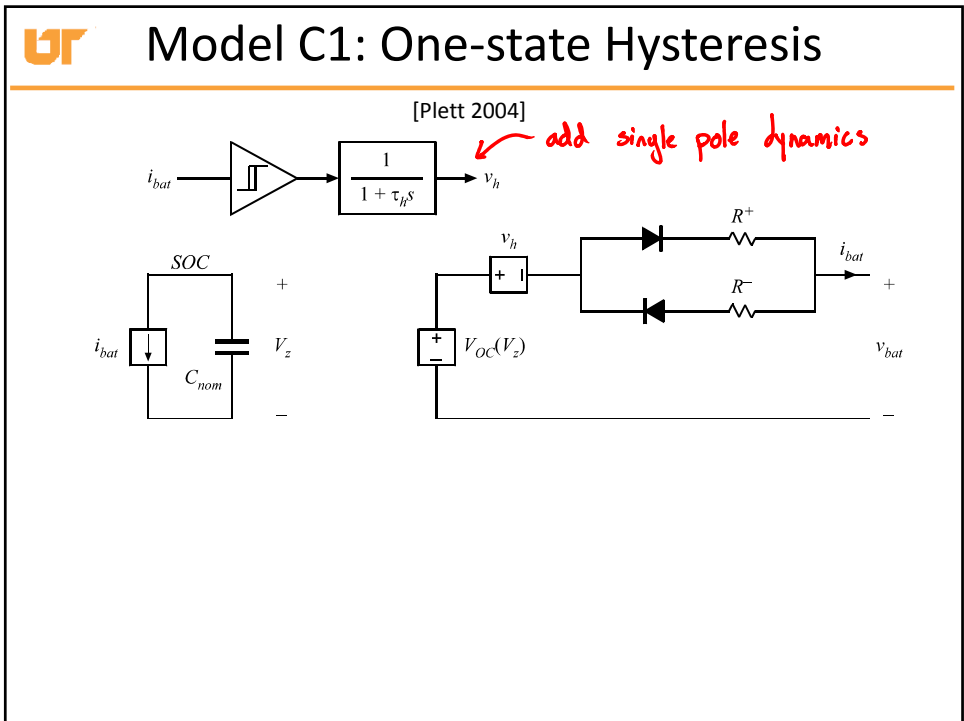
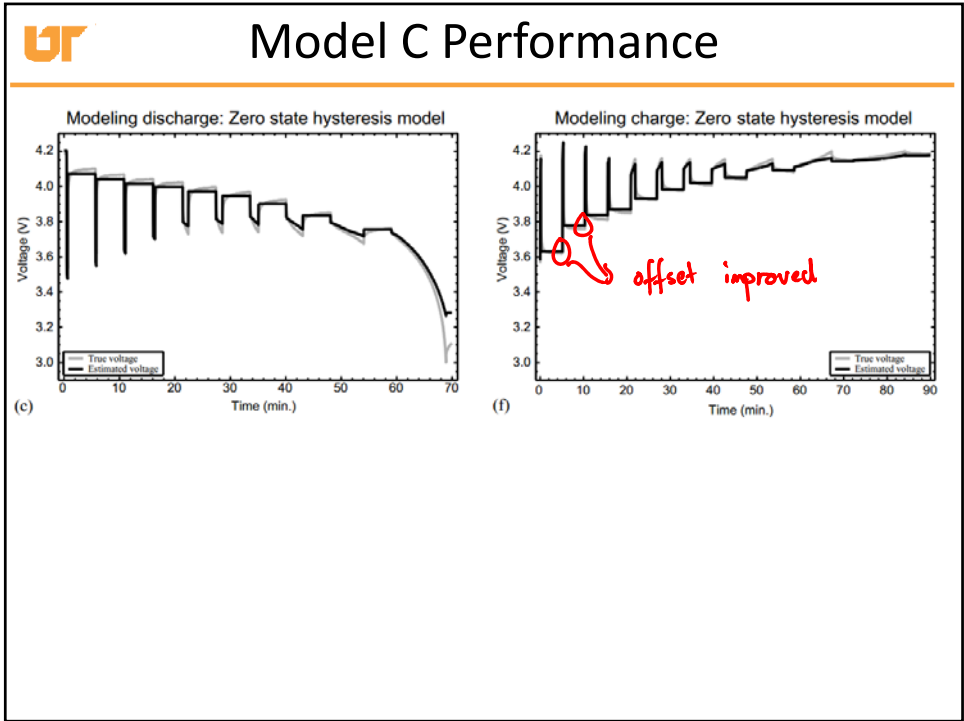


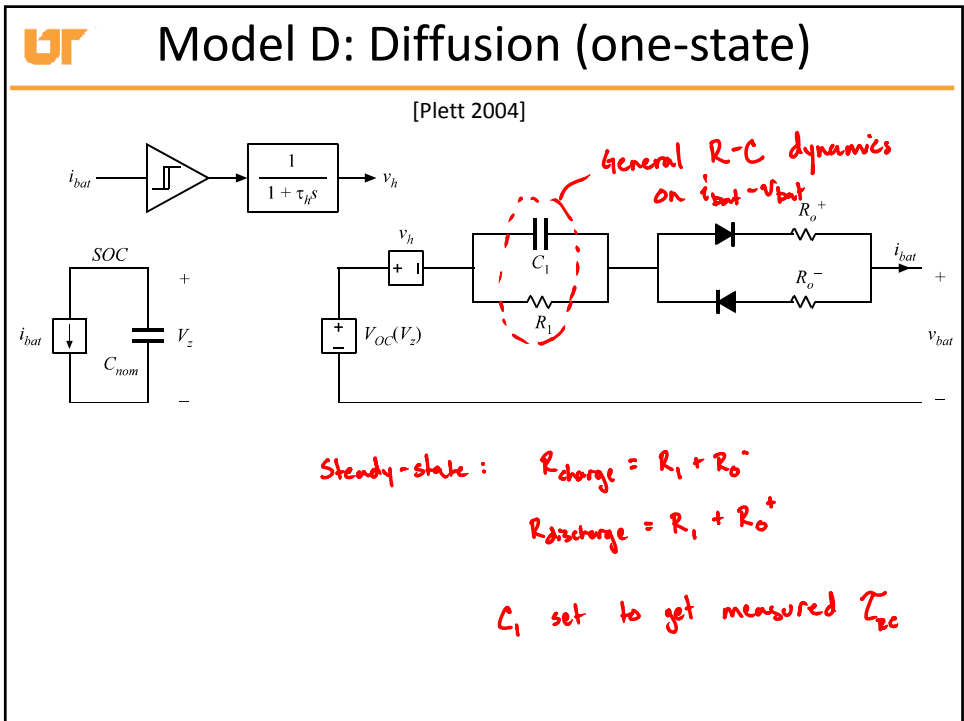
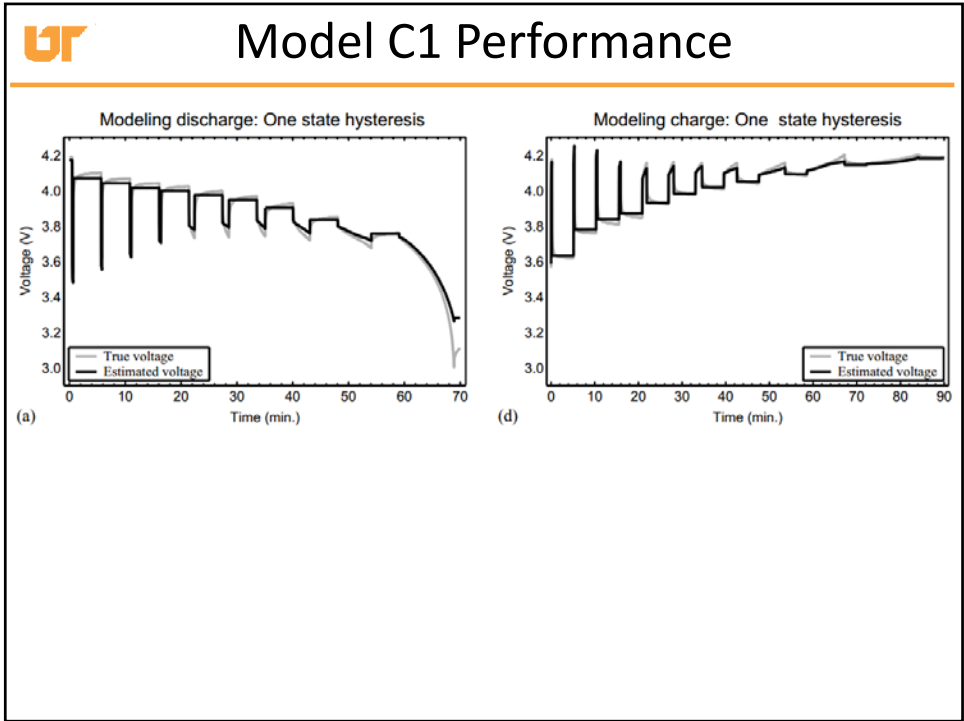
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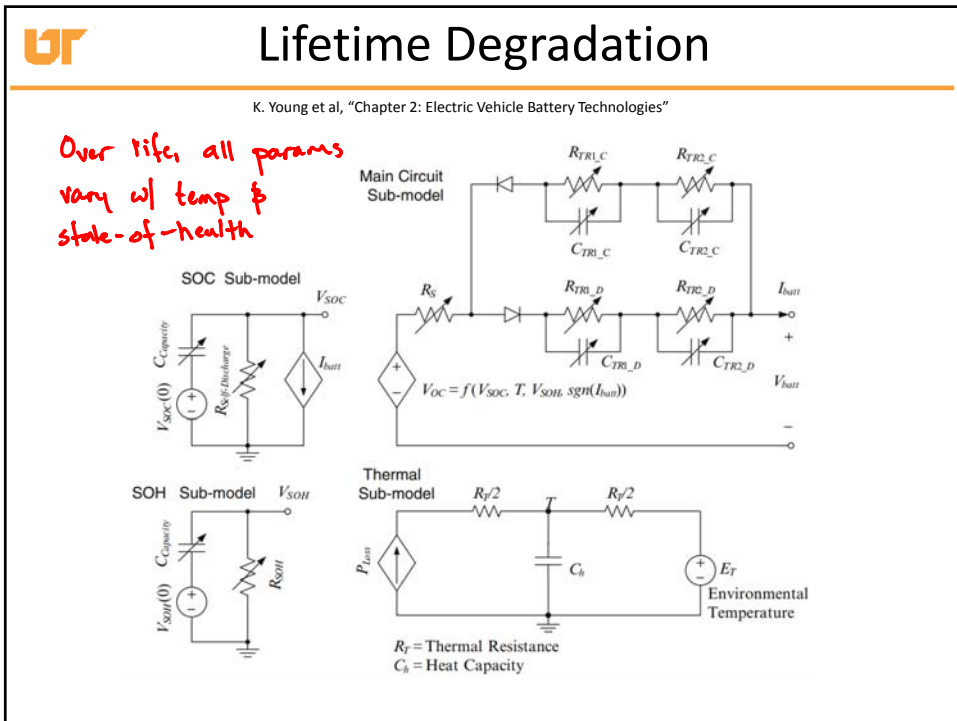
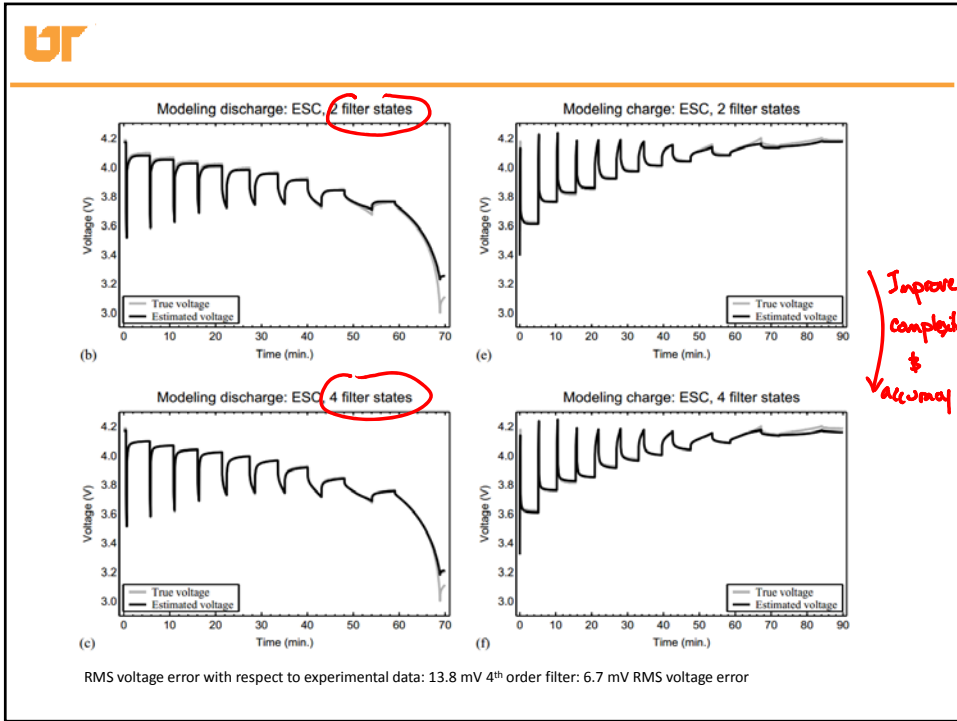
[Plett 2004-2] G. Plett, "Extended Kalman Filtering for Battery Management Systems of LiPB-Based HEV Battery Packs—Part 2: Modeling and Identification," *Journal of Power Sources*, Vol. 134, No. 2, August 2004, pp. 262–76.









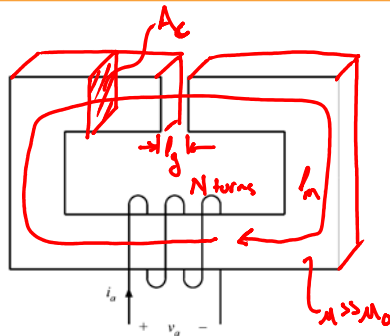




PM Motor Operation



Magnetic Circuit



Assume:

- B & \mathcal{F} are constant throughout the core
- Magnetic flux is contained entirely within the core (except at air gap)
- No fringing at air gap
- Material is linear, unsaturated; $B = \mu H$

Apply:

$$\text{Ampere's law: } N i_a = \oint_{\mathcal{F}} H \cdot dl = \frac{B}{\mu} (l_m - l_g) + \frac{B}{\mu_0} l_g$$

$$\text{Faraday's Law: } v_a = N \frac{d\Phi}{dt} = N \frac{d}{dt} (B A_c) = N A_c \frac{dB}{dt}$$

$$\text{Combine: } v_a = N A_c \frac{d}{dt} \left(\frac{N i_a}{\frac{l_m - l_g}{\mu} + \frac{l_g}{\mu_0}} \right) = \frac{N^2 A_c}{\frac{l_m - l_g}{\mu} + \frac{l_g}{\mu_0}} \frac{di_a}{dt}$$

$v_a = L \frac{di_a}{dt}$

UF Equivalent Circuit

$R = \rho \frac{N \cdot M L}{A_w}$
 $L \approx \frac{\mu_0 N^2 A_c}{l_g}$
 if $\mu \gg \mu_0$

UF Single Phase Motor (Simplified)

Assume magnet has flux Φ_m & $\mu \gg \mu_0$
 L & R still present, but by Faraday's law to find additional voltage due to permanent magnet's flux
 $v_{a,extra} = \frac{d}{dt} (N \Phi_m f(\theta_r))$
 some function describing how much flux couples into core.
 As an example (not inherently true) $f(\theta_r) = \sin(\theta_r)$
 define "flux linkage" $\lambda_m = N \Phi_m$, units of $\frac{V \cdot sec}{rad}$



Electromechanical Conversion

The power going into the winding is

$$P_a = i_a v_a = i_a^2 R_w + i_a L \frac{di_a}{dt} + i_a \lambda_m \omega_r \cos(\theta_r)$$

\uparrow \uparrow \uparrow
 Winding DC AC-only reactive power transferred
 copper loss current to mechanical

In mechanical domain, instantaneous power of the rotor is

$$P_m = \omega_r \tau_r$$

\uparrow \uparrow
 speed Torque

Assuming 100% conversion efficiency.

$$P_m = P_e = i_a \lambda_m \omega_r \cos(\theta_r) = \omega_r \tau_r$$

$$\tau_r = i_a \lambda_m \cos(\theta_r)$$

Problem: when
 $\theta_r \rightarrow \frac{\pi}{2}, \frac{3\pi}{2}$,
 $\tau_r \rightarrow 0!$



Winding Voltage Equation

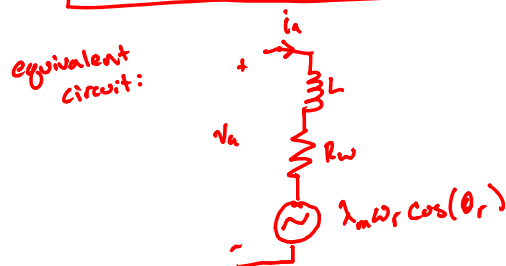
$$v_{a,extra} = \lambda_m \frac{d}{dt} \sin(\theta_r) = \lambda_m \cos(\theta_r) \frac{d}{dt} \theta_r$$

if spinning at a constant rate, $\frac{d}{dt} \theta_r = \omega_r$

$$v_{a,extra} = \lambda_m \omega_r \cos(\theta_r)$$

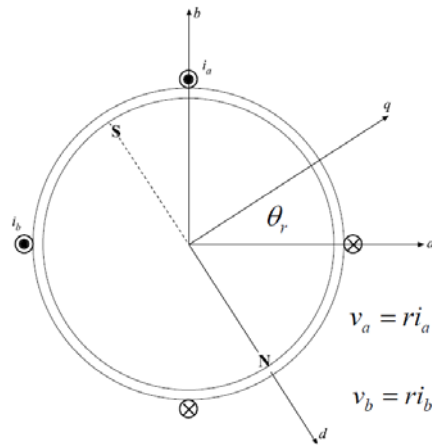
Total equation is then

$$v_a = R_w i_a + L \frac{di_a}{dt} + \lambda_m \omega_r \cos(\theta_r)$$





2-Pole, 2-Phase PMSM



Two-pole, two-phase PMSM
terminal characteristics in
stator reference frame

$$\lambda_a(\theta_r) = \lambda_M \sin(\theta_r)$$

$$\lambda_b(\theta_r) = -\lambda_M \cos(\theta_r)$$

Same as
before

$$v_a = ri_a + \frac{d\lambda_a}{dt} = ri_a + L \frac{di_a}{dt} + \lambda_M \omega_r \cos(\theta_r)$$

$$v_b = ri_b + \frac{d\lambda_b}{dt} = ri_b + L \frac{di_b}{dt} + \lambda_M \omega_r \sin(\theta_r)$$

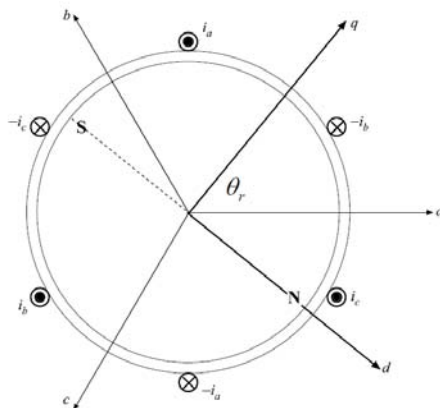
$$T_m = \lambda_M (i_a \cos(\theta_r) + i_b \sin(\theta_r))$$

e.g. select $i_a = I \cos(\theta_r)$ $i_b = I \sin(\theta_r)$

$$T_m = \lambda_M I (\cos^2 \theta_r + \sin^2 \theta_r) = \underline{\underline{\lambda_M I}} \rightarrow \text{constant!}$$



3-Phase, 2-Pole PMSM



$$\lambda_a(\theta_r) = \lambda_m \sin(\theta_r)$$

$$\lambda_b(\theta_r) = \lambda_m \sin\left(\theta_r - \frac{2\pi}{3}\right)$$

$$\lambda_c(\theta_r) = \lambda_m \sin\left(\theta_r - \frac{4\pi}{3}\right)$$

$$\begin{cases} i_a = I \cos(\theta_r) \\ i_b = I \cos\left(\theta_r - \frac{2\pi}{3}\right) \\ i_c = I \cos\left(\theta_r - \frac{4\pi}{3}\right) \end{cases}$$

$$T_m = i_a \lambda_m \omega_r \cos(\theta_r) + i_b \lambda_m \omega_r \cos\left(\theta_r - \frac{2\pi}{3}\right) + i_c \lambda_m \omega_r \cos\left(\theta_r - \frac{4\pi}{3}\right)$$

$$= \frac{3}{2} \lambda_m I$$

