

Global Illumination

– The Game of Light Transport

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Looking Back

- Ray-tracing and radiosity both compute global illumination
- Is there a more general methodology?
- It's a game of light transport.

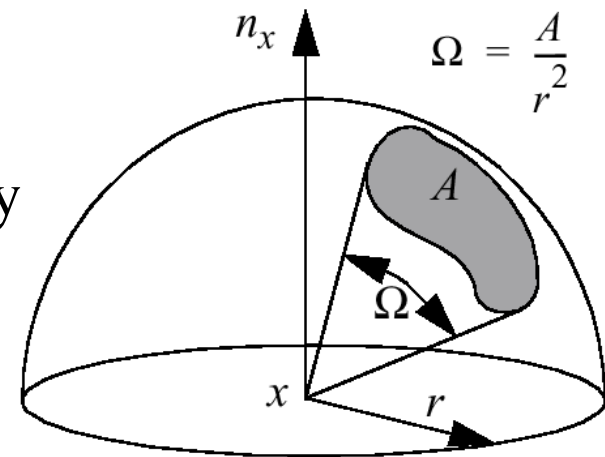
Radiance

- Radiance (L): for a point in 3D space, L is the light flux per unit projected area per unit solid angle, measured in W/(sr·m²)
 - sr – steradian: unit of solid angle
 - A cone that covers r² area on the radius-r hemisphere
 - A total of 2π sr on a hemisphere Ω.
 - power density/solid angle
 - The fundamental radiometric quantity

$$P = \int_{\text{Area}} \int_{\text{Solid Angle}} L(x \rightarrow \Theta) \cdot \cos \theta \cdot d\omega_{\Theta} \cdot dA$$

$L(x \rightarrow \Theta)$: radiance leaving point x in direction Θ

$L(x \leftarrow \Theta)$: radiance arriving at point x from direction Θ



Irradiance and Radiosity

- Irradiance (E)
 - Integration of incoming radiance over all directions, measured in W/m^2
 - Incident radiant power (Watt) on per unit projected surface area
- Radiance distribution is generally discontinuous, irradiance distribution is generally continuous, due to the integration
 - ‘shooting’, distribute radiance from a surface
 - ‘gathering’, integrating irradiance and accumulate light flux on surface
- Radiosity (B) is
 - Exitant radiant power (Watt) on per unit projected surface area, measured in W/m^2 as well

Relationships among the Radiometric Units

Flux: $\Phi(x \rightarrow \Theta)$

$$\text{Irradiance: } E(x \leftarrow \Theta) = \frac{d\Phi(x \leftarrow \Theta)}{dA^\perp}$$

$$\text{Radiant exitance or radiosity: } B(x \rightarrow \Theta) = \frac{d\Phi(x \rightarrow \Theta)}{dA^\perp}$$

$$\text{Radiance: } L(x \rightarrow \Theta) = \frac{d^2\Phi(x \rightarrow \Theta)}{d\omega dA^\perp} = \frac{d^2\Phi(x \rightarrow \Theta)}{d\omega dA \cos\theta}$$

$$\Phi = \int_A \int_\Omega L(x \rightarrow \Theta) \cos\theta d\omega_\Theta dA_x$$

$$E(x) = \int_\Omega L(x \leftarrow \Theta) \cos\theta d\omega_\Theta$$

$$B(x) = \int_\Omega L(x \rightarrow \Theta) \cos\theta d\omega_\Theta$$

Path Notation

- A non-mathematical way to categorize the behavior of global illumination algorithm
 - Diffuse to diffuse transfer
 - Specular to diffuse transfer
 - Diffuse to specular transfer
 - Specular to specular transfer
- Heckbert's string notation (1990): as light ray travels from source (L) to eye (E):
 - LDDE, LDSE+LDDE, LSSE+LDSE, LSDE, LSSDE

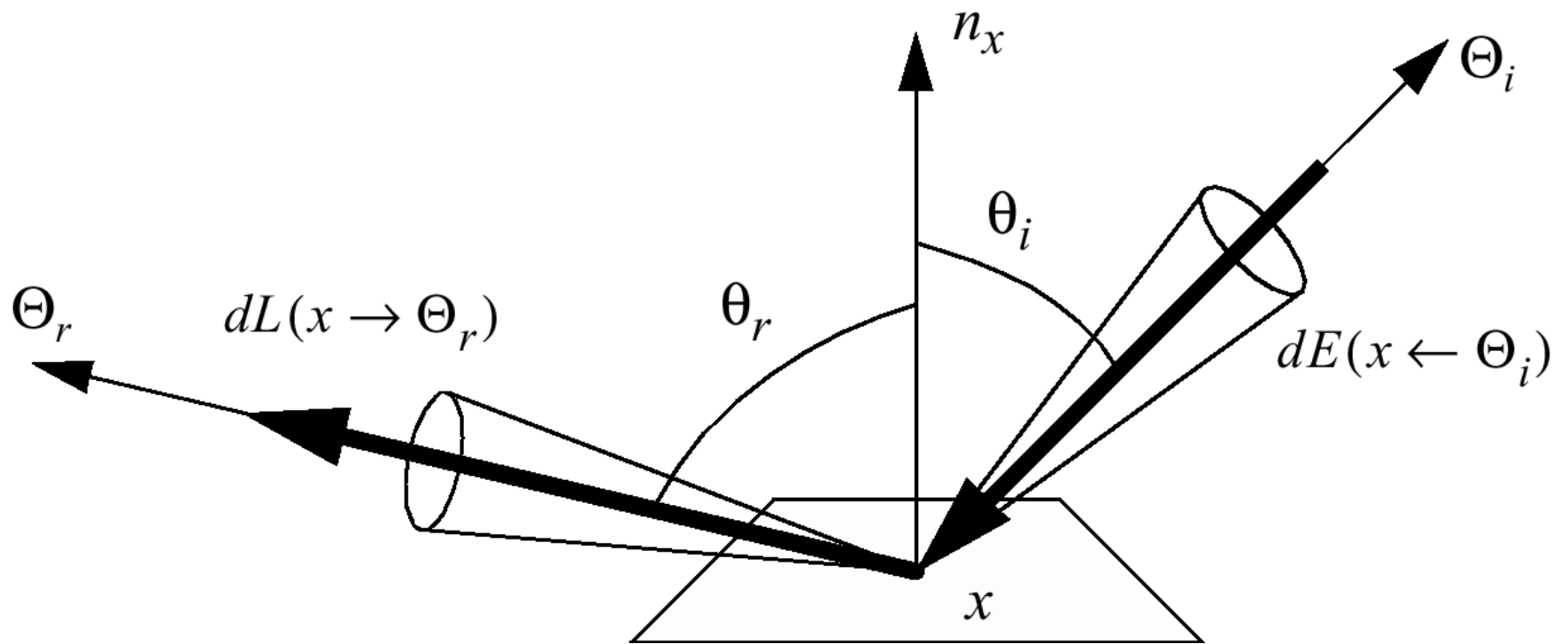
BRDF

- Materials interact with light in different ways, and different materials have different appearances given the same lighting conditions.
- The reflectance properties of a surface are described by a reflectance function, which models the interaction of light reflecting at a surface.
- The bi-directional reflectance distribution function (BRDF) is the most general expression of reflectance of a material
- The BRDF is defined as the ratio between differential radiance reflected in an exitant direction, and incident irradiance through a differential solid angle

$$f_r(x, \Theta_i \rightarrow \Theta_r) = \frac{dL(x \rightarrow \Theta_r)}{dE(x \leftarrow \Theta_i)} = \frac{dL(x \rightarrow \Theta_r)}{L(x \leftarrow \Theta_i) \cos \theta_i d\omega_{\Theta_i}}$$

BRDF

- The geometry of BRDF



BRDF properties

- Positive, and variable in regard to wave-length
- Reciprocity: the value of the BRDF will remain unchanged if the incident and exitant directions are interchanged.

$$f_r(x, \Theta_i \rightarrow \Theta_r) = f_r(x, \Theta_r \rightarrow \Theta_i)$$

- Generally, the BRDF is anisotropic.
- BRDF behaves as a linear function with respect to all incident directions.

$$L(x \rightarrow \Theta_r) = \int_{\Omega_x} f_r(x, \Theta \leftrightarrow \Theta_r) L(x \leftarrow \Theta) \cos(n_x, \Theta) d\omega_{\Theta}$$

BRDF Examples

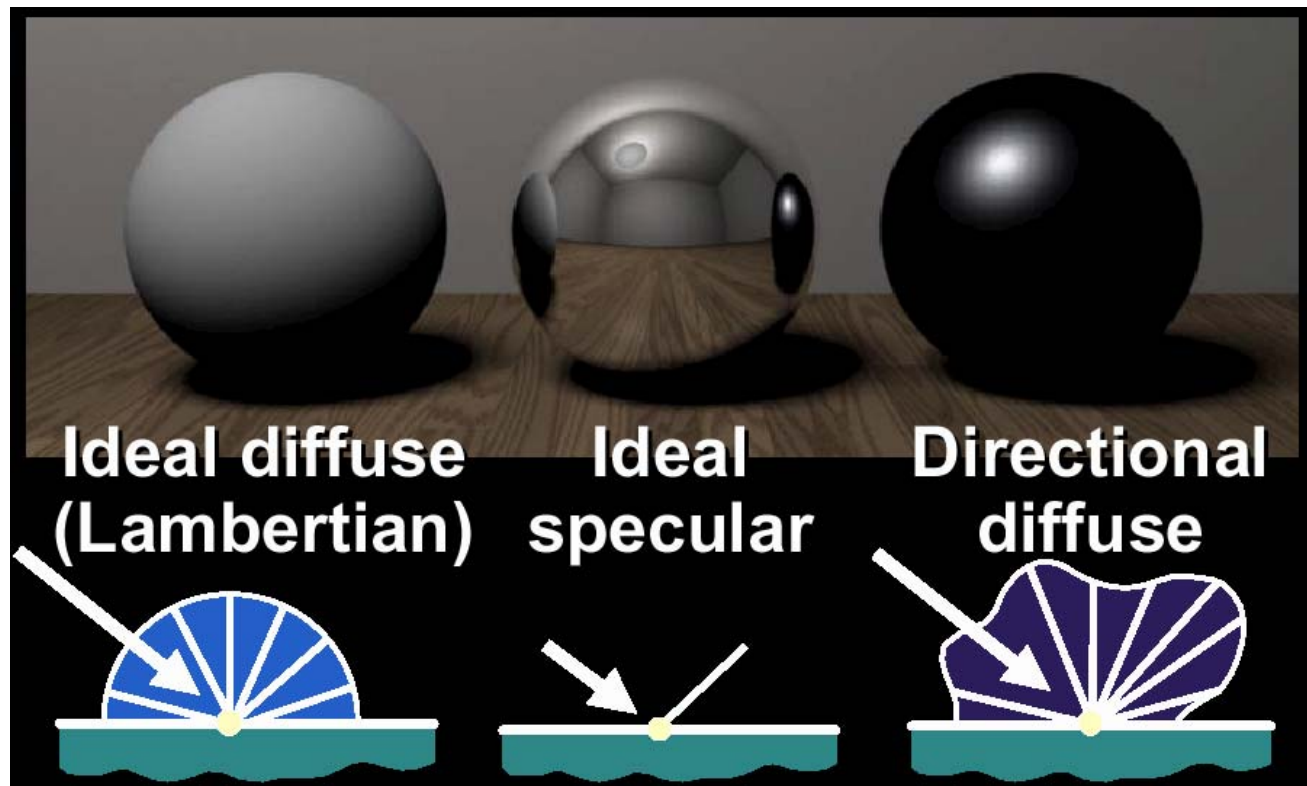
- Diffuse surface (Lambertian)

$$f_r(x, \Theta_i \rightarrow \Theta_r) = \frac{\rho_d}{\pi} \quad \rho_d \text{ varies from 0 to 1}$$

- Perfect specular surface
 - BRDF is non-zero in only one exitant direction
- Glossy surfaces (non ideally specular)
 - Difficult to model analytically
- Transparent surfaces
 - Need to model the full sphere (hemi-sphere is not enough)
 - BRDF is not usually enough, need BSSRDF (bi-directional sub-surface scattering reflectance distribution function)
 - The transparent side can be diffuse, specular or glossy

Reflectance

- 3 forms



The Rendering Equation

- Proposed by Jim Kajiya in his SIGGRAPH'1986 paper
 - Light transport equation in a general form
 - Describes not only diffuse surfaces, but also ones with complex reflective properties
 - Goal of computer graphics: solution of the rendering equation!
 - Looks simple and natural, but really is too complex to be solved exactly; various techniques to find approximate solutions are used

The Rendering Equation

- $I(x, x')$ = intensity passing from x' to x
- $g(x, x')$ = geometry term (1, or $1/r^2$, if x visible from x' , 0 otherwise)
- $\epsilon(x, x')$ = intensity emitted from x' in the direction of x
- $\rho(x, x', x'')$ = scattering term for x' (fraction of intensity arriving at x' from the direction of x'' scattered in the direction of x)
- S = union of all surfaces

$$I(x, x') = g(x, x') [\epsilon(x, x') + \int_S \rho(x, x', x'') I(x', x'') dx'']$$

Linear Operator

- Define a linear operator, M .

$$M(I)(x, x') = \int_S \rho(x, x', x'') I(x', x'')$$

- The rendering equation:

$$I = g\epsilon + gM(I)$$

- How to solve it?

Neumann Series Solution

- Start with an initial guess I_0
- Compute a better solution

$$I_1 = g\epsilon + gM(I_0)$$

- Compute an even better solution

$$I_2 = g\epsilon + gM(I_1) = g\epsilon + gMg\epsilon + gMgM(I_0)$$

- Then, $I = g\epsilon + gMg\epsilon + gMgMg\epsilon + gMgMgMg\epsilon + \dots$
- In practice one needs to truncate it somewhere

Examples

- No shading/illumination, just draw surfaces as emitting themselves:

$$I = g\epsilon$$

- Direct illumination, no shadows:

$$I = g\epsilon + gM\epsilon$$

- Direct illumination with shadows:

$$I = g\epsilon + gMg\epsilon$$

Implications

- How successful is a global illumination algorithm?
 - The first term is simple, just visibility
 - How an algorithm handles the remaining terms and the recursion?
 - How does it handle the combinations of diffuse and specular reflectivity
- The **rendering equation** is a view-independent statement of the problem
- How are the radiosity algorithm and the ray-tracing algorithm?

Monte Carlo Techniques in Global Illumination

- Monte Carlo is a general class of estimation method based on statistical sampling
 - The most famous example: to estimate π
- Monte Carlo techniques are commonly used to solve integrals with no analytical or numerical solution
 - The rendering equation has one such integral

Basic Monte Carlo Integration

- Suppose we want to numerically integrate a function over an integration domain D (of dimension d), i.e., we want to compute the value of the integral I :

$$I = \int_D f(x) dx$$

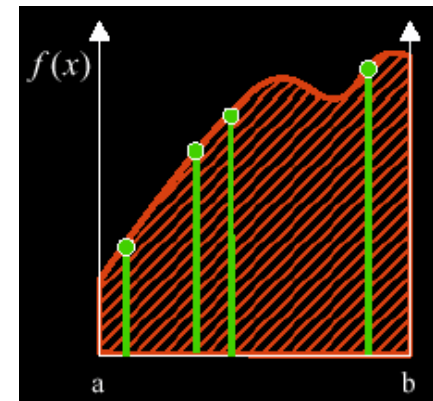
$$D = [\alpha_1 \dots \beta_1] \times [\alpha_2 \dots \beta_2] \times \dots \times [\alpha_d \dots \beta_d] \quad (\alpha_i, \beta_i \in \mathfrak{R})$$

- Common deterministic approach: construct a number of sample points, and use the function values at those points to compute an estimate of I .
- Monte Carlo integration basically uses the same approach, but uses a stochastic process to generate the sample points. And would like to generate N sample points **distributed uniformly over D** .

Basic Monte Carlo Integration

- The mean of the evaluated function values at each randomly generated sample point multiplied by the area of the integration domain, provides an unbiased estimator for I:

$$\langle I \rangle = \left(\frac{1}{N} \sum_{i=1}^N f(x_i) \right) \cdot \left(\prod_{i=1}^d (\beta_i - \alpha_i) \right)$$



- Monte Carlo methods provides an un-biased estimator
- The variance reduces as N increases
- Usually, given the same N, deterministic approach produces less error than Monte Carlo methods

When to Use Monte Carlo?

- High dimension integration – the sample points needed in deterministic approach exponential increase
- Complex integrand: practically can't tell the error bound for deterministic approaches
- Monte Carlo is always un-biased, and for rendering purpose, it converts errors into noise!!

Two Types of Monte Carlo

- Monte Carlo integration methods can roughly be subdivided in two categories:
 - those that have no information about the function to be integrated: ‘blind Monte Carlo’
 - those that do have some kind of information available about the function: ‘informed Monte Carlo’
- Intuitively, one expects that informed Monte Carlo methods to produce more accurate results as opposed to blind Monte Carlo methods.
- The basic Monte Carlo integration is a blind Monte Carlo method

Importance Sampling

- An informed Monte Carlo
- Importance sampling uses a non-uniform probability function, $pdf(x)$, for generating samples.
 - By choosing the probability function $pdf(x)$ wisely on the basis of some knowledge of the function to be integrated, we can often reduce the variance
 - Can prove: if can get the $pdf(x)$ to match the exact shape of the function to be integrated, $f(x)$, the variance of the integration estimation is 0.
- Practically, can use a sample table to generate a ‘good’ pdf.
- Intuitively, want to send more rays into the more detailed areas in space

Stratified Sampling

- Importance sampling (probability) using a limited number of samples, which is the case for graphics rendering, does not have a guarantee.
- Stratified sampling address this further: the basic idea of stratified sampling is to split up the integration domain in m disjunct subdomains (also called *strata*), and evaluate the integral in each of the subdomains separately with one or more samples.
- More precisely:

$$\int_0^1 f(x) dx = \int_0^{\alpha_1} f(x) dx + \int_{\alpha_1}^{\alpha_2} f(x) dx + \dots + \int_{\alpha_{m-2}}^{\alpha_{m-1}} f(x) dx + \int_{\alpha_{m-1}}^1 f(x) dx$$

More On Ray-Tracing

- Already discussed recursive ray-tracing!
- Improvements to ray-tracing!
 - Area sampling variations to address aliasing
 - Cone tracing (only talk about this)
 - Beam tracing
 - Pencil tracing
- Distributed ray-tracing!

Cone Tracing (1984)

- Generalize linear rays into cones
- One cone is fired from eye into each pixel
 - Have a wide angle to encompass the pixel
- The cone is intersected with objects in its path
- Reflection and refraction are modeled as spherical mirrors and lenses
 - Use the curvature of the object intersecting that cone
 - Broaden the reflected and refracted cones to simulate further scattering
- Shadow: proportion of the shadow cone that remains unblocked

Distributed Ray-Tracing

- Another way to address aliasing
- By Cook, Porter, and Carpenter in 1984.
- A stochastic approach to supersampling that trades objectionable aliasing artifacts for the less offensive artifacts of noise
- ‘Distributed’: rays are stochastically distributed to sample the quantities
- This method was covered during our recursive ray tracing lecture as extension to correct aliasing

Sampling Other Dimensions

- Other than stochastic spatial sampling for anti-aliasing, can sample in other dimensions
 - Motion blur (distribute rays in time)
 - Depth of field (distribute rays over the area of the camera lens)
 - Rough surfaces: blurred specular reflections and translucent refraction (distribute rays according to specular reflection and transmission functions)
 - Soft shadow: distribute shadow feeler rays over the solid angle span by the area light source
- In all cases, use stochastic sampling to perturb rays