

Particle Swarm Optimization

April 16, 2026



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Steven Dao
Laura Smith
Jonathan Tran

1. What is a possible downside of high exploitation?

2. What problem does Guaranteed Convergence PSO (GCPSO) attempt to solve?

3. Which field is PSO research currently mostly concentrated in?



Quiz



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Introductions

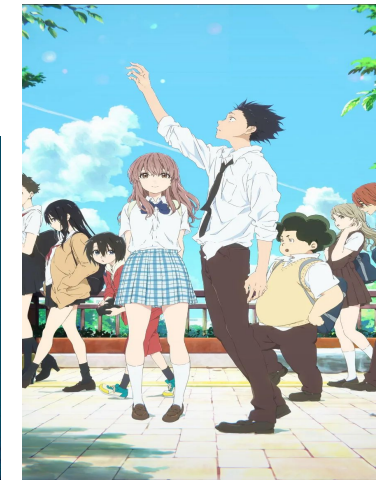
Jonathan Tran

- Born in Chattanooga, TN
 - Known as the Scenic City and Gig City
- Vietnamese and Chinese
- Attended Ooltewah High School
- BS in Computer Science at UTK 2025
 - Minor in Cybersecurity
- Completing 5-year MS/BS in CS



Jonathan Tran

- Hobbies
 - Cycling, going to conventions, sleeping...
 - Looking to get more into chess, cooking, learn an instrument
- Games
 - Persona 5, SSBU
- Anime
 - Mob Psycho 100, A Silent Voice
- Reading
 - Manga, Manhwa, Light Novels
- Music
 - Hoshimachi Suisei, Ado



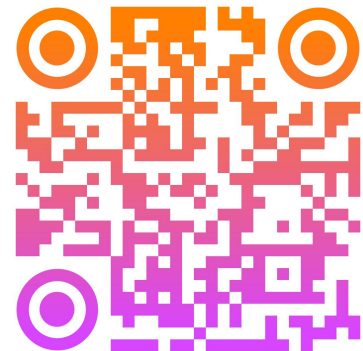
Steven Dao

- Born and raised in Nashville, TN
 - First graduating class of my high school
- Finishing up 5YR CS MS/BS @ UTK 2026
 - Cybersecurity Minor
- CS PhD coming UTK Fall 2026
 - Advisor: Michela Taufer w/ Global Computing Lab



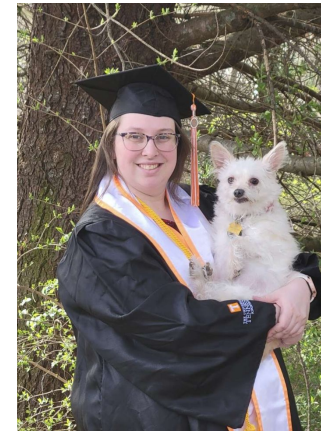
Steven Dao

- Vietnamese Name: Minhtrung
 - Loosely means “Truthful Soul”
- Plays Shamisen
 - Shamisen Knoxville
- I was born at 5:45PM and my brother at 5:45AM.
- Hobbies: Hacky Sack, Karaoke, Rhythm Games
 - I have karaoke equipment stored in my car right now.

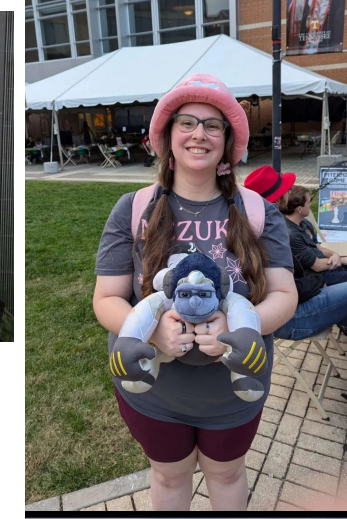


Laura Smith

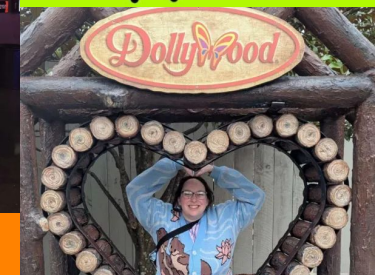
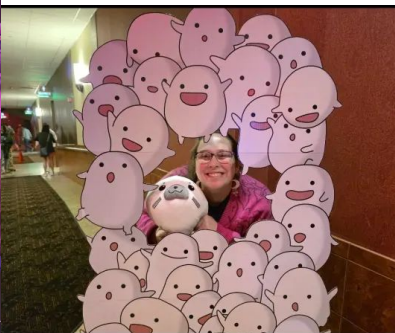
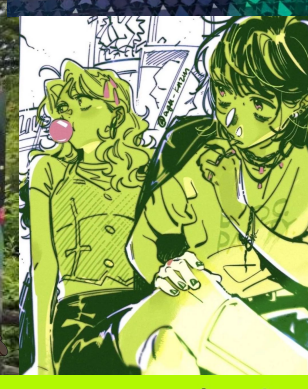
- Born in Dallas, Texas but moved to Colorado at a young age
- Did the IB program in high school at Douglas County High School
- Bachelors of science in Computer Science here at UTK 2025
 - minors in cybersecurity and machine learning and a concentration in scientific computing
- Current 5-year Master's student
 - August 2026
- Continuing to the PhD in the fall
 - Advisor: Dr. Rachael Burns in the STARI lab
- Research in Socially Assistive Robotics - Quad4Elders
- Helping out with the FujiView research as well



Laura Smith



- My main hobbies are tennis, art, playing video games, reading books and manga, and going to the theatre
- I love trying new things and have had so many hobbies
 - Sewing, knitting, crocheting, cross stitching, jewelry making, metal work, pottery, making stained glass art, 3D printing, MTG, Pokemon, Beyblade, Yugioh, cooking, fencing, making costumes, prop making, leather work, musical theatre, martial arts, etc.
- I run the manga reading club every week



Outline

- Overview and Definitions
- History of Particle Swarm Optimization
- Algorithm Specifications
- Deep Dive into Applications
- Implementations of PSO
- Open Issues
- Discussion
- References

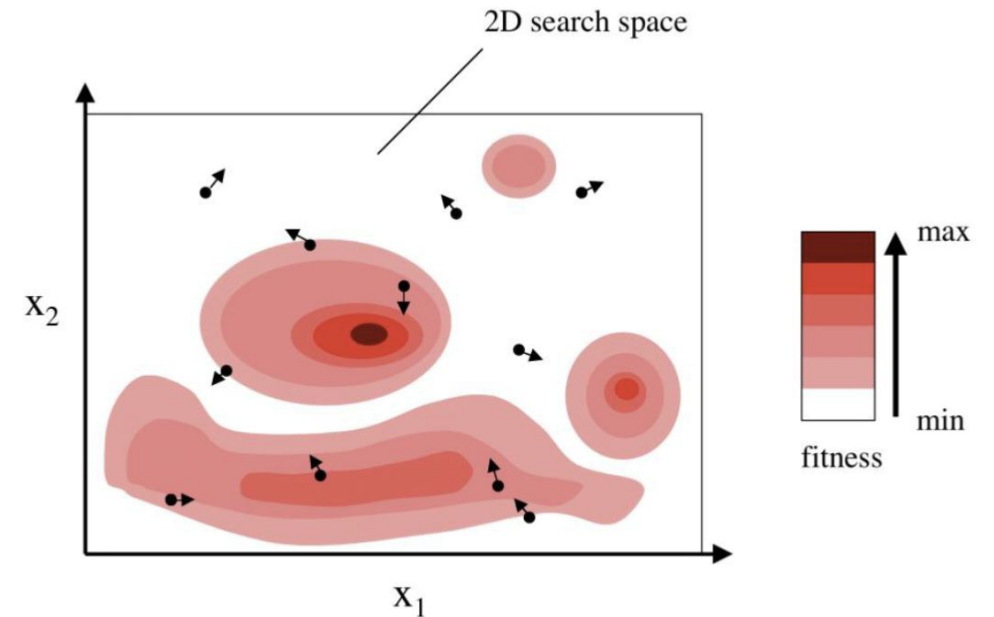
Overview and Definitions - Birds

- Particle Swarm Optimization (PSO) is an optimization algorithm inspired by **bird flocking behavior**
 - Continuous optimization search
- Model for social information sharing
 - Cooperative search style
- Combines
 - Public knowledge
 - Private knowledge



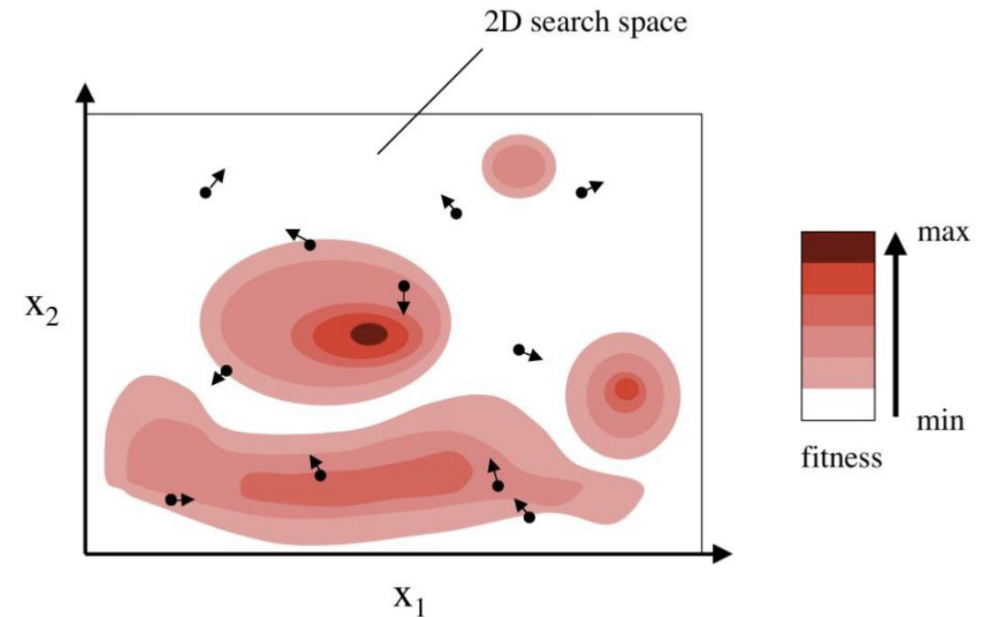
Overview and Definitions - PSO

- Search space
- Particles
 - Position
 - Velocity and momentum
 - Hyperparameters
 - Social bias
 - Cognitive bias
 - Inertia
- Neighbor relations
 - How is information shared?



Overview and Definitions - Search

- Exploration
 - Global Search
 - High exploration may never settle on a final answer
- Exploitation
 - Local Search
 - High exploitation may cause premature convergence
- Performance Metrics
 - Convergence Time
 - Fitness
 - Success Rate



Benefits of PSO

- Relatively simple to implement
- Doesn't require gradient information or continuity
 - Good for Black-box problems
- Few hyperparameters
- Highly efficient and parallelizable calculations
- Relatively fast convergence
 - Finds a “good enough” answer quickly

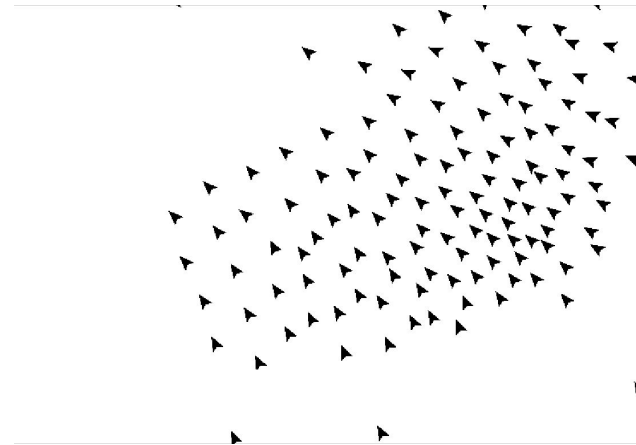
Drawbacks

- Can be difficult to transform the parameters of a problem to be solved so that it can be encoded and searched by particles
- Risk of premature convergence (local optima)
- High hyperparameter sensitivity

History

History

- **James Kennedy and Russel Eberhart** developed PSO in **1995**
- Inspired by **Craig Reynold's Boids model** showing flocking and collective motion
- Kennedy and Russel first started to add **food sources** to the model, then realized it could be used for **optimization**



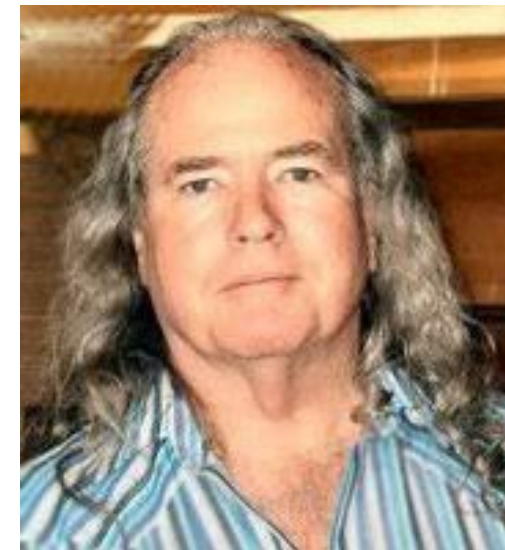
Flocking Boids



Craig W. Reynolds
Symbolics Graphics Division



Dr. Russel C. Eberhart
Purdue School of Engineering and
Technology



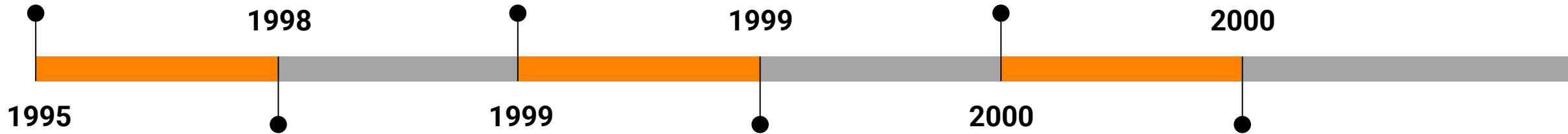
Dr. James Kennedy
Bureau of Labor Statistics

$$K = \frac{2}{|2 - \varphi - \sqrt{\varphi^2 - 4\varphi}|}$$

James Kennedy & Russell Eberhart introduce **PSO** based on social behavior and flocking

Maurice Clerc introduces a **constriction factor** to help **PSO solve faster**

P.N. Suganthan proposes a **dynamic neighborhood** where particles become neighbors when they are close to each other

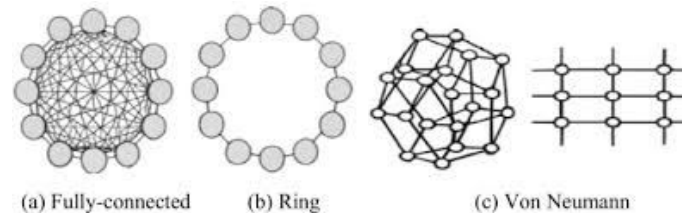


Eberhart works with **Yuhui Shi** to introduce **inertia to stabilize convergence**

Kennedy tests **static neighborhood topologies** (ring, star, von neumann,

Kennedy introduces **social stereotyping** using clustering behavior

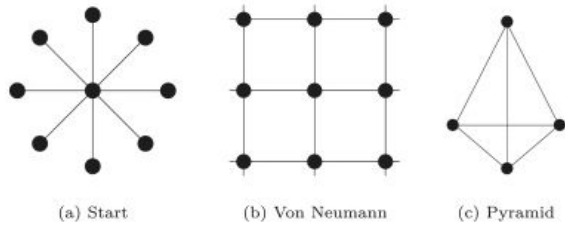
$$\omega > \frac{1}{2} (\varphi_1 + \varphi_2) - 1.$$



(a) Fully-connected

(b) Ring

(c) Von Neumann

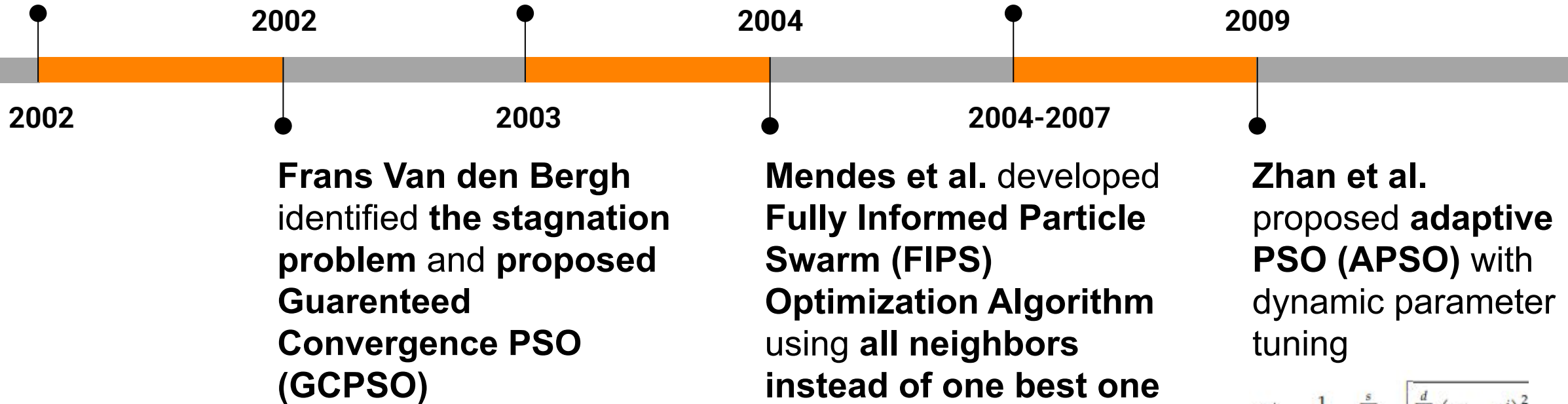


$$FDR = \frac{f(\vec{P}_t^j) - f(\vec{x}_t^i)}{|\vec{P}_t^j - \vec{x}_t^i|}$$

Kalyan Veermachaneni et al. introduced the **fitness-distance ratio (FDR)** to choose neighbors based on **solution quality and distance**

Brits, Parsopoulos, and Vrahatis introduced **niching, multi-swarm, and multimodal optimization methods**

Kennedy & Ricardo Mendes compared swarm topologies and **found von neuman performed best**



$$D_t^i = \frac{1}{s-1} \sum_{j=1, j \neq i}^s \sqrt{\sum_{d=1}^d (\bar{x}_t^i - \bar{x}_t^j)^2}$$

Modern Work

2010-2020

- **Adaptive PSO** (APSO), dynamic parameter tuning
- **Multi-objective PSO** (MOPSO) and Pareto Optimization
- **Cooperative PSO**, multi-swarm Methods
- **Niching, multimodal PSO, species-based PSO**
- **Parallel PSO, GPU implementations, big data PSO**

2020-Today

- **Adaptive and learning-based PSO**
- **Niching, multimodal, and multi-objective PSO** improvements
- **Parallel, distributed, and multi-agent PSO**
- **Speciation and diversity-preserving PSO**

Algorithm Description

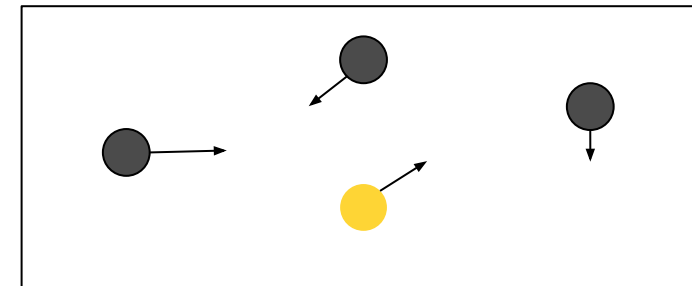
Overview

PSO is stochastic, iterative, and evolutionary.

1. Initialize
2. Step
 - a. Determines new solution candidates and new fitness scores
 - b. Update personal bests and global best
3. Repeat until some stop condition

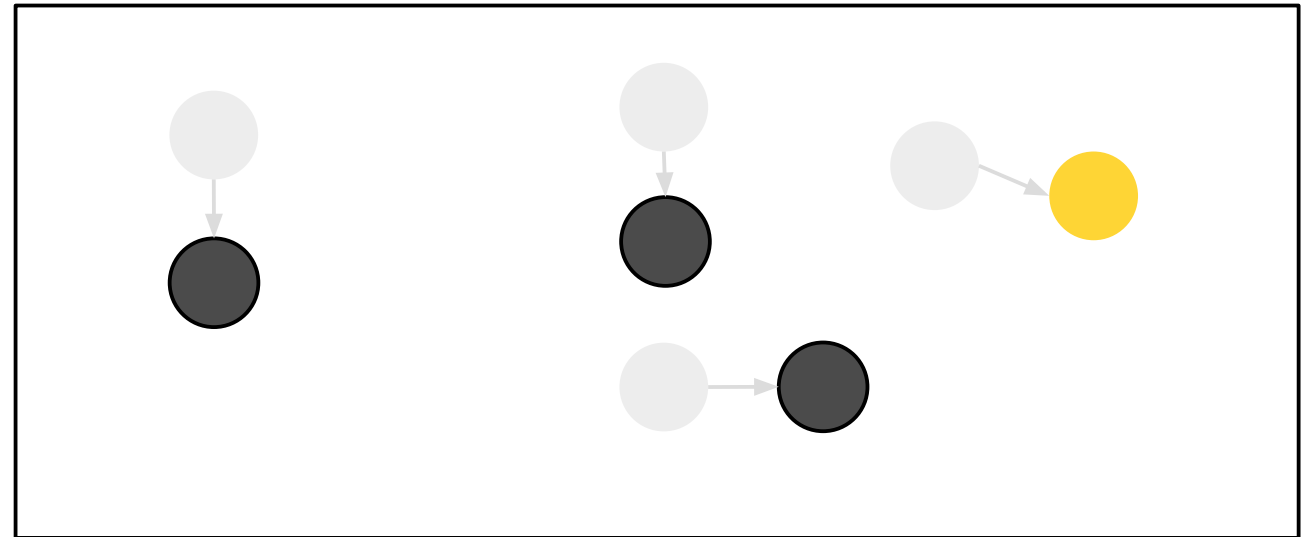
Initialization

1. We start with some number of particles, each representing a solution candidate.
2. Randomly initialize each particle's position and velocity in the solution space.
3. Calculate each particle's fitness.
 - a. This also becomes each particle's "personal best fitness".
4. Determine which particle has the best fitness to find current best solution candidate.



Step

1. Calculate new velocity.
 - a. Depends on old velocity, personal bests, and global best.
2. Add position and new velocity to determine new position.
3. Recalculate fitness
4. Update personal bests.
5. Update global best.



Calculating New Velocity

$$V_{new} = \omega V_{old} + c_1 r_1 (p_{best} - x) + c_2 r_2 (gbest - x)$$

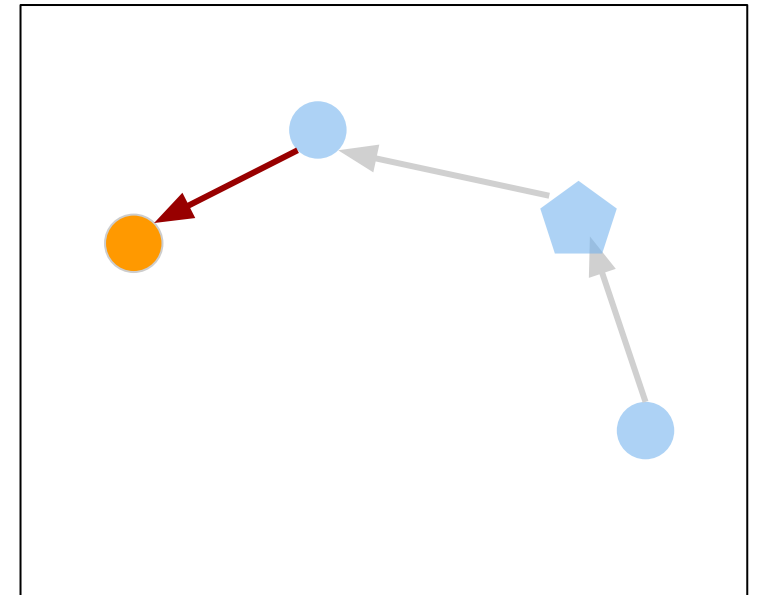
Hyperparameters:

- omega: inertia weight
- c1: cognitive weight
- c2: social weight

Calculating New Velocity

$$V_{new} = \omega V_{old} + c_1 r_1 (p_{best} - x) + c_2 r_2 (gbest - x)$$

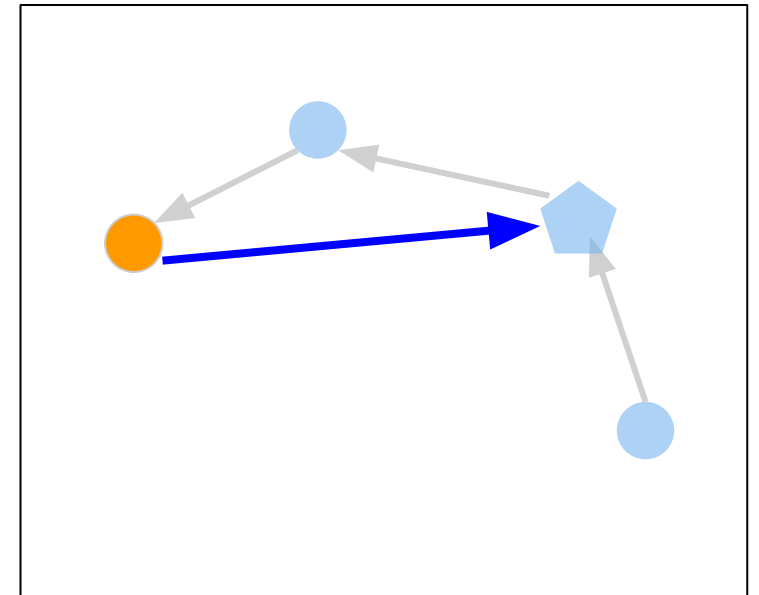
- Original random direction of exploration.
- omega can be described as a dampening factor.



Calculating New Velocity

$$V_{new} = \omega V_{old} + c_1 r_1 (p_{best} - x) + c_2 r_2 (gbest - x)$$

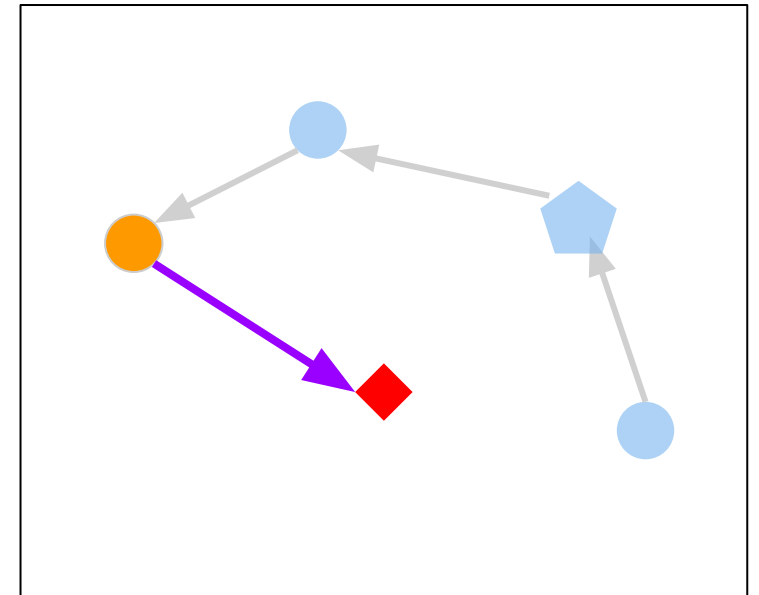
- r_1 is randomized between $[0, 1]$ each step.
- c_1 , the cognitive bias, scales tendency to return back to known personal best



Calculating New Velocity

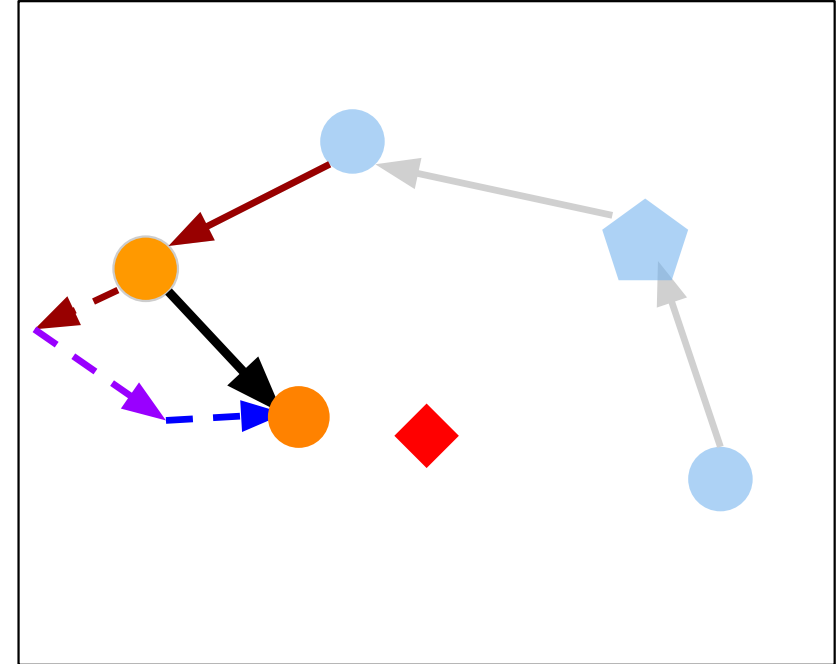
$$V_{new} = \omega V_{old} + c_1 r_1 (p_{best} - x) + c_2 r_2 (g_{best} - x)$$

- r_2 also randomized between $[0, 1]$ each step.
- c_1 , the social bias, scale tendency to go to globally known best



Calculating New Position

$$P_{new} = P_{old} + V_{new}$$



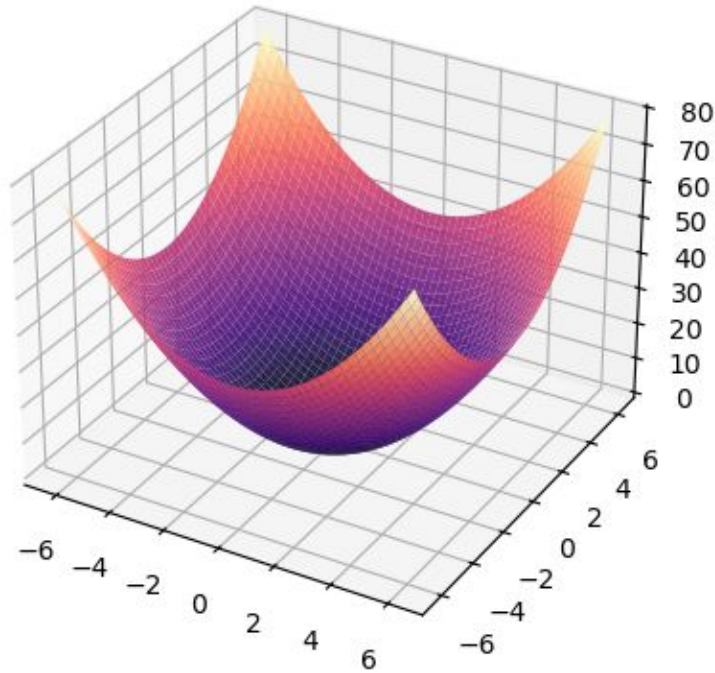
Stopping Conditions

- Fixed Iteration Count
- Global Best Stagnation
- Inter-swarm Variance

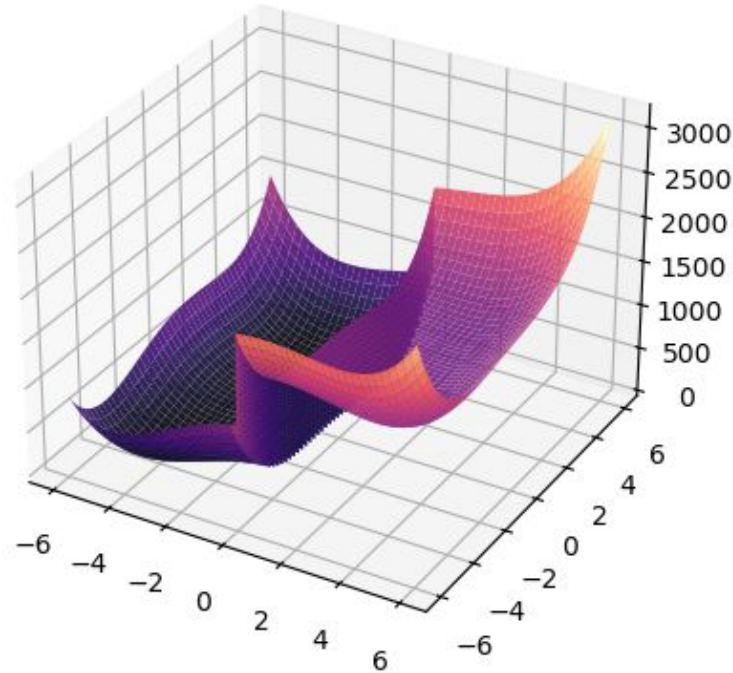
Which do we use? It depends on the application.

Applications

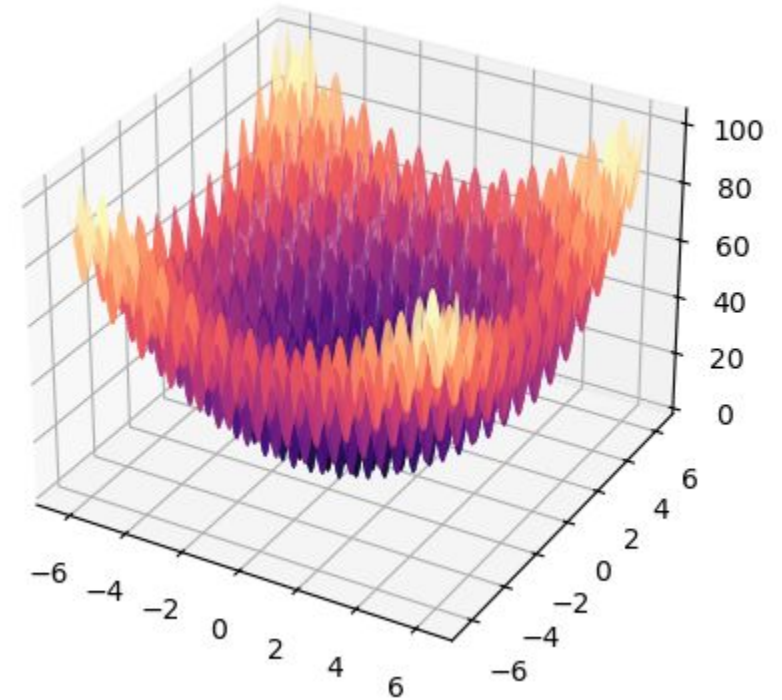
Finding Optima of Functions



trivial



discontinuous



noisy

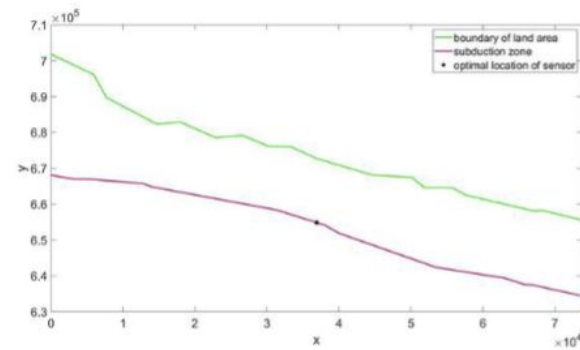
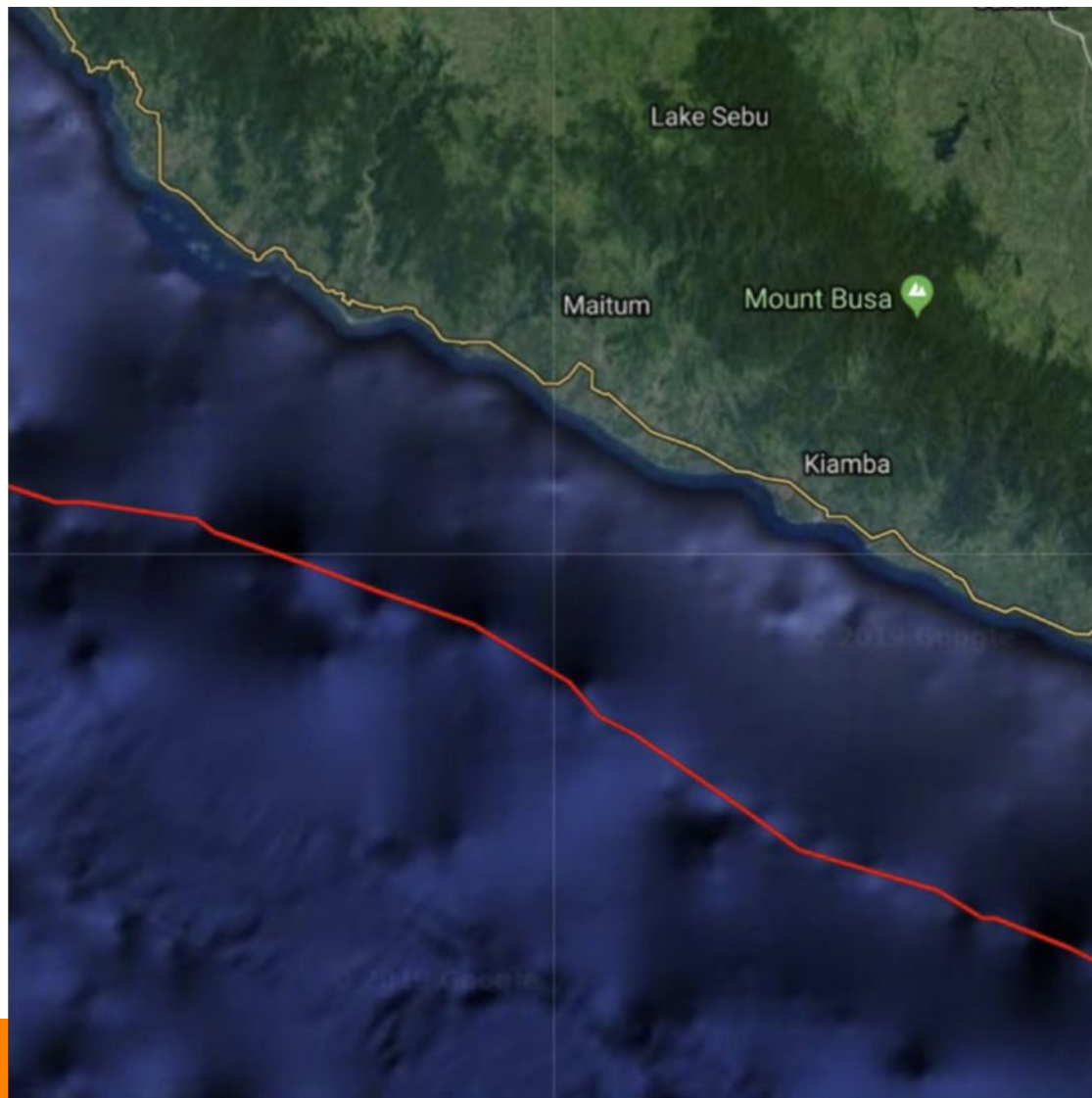
Mobile Robot Navigation

- Automated mobile robots must navigate through terrain
 - Pathing can be difficult to determine
- Can be optimized with PSO

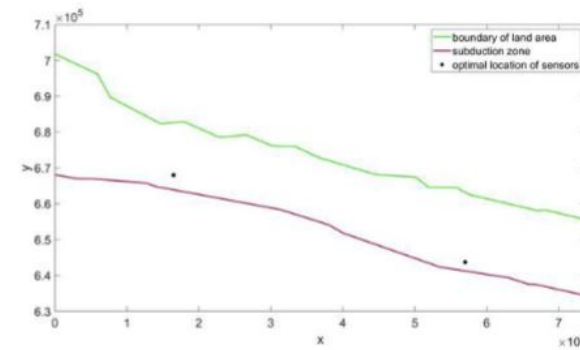
- Particle: a potential path or coordinate sequence
- Search space: physical environment



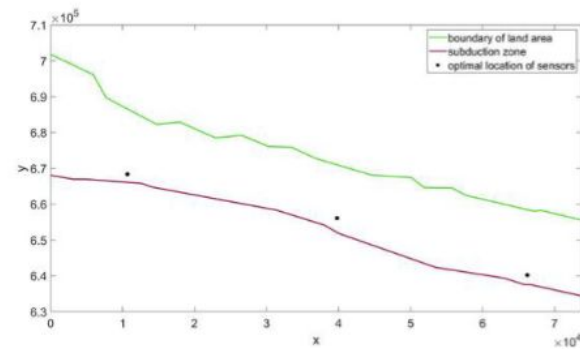
Optimal placement of tsunami sensors



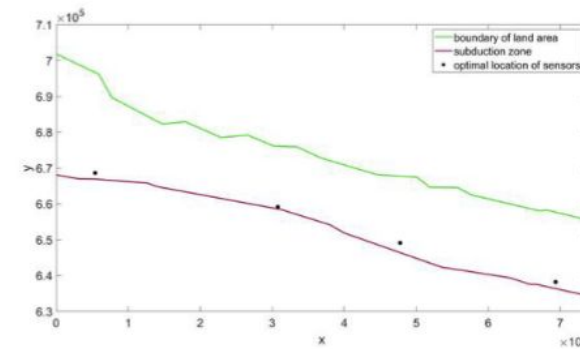
A



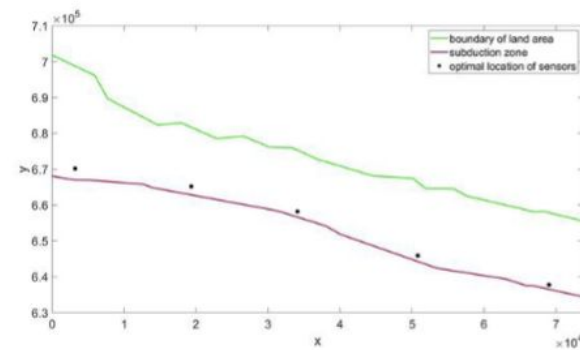
B



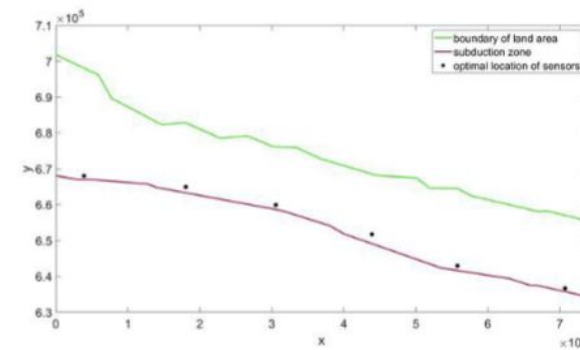
C



D



E



F

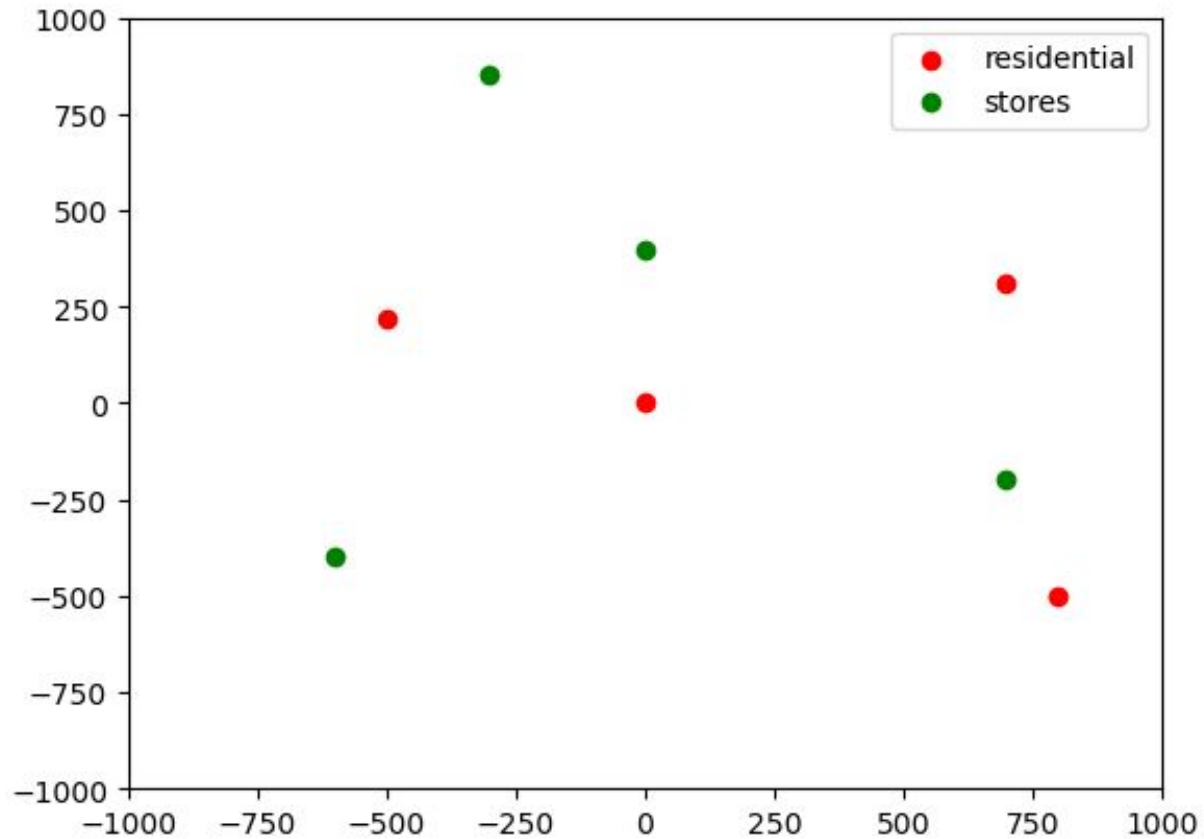
Toy Example - Warehouse Placement

Supposed we have an area of land with residential areas and stores. We want to choose locations for 3 warehouses that...

- are close to stores
- are far from residential areas
- spreads the warehouses out
 - We don't want all the warehouses in one spot

Implementation

Warehouse Placement



- Continuous 2000x2000 area
- 4 stores
- 4 residential areas

Warehouse Placement

- Converting it to a PSO problem:
 - Encode each candidate solution as a 6D vector

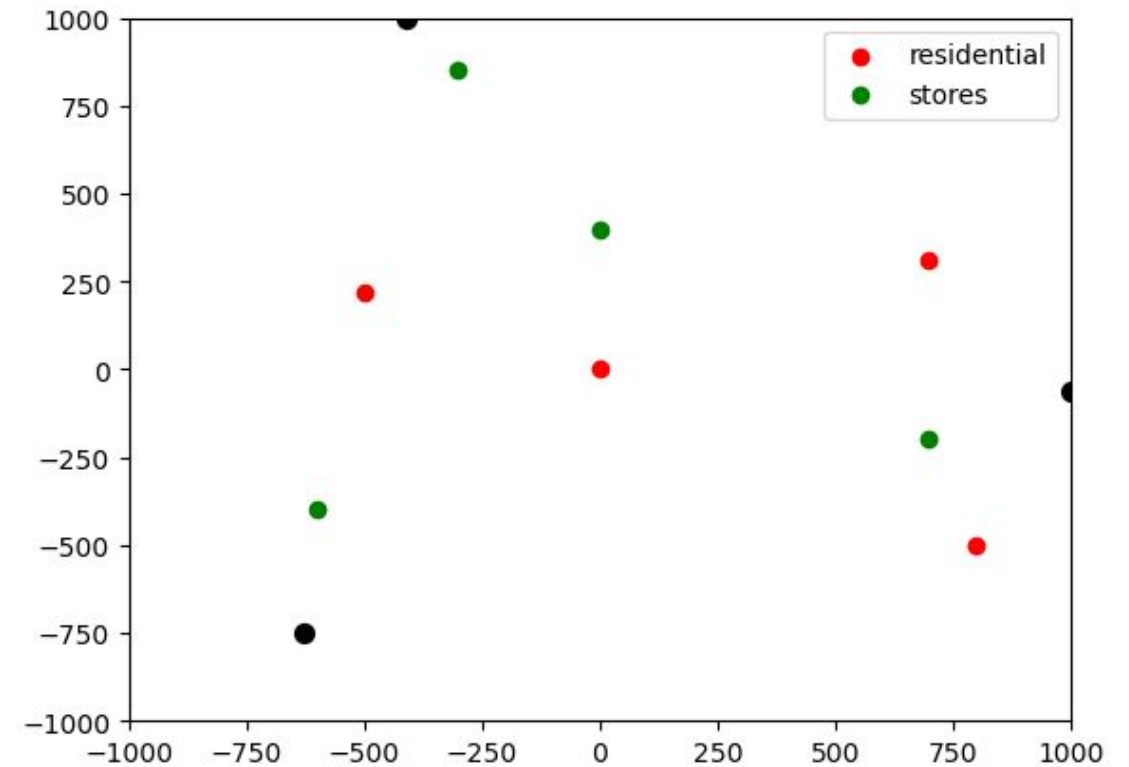
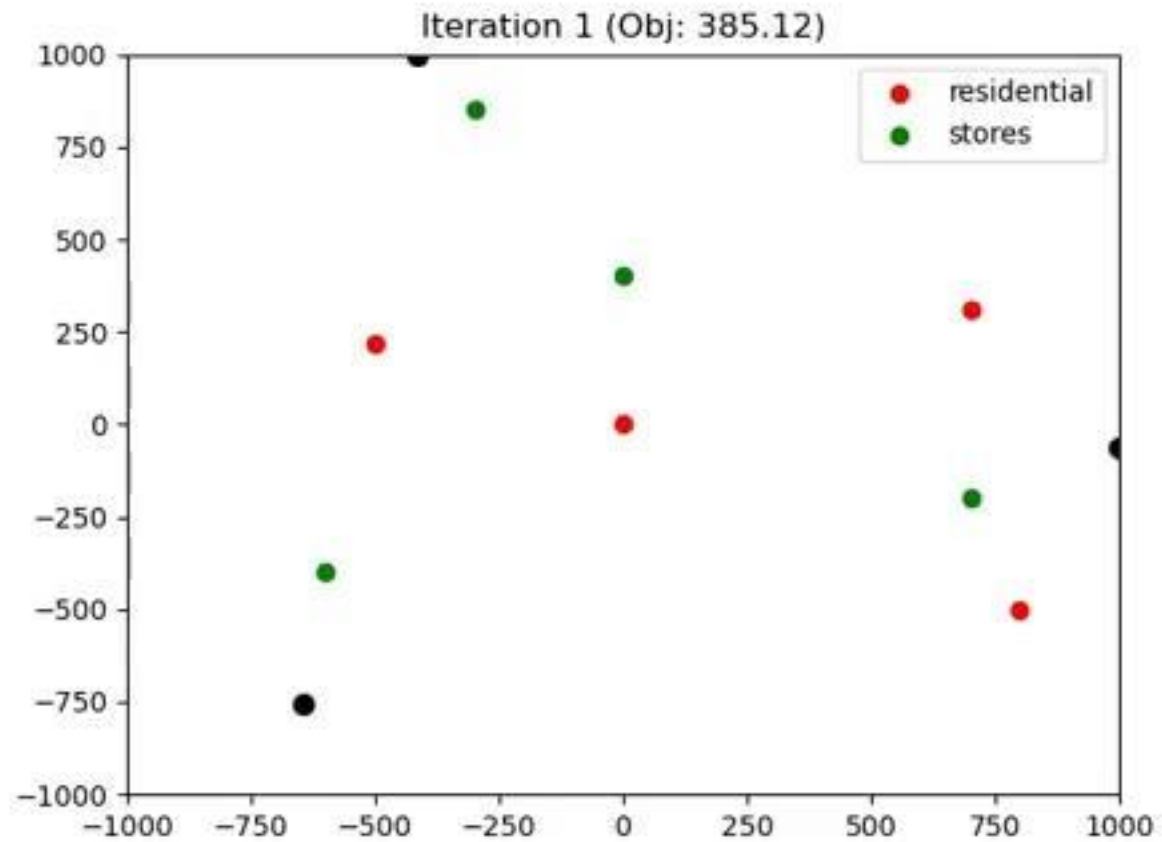
$$[x_1, y_1, x_2, y_2, x_3, y_3,]$$

- Let's start by designing a fitness function for our goals
 - Maximize min distance from residential areas.
 - Minimize max distance to stores.
 - Maximize min distance between warehouses
 - We will MAXIMIZE

$$fitness = w_1 res_{min} - w_2 store_{max} + w_3 intra_{min}$$

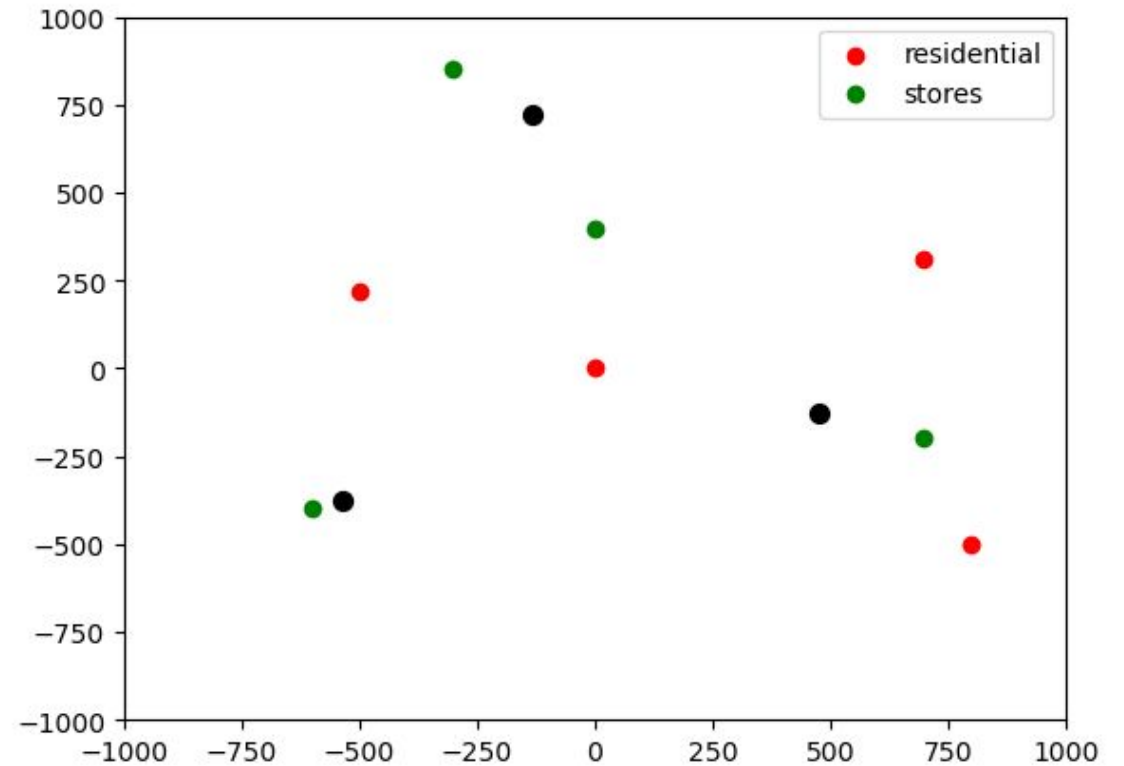
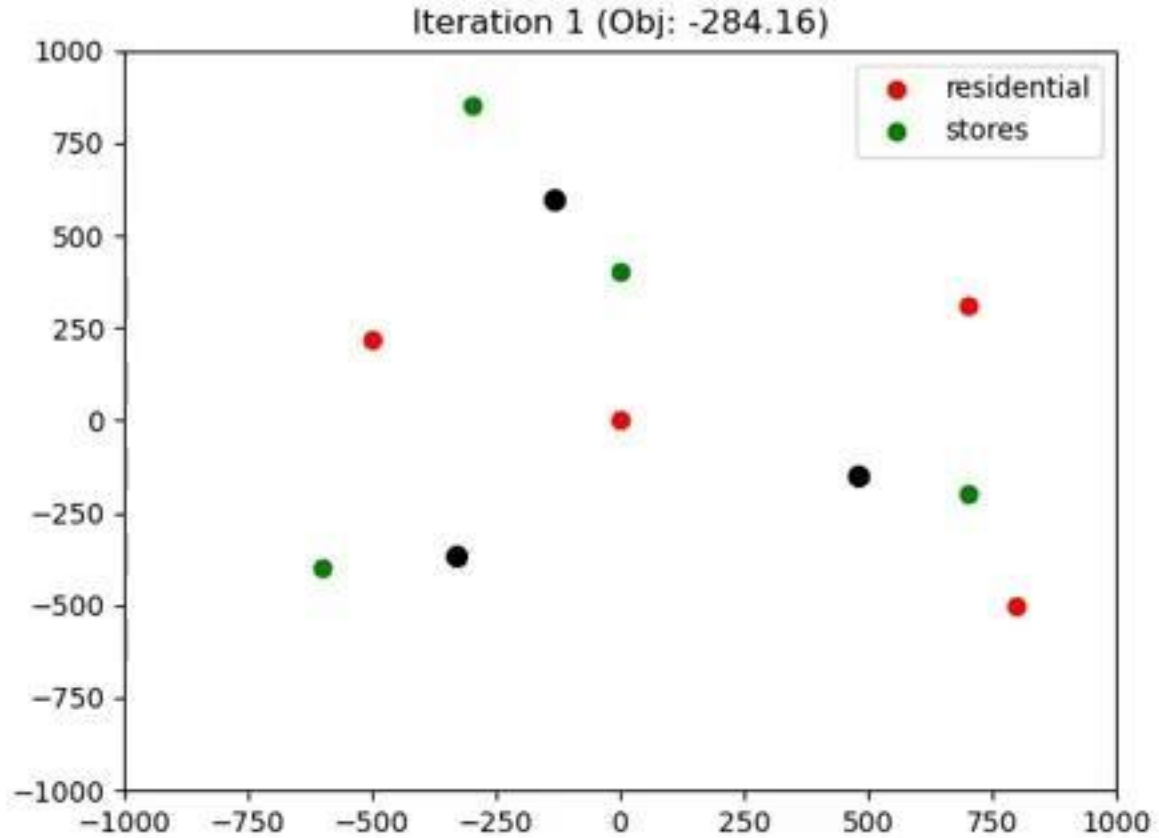
Warehouse Placement

$$w_1, w_2, w_3 = 1$$



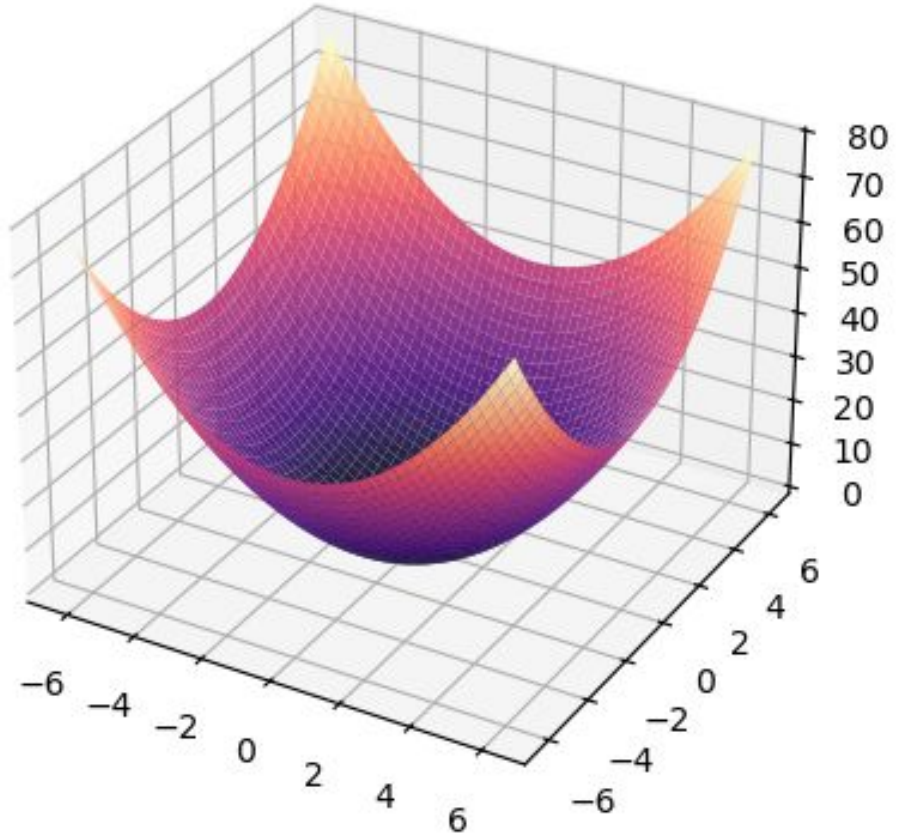
Warehouse Placement

$$w_1, w_2 = 1 \quad w_3 = 0.6$$

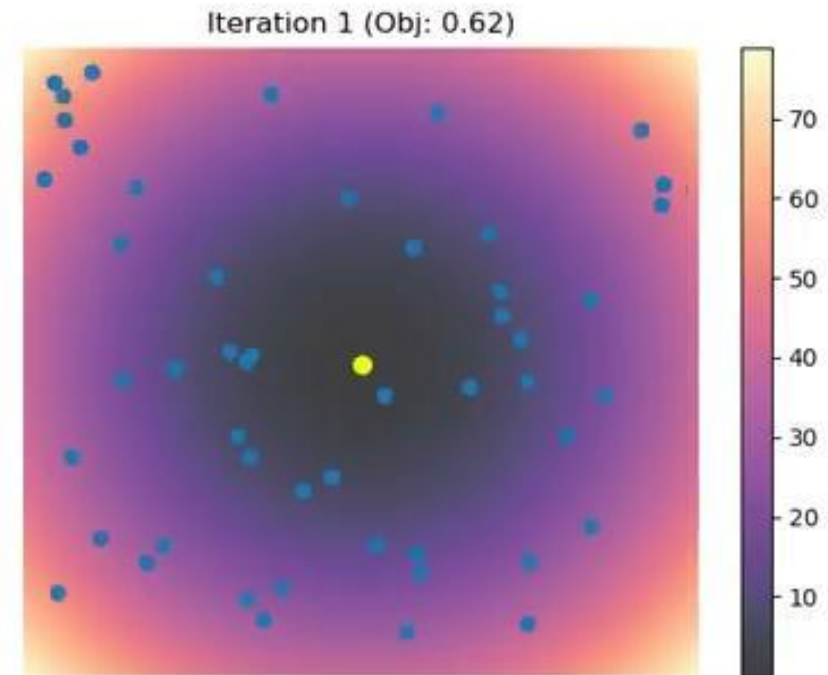


Function Optimization

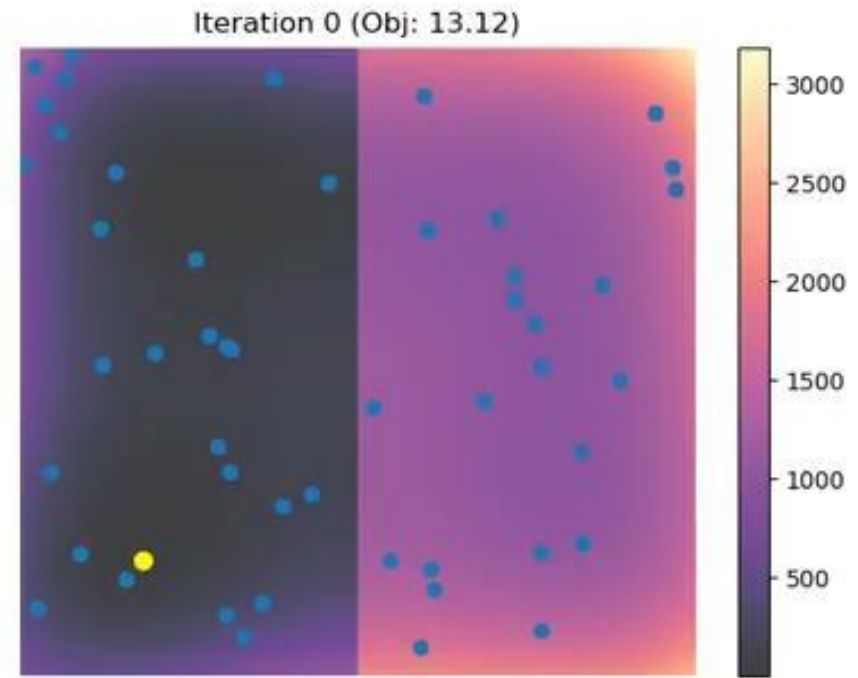
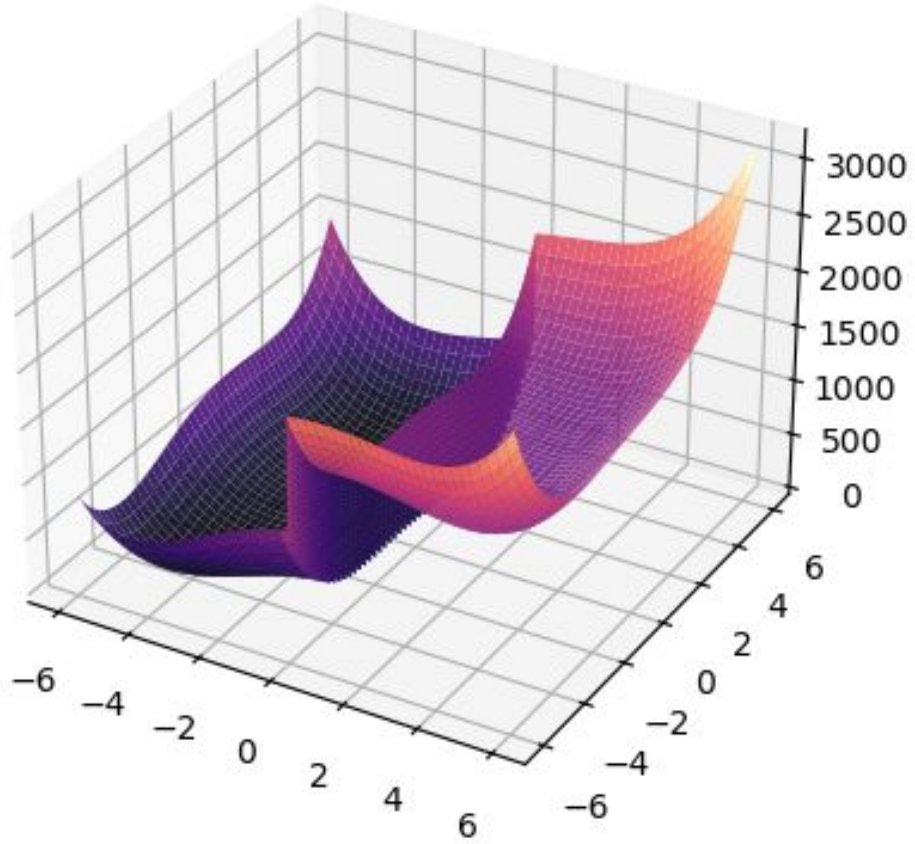
Function Optimization



Sphere Function

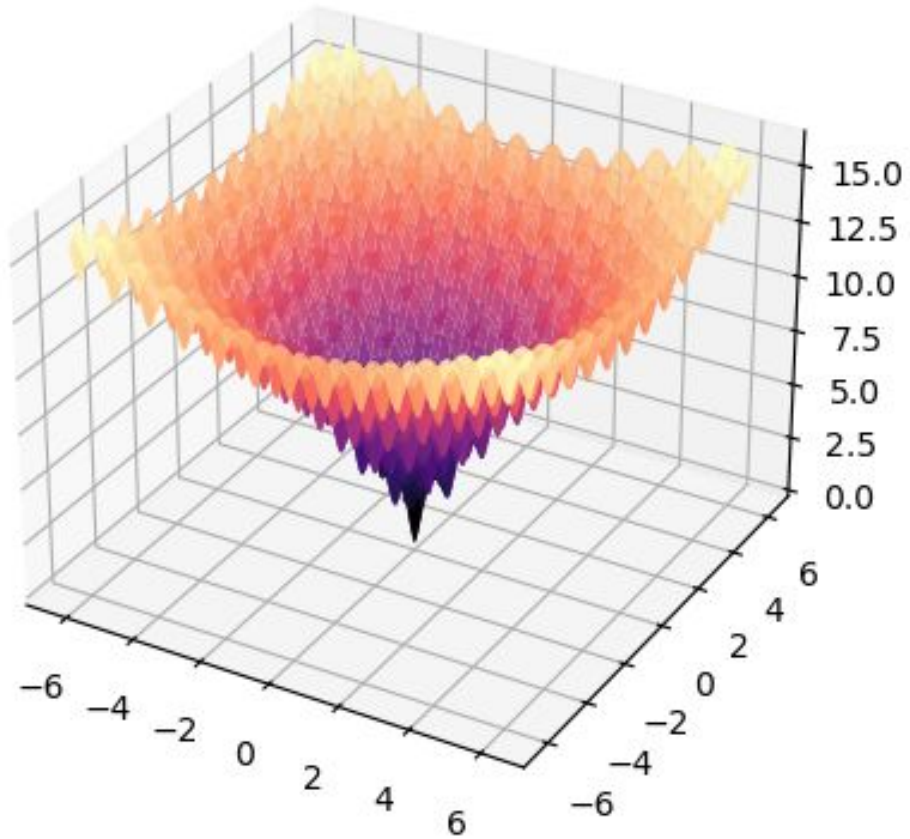


Function Optimization

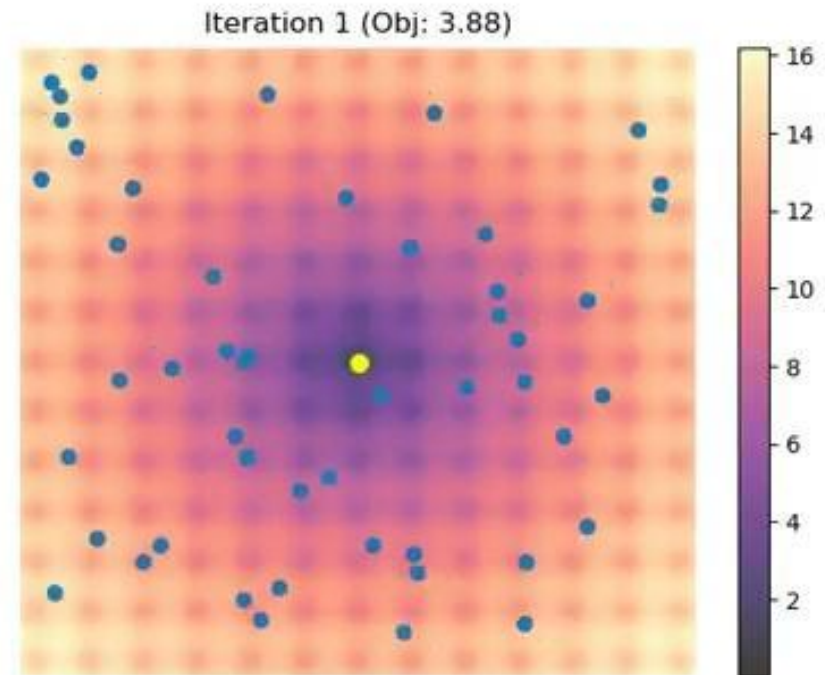


Discontinuous HimmelBlau

Function Optimization



Ackley Function



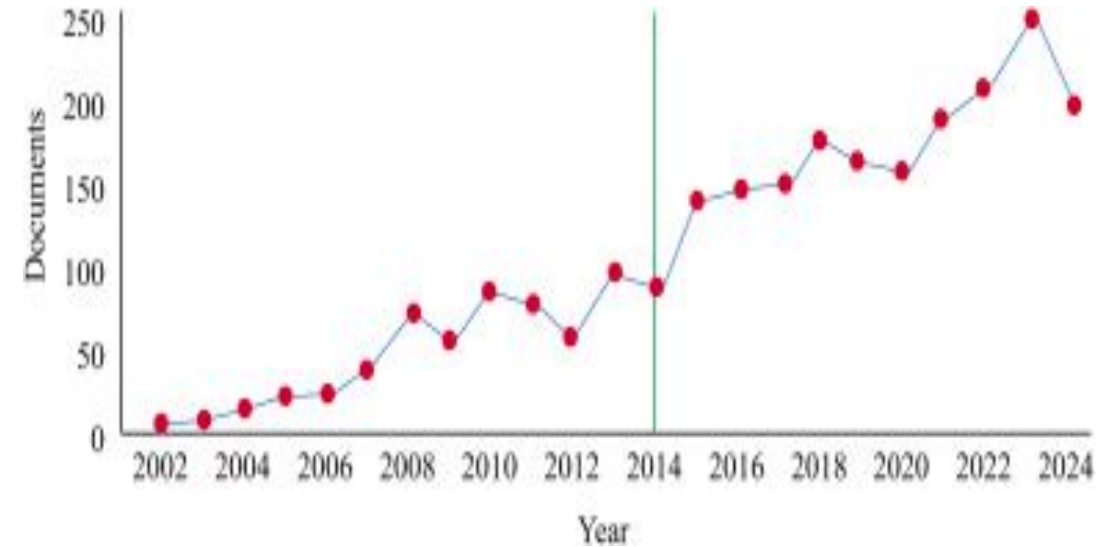
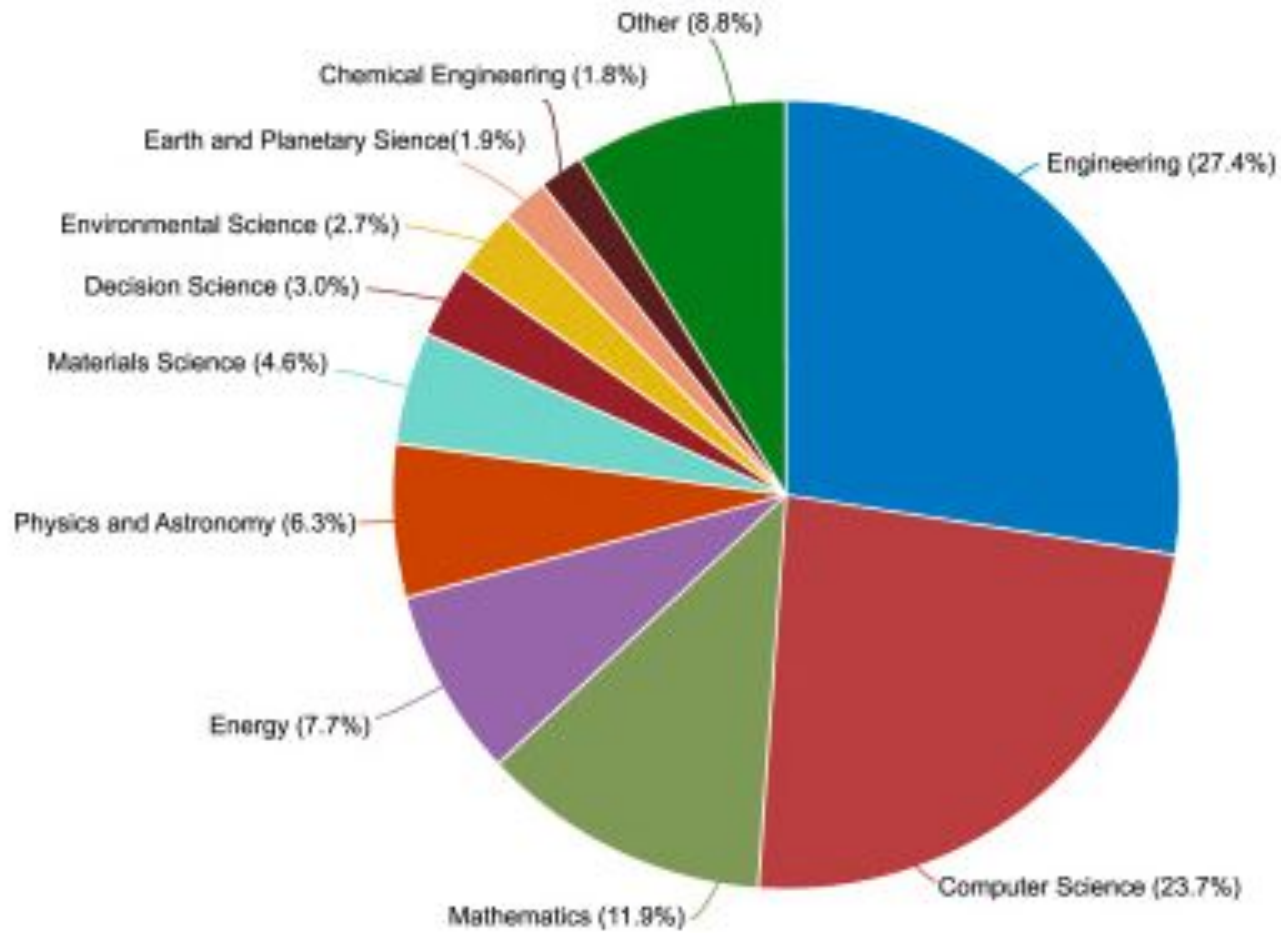
Open Issues

Algorithm

- Premature convergence
 - Local optimums
 - Especially bad in multimodal problems
- Exploration vs. Exploitation
 - Hard to balance
 - No universal setting works for all problems

Improvements

- Parameter sensitivity
 - Required manual tuning
- Stagnation
- Scalability
 - Swarm is less effective as dimensions grow
- Loss of diversity
 - Reduces ability to explore new solutions



Machine Learning & AI

- Hyperparameter tuning
- Neural architecture search
- Feature selection

Deep Learning Optimization

- Training neural networks as an alternative to gradient descent
- Weight initialization and tuning

Internet of Things (IoT)

- Resource allocation
- Network optimization
- Energy-efficient routing

Smart Grids & Energy Systems

- Power distribution optimization
- Renewable energy scheduling
- Load balancing

Robotics & Autonomous Systems

- Path planning
- Multi-agent coordination
- Swarm robotics

Bioinformatics & Healthcare

- Gene selection
- Protein structure prediction
- Medical image analysis

Cloud Computing

- Task scheduling
- Resource allocation
- Load balancing

Combinatorial Optimization

- Traveling Salesman Problem
- Scheduling problems
- Logistics optimization

Discussion

What's your favorite potential use case?

Why do you think swarm behavior is a good model for solving optimization problems?

Why do you think randomness is important in PSO?
Could the algorithm work without it?

How might PSO behave differently if applied to a changing environment?

1. What is a possible downside of high exploitation?

2. What problem does Guaranteed Convergence PSO (GCPSO) attempt to solve?

3. Which field is PSO research currently mostly concentrated in?



Quiz



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Thank You for Listening!



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