#### Classification of Dilemmas

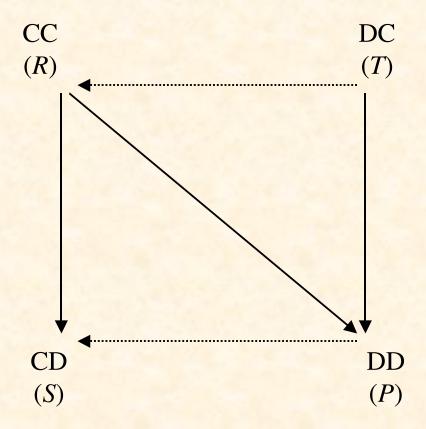
### General Payoff Matrix

|     |           |           | Bob             |  |  |
|-----|-----------|-----------|-----------------|--|--|
|     |           | cooperate | defect          |  |  |
| Ann | cooperate | CC (R)    | CD (S)          |  |  |
|     | defect    | DC (T)    | DD ( <i>P</i> ) |  |  |

## General Conditions for a Dilemma

- You always benefit if the other cooperates:
  - CC > CD and DC > DD
- You sometimes benefit from defecting:
  - DC > CC or DD > CD
- Mutual coop. is preferable to mut. def.
  - CC > DD
- Consider relative size of CC, CD, DC, DD
  - think of as permutations of R, S, T, P
  - only three result in dilemmas

#### Three Possible Orders



The three dilemmas: TRSP, RTPS, TRPS

#### The Three Dilemmas

- Chicken (TRSP)
  - DC > CC > CD > DD
  - characterized by mutual defection being worst
- Stag Hunt (*RTPS*)
  - CC > DC > DD > CD
  - better to cooperate with cooperator
- Prisoners' Dilemma (TRPS)
  - DC > CC > DD > CD
  - better to defect on cooperator

#### The Iterated Prisoners' Dilemma

and Robert Axelrod's Experiments

#### Assumptions

- No mechanism for enforceable threats or commitments
- No way to foresee a player's move
- No way to eliminate other player or avoid interaction
- No way to change other player's payoffs
- Communication only through direct interaction

#### Axelrod's Experiments

- Intuitively, expectation of future encounters may affect rationality of defection
- Various programs compete for 200 rounds
  - encounters each other and self
- Each program can remember:
  - its own past actions
  - its competitors' past actions
- 14 programs submitted for first experiment

#### IPD Payoff Matrix

|   |           | В         |        |  |
|---|-----------|-----------|--------|--|
|   |           | cooperate | defect |  |
| A | cooperate | 3, 3      | 0, 5   |  |
|   | defect    | 5, 0      | 1, 1   |  |

N.B. Unless DC + CD < 2 CC (i.e. T + S < 2 R), can win by alternating defection/cooperation

## Indefinite Number of Future Encounters

- Cooperation depends on expectation of indefinite number of future encounters
- Suppose a known finite number of encounters:
  - No reason to C on last encounter
  - Since expect D on last, no reason to C on next to last
  - And so forth: there is no reason to C at all

# Analysis of Some Simple Strategies

- Three simple strategies:
  - ALL-D: always defect
  - ALL-C: always cooperate
  - RAND: randomly cooperate/defect
- Effectiveness depends on environment
  - ALL-D optimizes local (individual) fitness
  - ALL-C optimizes global (population) fitness
  - RAND compromises

### **Expected Scores**

| playing [ | ALL-C | RAND | ALL-D | Average |
|-----------|-------|------|-------|---------|
| ALL-C     | 3.0   | 1.5  | 0.0   | 1.5     |
| RAND      | 4.0   | 2.0  | 0.5   | 2.166   |
| ALL-D     | 5.0   | 3.0  | 1.0   | 3.0     |

#### Result of Axelrod's Experiments

- Winner is Rapoport's **TFT** (Tit-for-Tat)
  - cooperate on first encounter
  - reply in kind on succeeding encounters
- Second experiment:
  - 62 programs
  - all know TFT was previous winner
  - TFT wins again

# Characteristics of Successful Strategies

- Don't be envious
  - at best TFT ties other strategies
- Be nice
  - i.e. don't be first to defect
- Reciprocate
  - reward cooperation, punish defection
- Don't be too clever
  - sophisticated strategies may be unpredictable & look random