

Solution to ECE Test #12 S09

1. The device which accepts an impulse excitation, produces a rectangular response and is used in modeling the action of a DAC is called a zero-order hold.
2. Digital filters whose impulse response goes to zero at a finite time and stays there forever after that are called finite-duration impulse response (FIR) filters
3. Digital filters whose impulse response approaches zero asymptotically as time approaches infinity are called infinite-duration impulse response (IIR) filters

4. When trying to design an approximation to an ideal differentiator ($y(t) = \frac{d}{dt}(x(t))$) using the step invariant technique we encounter a major problem.

$$Y(s) = sX(s) \Rightarrow H(s) = s \Rightarrow H_{-1}(s) = s \times 1/s = 1 \Rightarrow h_{-1}(t) = \delta(t)$$

The next step would be to sample the CT step response. But, since the step response is a CT impulse it cannot be sampled.

5. A lowpass analog filter has unity gain at a frequency of zero and a single real pole at $s = -20$. A digital filter is designed to approximate it using the impulse-invariant technique with a sampling rate of 200 Hz. Find the following.

$$h(t) = 20e^{-20t} u(t) \quad h[n] = 20(0.9048)^n u[n]$$

$$H(z) = 20 \frac{z}{z - 0.9048} \quad H_{-1}(s) = \frac{20}{s(s + 20)}$$

$$h_{-1}(t) = 20(1 - e^{-20t})u(t) \quad H_{-1}(z) = 20 \frac{z^2}{(z-1)(z-0.9048)}$$

$$H(s) = \frac{20}{s + 20} \Rightarrow h(t) = 20e^{-20t} u(t) \Rightarrow h[n] = 20e^{-20n/200} u[n] = 20(0.9048)^n u[n]$$

$$H_{-1}(s) = \frac{20}{s(s + 20)} \Rightarrow h_{-1}(t) = 20(1 - e^{-20t})u(t)$$

$$H(z) = 20 \frac{z}{z - 0.9048} \Rightarrow H_{-1}(z) = 20 \frac{z}{z - 1} \frac{z}{z - 0.9048} = 20 \frac{z^2}{z^2 - 1.9048z + 0.9048}$$

$$H_{-1}(z) = 20 \frac{z^2}{z^2 - 1.9048z + 0.9048} = 20z \times \frac{z}{z^2 - 1.9048z + 0.9048}$$

$$H_{-1}(z) = \frac{20z^2}{(z-1)(z-0.9048)} \Rightarrow \lim_{n \rightarrow \infty} h_{-1}[n] = \lim_{z \rightarrow 1} (z-1) \frac{20z^2}{(z-1)(z-0.9048)}$$

$$= \lim_{z \rightarrow 1} \frac{20z^2}{(z-0.9048)} = 210.1$$

What is the numerical final value of the digital filter to a unit sequence? 210.1

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3. The device which accepts an impulse excitation, produces a rectangular response and is used in modeling the action of a DAC is called a zero-order hold.

4. When trying to design an approximation to an ideal differentiator ($y(t) = \frac{d}{dt}(x(t))$) using the step invariant technique we encounter a major problem.

$$Y(s) = sX(s) \Rightarrow H(s) = s \Rightarrow H_{-1}(s) = s \times 1/s = 1 \Rightarrow h_{-1}(t) = \delta(t)$$

The next step would be to sample the CT step response. But, since the step response is a CT impulse it cannot be sampled.

5. A lowpass analog filter has unity gain at a frequency of zero and a single real pole at $s = -30$. A digital filter is designed to approximate it using the impulse-invariant technique with a sampling rate of 200 Hz. Find the following.

$$h(t) = 30e^{-30t} u(t) \quad h[n] = 30(0.8607)^n u[n]$$

$$H(z) = 30 \frac{z}{z - 0.8607} \quad H_{-1}(s) = \frac{30}{s(s + 30)}$$

$$h_{-1}(t) = 30(1 - e^{-30t})u(t) \quad H_{-1}(z) = 30 \frac{z^2}{(z-1)(z-0.8607)}$$

$$H(s) = \frac{30}{s + 30} \Rightarrow h(t) = 30e^{-30t} u(t) \Rightarrow h[n] = 30e^{-30n/200} u[n] = 30(0.8607)^n u[n]$$

$$H_{-1}(s) = \frac{30}{s(s + 30)} \Rightarrow h_{-1}(t) = 30(1 - e^{-30t})u(t)$$

$$H(z) = 30 \frac{z}{z - 0.8607} \Rightarrow H_{-1}(z) = 30 \frac{z}{z - 1} \frac{z}{z - 0.8607} = 30 \frac{z^2}{z^2 - 1.8607z + 0.8607}$$

$$H_{-1}(z) = 30 \frac{z^2}{z^2 - 1.8607z + 0.8607} = 30z \times \frac{z}{z^2 - 1.8607z + 0.8607}$$

$$H_{-1}(z) = \frac{30z^2}{(z-1)(z-0.8607)} \Rightarrow \lim_{n \rightarrow \infty} h_{-1}[n] = \lim_{z \rightarrow 1} (z-1) \frac{30z^2}{(z-1)(z-0.8607)}$$

$$= \lim_{z \rightarrow 1} \frac{30z^2}{(z-0.8607)} = 215.36$$

What is the numerical final value of the digital filter to a unit sequence? 215.36