Solution ofECE 316 Test 3 S11

1. Sketch a root locus for each of the diagrams below. The diagrams show the poles and zeros of the loop transfer function $T(s)$ of a feedback system.

For each system indicate whether it will be unstable at some finite positive value of the gain constant *K*

- A Unstable at some finite positive *K*
- B Stable for all finite positive *K*
C Stable for all finite positive *K*
- C Stable for all finite positive *K*
- D Unstable at some finite positive *K*
E Stable for all finite positive *K*
- E Stable for all finite positive *K*
- F Unstable at some finite positive *K*
- G Unstable at some finite positive *K*
- H Stable for all finite positive *K*
- I Stable for all finite positive *K*

2. For each stable unity-gain feedback system whose forward-path transfer function $H_1(s)$ is given below, indicate whether its error signal in response to a step and a ramp approaches zero, a finite, non-zero value or infinity as $t \to \infty$.

3. We have studied 6 methods for approximating an analog filter by a digital filter.

Impulse Invariant, Step Invariant, Finite Difference, Matched-z, Direct Substitution and Bilinear

(a) Which method(s) can be done without using any time-domain functions in the process?

Finite Difference, Matched-z, Direct Substitution and Bilinear

(b) Which method(s) squeeze(s) the entire continuous-time frequency from zero to infinity into the discrete-time radian-frequency range zero to π .

Bilinear

(c) Which two methods are almost the same, differing only by a time-domain delay?

Matched-z, Direct Substitution

(d) Which method can design an unstable digital filter while trying to approximate a stable analog filter and, if constrained to only stable designs, restricts the flexibility of the design to only certain types of filters?

Finite Difference

4. Using the bilinear method with a sampling rate of 10 samples/second find the transfer function of a digital filter that approximates an analog filter whose transfer function is

$$
H(s) = \frac{20}{s^2 + 3s + 8}.
$$

The transfer function of the digital filter can be expressed in the form

$$
H(z) = A \frac{z^2 + b_1 z + b_2}{z^2 + a_1 z + a_2}.
$$

Find the numerical values of the constants.

$$
A = \begin{array}{c} \begin{array}{c} \hline \end{array} \end{array} \quad , \ \ b_1 = \begin{array}{c} \hline \end{array} \quad , \ \ b_2 = \begin{array}{c} \hline \end{array} \end{array} \quad , \ \ a_1 = \begin{array}{c} \hline \end{array} \quad , \ \ a_2 = \begin{array}{c} \hline \end{array} \quad , \ \ a_3 = \begin{array}{c} \hline \end{array} \quad , \ \ a_4 = \begin{array}{c} \hline \end{array} \quad , \ \ a_5 = \begin{array}{c} \hline \end{array} \quad , \ \ a_6 = \begin{array}{c} \hline \end{array} \quad , \ \ a_7 = \begin{array}{c} \hline \end{array} \quad , \ \ a_8 = \begin{array}{c} \hline \end{array} \quad , \ \ a_9 = \begin{array}{c} \hline \end{array} \quad , \ \ a_1 = \begin{array}{c} \hline \end{array} \quad , \ \ a_2 = \begin{array}{c} \hline \end{array} \quad , \ \ a_3 = \begin{array}{c} \hline \end{array} \quad , \ \ a_4 = \begin{array} \hline \end{array} \quad , \ \ a_5 = \begin{array} \hline \end{array} \quad , \ \ a_6 = \begin{array} \hline \end{array} \quad , \ \ a_7 = \begin{array} \hline \end{array} \quad , \ \ a_8 = \begin{array} \hline \end{array} \quad , \ \ a_9 = \begin{array} \hline \end{array} \quad , \ \ a_1 = \begin{array} \hline \end{array} \quad , \ \ a_1 = \begin{array} \hline \end{array} \quad , \ \ a_2 = \begin{array} \hline \end{array} \quad , \ \ a_3 = \begin{array} \hline \end{array} \quad , \ \ a_4 = \begin{array} \hline \end{array} \quad , \ \ a_5 = \begin{array} \hline \end{array} \quad , \ \ a_6 = \begin{array} \hline \end{array} \quad , \ \ a_7 = \begin{array} \hline \end{array} \quad , \ \ a_8 = \begin{array} \hline \end{array} \quad , \ \ a_9 = \begin{array} \hline \end{array} \quad , \ \ a_1 = \begin{array} \hline \end{array} \quad , \ \ a_2 = \begin{array} \
$$

$$
H(z) = \frac{20}{\left(\frac{2}{T_s} \frac{z-1}{z+1}\right)^2 + 3\left(\frac{2}{T_s} \frac{z-1}{z+1}\right) + 8} = \frac{20T_s^2(z+1)^2}{4(z-1)^2 + 6T_s(z-1)(z+1) + 8T_s^2(z+1)^2}
$$

$$
H(z) = \frac{20T_s^2 z^2 + 40T_s^2 z + 20T_s^2}{4z^2 - 8z + 4 + 6T_s z^2 - 6T_s + 8T_s^2 z^2 + 16T_s^2 z + 8T_s^2} = 20T_s^2 \frac{z^2 + 2z + 1}{(4 + 6T_s + 8T_s^2)z^2 - (8 - 16T_s^2)z + 8T_s^2 - 6T_s + 4T_s^2 z + 16T_s^2 z + 16T_s^
$$

$$
H(z) = 0.2 \frac{z^2 + 2z + 1}{4.68z^2 - 7.84z + 3.48} = 0.0427 \frac{z^2 + 2z + 1}{z^2 - 1.6752z + 0.7436}
$$

- 5. Among the four analog filter types, Butterworth, Chebyshev Type 1, Chebyshev Type 2 and Elliptic, which one(s) have the following characteristics?
	- (a) Monotonic frequency response in both the passband and stopband.

Butterworth

(b) Monotonic frequency response in the passband and ripple in the stopband.

Chebyshev Type 2

(c) Monotonic frequency response in the stopband and ripple in the passband.

Chebyshev Type 1

(d) Ripple in both the passband and the stopband.

Elliptic

(e) The fastest transition from the passband to the stopband for a given filter order.

Elliptic

(f) The slowest transition from the passband to the stopband for a given filter order.

Butterworth

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E Stable for all finite positive *K*
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F Unstable at some finite positive
- F Unstable at some finite positive *K*
- G Unstable at some finite positive *K*
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2. For each stable unity-gain feedback system whose forward-path transfer function $H_1(s)$ is given below, indicate whether its error signal in response to a step and a ramp approaches zero, a finite, non-zero value or infinity as $t \rightarrow \infty$.

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(b) Which two methods are almost the same, differing only by a time-domain delay?

Matched-z, Direct Substitution

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Finite Difference

(d) Which method(s) can be done without using any time-domain functions in the process?

Finite Difference, Matched-z, Direct Substitution and Bilinear

4. Using the bilinear method with a sampling rate of 8 samples/second find the transfer function of a digital filter that approximates an analog filter whose transfer function is

$$
H(s) = \frac{20}{s^2 + 3s + 8} \, .
$$

The transfer function of the digital filter can be expressed in the form

$$
H(z) = A \frac{z^2 + b_1 z + b_2}{z^2 + a_1 z + a_2}.
$$

Find the numerical values of the constants.

$$
A = \begin{array}{c} \begin{array}{c} \hline \end{array} \end{array} \quad , \ \ b_1 = \begin{array}{c} \hline \end{array} \end{array} \quad , \ \ b_2 = \begin{array}{c} \hline \end{array} \end{array}
$$

$$
H(z) = \frac{20}{\left(\frac{2}{T_s} \frac{z-1}{z+1}\right)^2 + 3\left(\frac{2}{T_s} \frac{z-1}{z+1}\right) + 8} = \frac{20T_s^2(z+1)^2}{4(z-1)^2 + 6T_s(z-1)(z+1) + 8T_s^2(z+1)^2}
$$

$$
H(z) = \frac{20T_s^2 z^2 + 40T_s^2 z + 20T_s^2}{4z^2 - 8z + 4 + 6T_s z^2 - 6T_s + 8T_s^2 z^2 + 16T_s^2 z + 8T_s^2} = 20T_s^2 \frac{z^2 + 2z + 1}{(4 + 6T_s + 8T_s^2)z^2 - (8 - 16T_s^2)z + 8T_s^2 - 6T_s + 4T_s^2 z + 16T_s^2 z + 16T_s^
$$

$$
H(z) = 0.0641 \frac{z^2 + 2z + 1}{z^2 - 1.5897z + 0.6923}
$$

- 5. Among the four analog filter types, Butterworth, Chebyshev Type 1, Chebyshev Type 2 and Elliptic, which one(s) have the following characteristics?
	- (a) Monotonic frequency response in the passband and ripple in the stopband.

Chebyshev Type 2

(b) Monotonic frequency response in the stopband and ripple in the passband.

Chebyshev Type 1

(c) Ripple in both the passband and the stopband.

Elliptic

(d) The fastest transition from the passband to the stopband for a given filter order.

Elliptic

(e) The slowest transition from the passband to the stopband for a given filter order.

Butterworth

(f) Monotonic frequency response in both the passband and stopband.

Butterworth

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B Unstable at some finite positive
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E Stable for all finite positive *K*
- E Stable for all finite positive *K*
- F Unstable at some finite positive *K*
- G Unstable at some finite positive *K*
- H Unstable at some finite positive *K* I Unstable at some finite positive *K*
	- A B C [*s*] [*s*] [*s*] 5 5 5 0 0 0 -5 -5 -5 -8 -6 -4 -2 0 2 4 -8 -6 -4 -2 0 2 4 -8 -6 -4 -2 0 2 4 $\mathbf D$ E F[*s*] [*s*] [*s*] 5 5 5 0 0 0 -5 -5 -5 -8 -6 -4 -2 0 2 4 -8 -6 -4 -2 0 2 4 -8 -6 -4 -2 0 2 4 G H I [*s*] [*s*] [*s*] 5 5 5 ত 0 0 0 ໑ -5 -5 -5 -8 -6 -4 -2 0 2 4 -8 -6 -4 -2 0 2 4 -8 -6 -4 -2 0 2 4
-
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(c) Which method(s) squeeze(s) the entire continuous-time frequency from zero to infinity into the discrete-time radian-frequency range zero to π .

Bilinear

(d) Which two methods are almost the same, differing only by a time-domain delay?

Matched-z, Direct Substitution

4. Using the bilinear method with a sampling rate of 12 samples/second find the transfer function of a digital filter that approximates an analog filter whose transfer function is

$$
H(s) = \frac{20}{s^2 + 3s + 8} \, .
$$

The transfer function of the digital filter can be expressed in the form

$$
H(z) = A \frac{z^2 + b_1 z + b_2}{z^2 + a_1 z + a_2}.
$$

Find the numerical values of the constants.

$$
A = \begin{array}{c} \begin{array}{c} \hline \end{array} \end{array} \quad , \ \ b_1 = \begin{array}{c} \hline \end{array} \quad , \ \ b_2 = \begin{array}{c} \hline \end{array} \end{array} \quad , \ \ a_1 = \begin{array}{c} \hline \end{array} \quad , \ \ a_2 = \begin{array}{c} \hline \end{array}
$$

$$
H(z) = \frac{20}{\left(\frac{2}{T_s} \frac{z-1}{z+1}\right)^2 + 3\left(\frac{2}{T_s} \frac{z-1}{z+1}\right) + 8} = \frac{20T_s^2(z+1)^2}{4(z-1)^2 + 6T_s(z-1)(z+1) + 8T_s^2(z+1)^2}
$$

$$
H(z) = \frac{20T_s^2 z^2 + 40T_s^2 z + 20T_s^2}{4z^2 - 8z + 4 + 6T_s z^2 - 6T_s + 8T_s^2 z^2 + 16T_s^2 z + 8T_s^2} = 20T_s^2 \frac{z^2 + 2z + 1}{(4 + 6T_s + 8T_s^2)z^2 - (8 - 16T_s^2)z + 8T_s^2 - 6T_s + 4T_s^2 z + 16T_s^2 z + 16T_s^
$$

$$
H(z) = 0.0305 \frac{z^2 + 2z + 1}{z^2 - 1.7317z + 0.7805}
$$

- 5. Among the four analog filter types, Butterworth, Chebyshev Type 1, Chebyshev Type 2 and Elliptic, which one(s) have the following characteristics?
	- (a) The slowest transition from the passband to the stopband for a given filter order.

Butterworth

(b) Monotonic frequency response in both the passband and stopband.

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