

# Solution of ECE 316 Test 1 S10

1. In the filter and Bode diagram of its frequency response magnitude below, the frequency response of the filter is defined as  $H(j\omega) = \frac{V_o(j\omega)}{V_i(j\omega)}$  and the operational amplifier is ideal.

- (a) If the transfer function  $H(s)$  is expressed in the form

$$H(s) = A \frac{1}{s + 1/\tau}$$

find  $A$  and  $\tau$  expressed in terms of  $R_f$ ,  $R_i$  and  $C$ .

The transfer function is

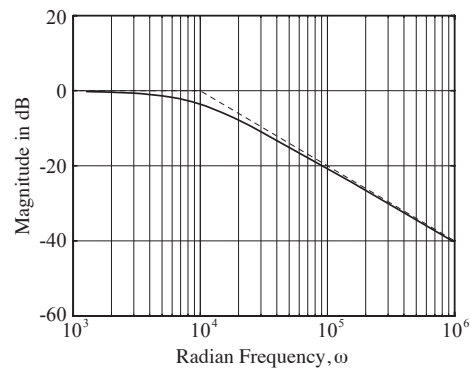
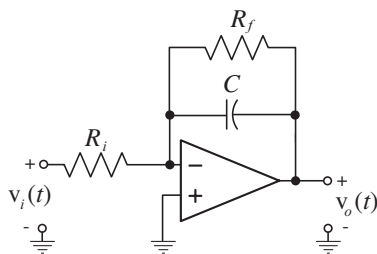
$$H(s) = -\frac{\frac{R_f / sC}{R_f + 1/sC}}{R_i} = -\frac{R_f}{sCR_f + 1} = -\frac{R_f}{R_i} \frac{1}{sCR_f + 1} = -\frac{1}{R_i C} \frac{1}{s + 1/R_f C}$$

- (b) If  $R_f = 10 \text{ k}\Omega$  find the numerical values of  $R_i$  and  $C$ .

The corner frequency is 10,000 radians/second.  $H(j\omega) = -\frac{1}{R_i C} \frac{1}{j\omega + 1/R_f C}$ . Therefore

$$1/R_f C = 10,000 \Rightarrow C = 1/10,000 R_f = 1/10^8 = 10 \text{ nF}.$$

The low-frequency gain is  $-R_f / R_i$ . Therefore, since from the Bode diagram it is also 0 dB,  $-R_f / R_i = -1$  and  $R_i = R_f = 10,000 \Omega$ .



2. A continuous-time system has a transfer function  $H(s) = \frac{s+1}{s(s+4)}$ .

- (a) At very low frequencies what slope (in dB/decade) does the Bode diagram of the magnitude frequency response approach and what phase angle (in radians) does the phase approach?

At very low frequencies  $H(j\omega) \cong \frac{1}{j4\omega}$  and the system is approximately an integrator, the slope is -20 dB/decade and the phase is  $-\pi/2$  radians.

- (b) At very high frequencies what slope (in dB/decade) does the Bode diagram of the magnitude frequency response approach and what phase angle (in radians) does the phase approach?

At very high frequencies  $H(j\omega) \cong \frac{j\omega}{(j\omega)^2} = \frac{1}{j\omega}$  and the system is again approximately an integrator, the slope is -20 dB/decade and the phase is  $-\pi/2$  radians.

Change the transfer function to  $H(s) = \frac{s-1}{s(s+4)}$  and repeat parts (a) and (b).

(a) repeated

At very low frequencies  $H(j\omega) \cong \frac{-1}{j4\omega}$  and the system is approximately an integrator, the slope is -20 dB/decade and the phase is  $\pi/2$  radians.

(b) repeated

At very high frequencies  $H(j\omega) \cong \frac{j\omega}{(j\omega)^2} = \frac{1}{j\omega}$  and the system is again approximately an integrator, the slope is -20 dB/decade and the phase is  $-\pi/2$  radians.

3. A continuous-time system has a transfer function  $H(s) = \frac{1}{s^2 + 3s + 20}$ .

- (a) At very low frequencies what slope (in dB/decade) does the Bode diagram of the magnitude frequency response approach and what phase angle (in radians) does the phase approach?

At very low frequencies  $H(j\omega) \cong \frac{1}{20}$  and the system is approximately a frequency-independent gain, the slope is 0 dB/decade and the phase is 0 radians.

- (b) At very high frequencies what slope (in dB/decade) does the Bode diagram of the magnitude frequency response approach and what phase angle (in radians) does the phase approach?

At very high frequencies  $H(j\omega) \cong \frac{1}{(j\omega)^2}$  and the system is approximately a double integrator, the slope is -40 dB/decade and the phase is  $-\pi$  radians.

4. A digital filter has a transfer function  $H(z) = \frac{z}{z - 0.5}$ . Its excitation is  $x[n] = \cos(2\pi n / N)$  and its response can be expressed in the form  $y[n] = A \cos(2\pi n / N - \theta)$ .

- (a) At what numerical radian frequency  $-\pi \leq \Omega < \pi$  is the amplitude of  $y[n]$  a maximum?

( $H(e^{j\Omega}) = H(z)|_{z \rightarrow e^{j\Omega}}$ ). (Be sure to carefully observe the limits and inequalities in  $-\pi \leq \Omega < \pi$ .)

$$H(e^{j\Omega}) = \frac{e^{j\Omega}}{e^{j\Omega} - 0.5} \Rightarrow |H(e^{j\Omega})| = \frac{1}{|e^{j\Omega} - 0.5|}$$

The maximum magnitude occurs at  $\Omega = 0$  and is  $|H(e^{j0})| = \frac{1}{|1 - 0.5|} = 2$ .

- (b) At what numerical radian frequency  $-\pi \leq \Omega < \pi$  is the amplitude of  $y[n]$  a minimum?

The maximum magnitude occurs at  $\Omega = -\pi$  and is  $|H(e^{-j\pi})| = \frac{1}{|-1 - 0.5|} = 2/3$ .

- (c) If  $N = 4$ , what is the numerical value of  $\theta$  in radians?

$$\theta = \angle H(e^{j\Omega}), \Omega = 2\pi / N = \pi / 2 \Rightarrow \theta = \angle \left( \frac{e^{j\pi/2}}{e^{j\pi/2} - 0.5} \right) = \pi / 2 - \angle(e^{j\pi/2} - 0.5)$$

$$\theta = \pi / 2 - \angle(j - 0.5) = \pi / 2 - 2.0344 = -0.4636 \text{ radians}$$

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1. In the filter and Bode diagram of its frequency response magnitude below, the frequency response of the filter is defined as  $H(j\omega) = \frac{V_o(j\omega)}{V_i(j\omega)}$  and the operational amplifier is ideal.

- (a) If the transfer function  $H(s)$  is expressed in the form

$$H(s) = A \frac{1}{s + 1/\tau}$$

find  $A$  and  $\tau$  expressed in terms of  $R_f$ ,  $R_i$  and  $C$ .

The transfer function is

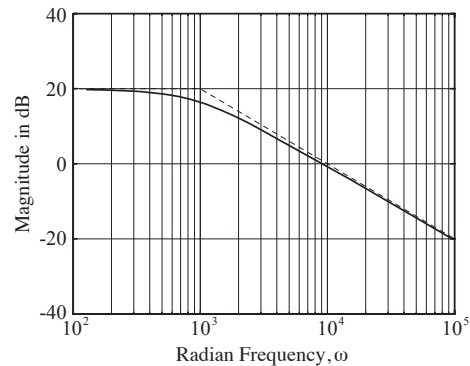
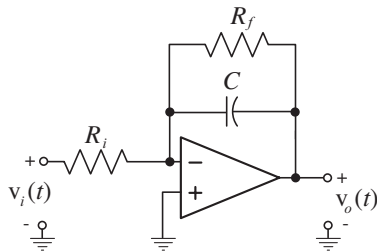
$$H(s) = -\frac{\frac{R_f / sC}{R_f + 1/sC}}{R_i} = -\frac{R_f}{sCR_f + 1} = -\frac{R_f}{R_i} \frac{1}{sCR_f + 1} = -\frac{1}{R_i C} \frac{1}{s + 1/R_f C}$$

- (b) If  $R_f = 10 \text{ k}\Omega$  find the numerical values of  $R_i$  and  $C$ .

The corner frequency is 1,000 radians/second.  $H(j\omega) = -\frac{1}{R_i C} \frac{1}{j\omega + 1/R_f C}$ . Therefore

$$1/R_f C = 1,000 \Rightarrow C = 1/1,000 R_f = 1/10^7 = 100 \text{ nF}.$$

The low-frequency gain is  $-R_f/R_i$ . Therefore, since from the Bode diagram it is also 20 dB,  $-R_f/R_i = -10$  and  $R_i = R_f/10 = 1,000 \Omega$ .



2. A continuous-time system has a transfer function  $H(s) = \frac{s+1}{(s+10)(s+4)}$ .

- (a) At very low frequencies what slope (in dB/decade) does the Bode diagram of the magnitude frequency response approach and what phase angle (in radians) does the phase approach?

At very low frequencies  $H(j\omega) \cong \frac{1}{40}$  and the system is approximately a frequency-independent gain, the slope is 0 dB/decade and the phase is 0 radians.

- (b) At very high frequencies what slope (in dB/decade) does the Bode diagram of the magnitude frequency response approach and what phase angle (in radians) does the phase approach?

At very high frequencies  $H(j\omega) \cong \frac{j\omega}{(j\omega)^2} = \frac{1}{j\omega}$  and the system is again approximately an integrator, the slope is -20 dB/decade and the phase is  $-\pi/2$  radians.

Change the transfer function to  $H(s) = \frac{s-1}{(s+10)(s+4)}$  and repeat parts (a) and (b).

(a) repeated

At very low frequencies  $H(j\omega) \cong \frac{-1}{40}$  and the system is approximately a frequency-independent gain, the slope is 0 dB/decade and the phase is  $\pm\pi$  radians.

(b) repeated

At very high frequencies  $H(j\omega) \cong \frac{j\omega}{(j\omega)^2} = \frac{1}{j\omega}$  and the system is again approximately an integrator, the slope is -20 dB/decade and the phase is  $-\pi/2$  radians.

3. A continuous-time system has a transfer function  $H(s) = \frac{s}{s^2 + 3s + 20}$ .

- (a) At very low frequencies what slope (in dB/decade) does the Bode diagram of the magnitude frequency response approach and what phase angle (in radians) does the phase approach?

At very low frequencies  $H(j\omega) \cong \frac{j\omega}{20}$  and the system is approximately a differentiator, the slope is +20 dB/decade and the phase is  $\pi/2$  radians.

- (b) At very high frequencies what slope (in dB/decade) does the Bode diagram of the magnitude frequency response approach and what phase angle (in radians) does the phase approach?

At very high frequencies  $H(j\omega) \cong \frac{1}{j\omega}$  and the system is approximately a double integrator, the slope is -20 dB/decade and the phase is  $-\pi/2$  radians.

4. A digital filter has a transfer function  $H(z) = \frac{z}{z - 0.3}$ . Its excitation is  $x[n] = \cos(2\pi n / N)$  and its response can be expressed in the form  $y[n] = A \cos(2\pi n / N - \theta)$ .

- (a) At what numerical radian frequency  $-\pi \leq \Omega < \pi$  is the amplitude of  $y[n]$  a maximum?

( $H(e^{j\Omega}) = H(z)|_{z \rightarrow e^{j\Omega}}$ ). (Be sure to carefully observe the limits and inequalities in  $-\pi \leq \Omega < \pi$ .)

$$H(e^{j\Omega}) = \frac{e^{j\Omega}}{e^{j\Omega} - 0.3} \Rightarrow |H(e^{j\Omega})| = \frac{1}{|e^{j\Omega} - 0.3|}$$

The maximum magnitude occurs at  $\Omega = 0$  and is  $|H(e^{j0})| = \frac{1}{|1 - 0.3|} = 0.1429$ .

- (b) At what numerical radian frequency  $-\pi \leq \Omega < \pi$  is the amplitude of  $y[n]$  a minimum?

The maximum magnitude occurs at  $\Omega = -\pi$  and is  $|H(e^{-j\pi})| = \frac{1}{|-1 - 0.3|} = 0.769$ .

- (c) If  $N = 4$ , what is the numerical value of  $\theta$  in radians?

$$\theta = \angle H(e^{j\Omega}), \Omega = 2\pi / N = \pi / 2 \Rightarrow \theta = \angle \left( \frac{e^{j\pi/2}}{e^{j\pi/2} - 0.3} \right) = \pi / 2 - \angle(e^{j\pi/2} - 0.3)$$

$$\theta = \pi / 2 - \angle(j - 0.3) = \pi / 2 - 1.8623 = -0.2915 \text{ radians}$$

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- (a) If the transfer function  $H(s)$  is expressed in the form

$$H(s) = A \frac{1}{s + 1/\tau}$$

find  $A$  and  $\tau$  expressed in terms of  $R_f$ ,  $R_i$  and  $C$ .

The transfer function is

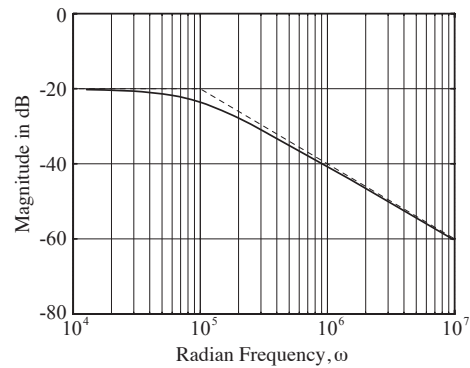
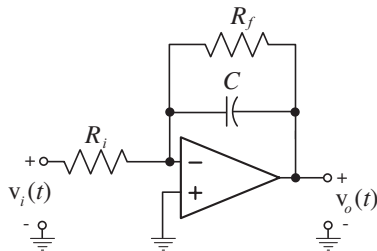
$$H(s) = -\frac{\frac{R_f / sC}{R_f + 1/sC}}{R_i} = -\frac{R_f}{sCR_f + 1} = -\frac{R_f}{R_i} \frac{1}{sCR_f + 1} = -\frac{1}{R_i C} \frac{1}{s + 1/R_f C}$$

- (b) If  $R_f = 10 \text{ k}\Omega$  find the numerical values of  $R_i$  and  $C$ .

The corner frequency is 100,000 radians/second.  $H(j\omega) = -\frac{1}{R_i C} \frac{1}{j\omega + 1/R_f C}$ . Therefore

$$1/R_f C = 100,000 \Rightarrow C = 1/100,000 R_f = 1/10^9 = 1 \text{ nF}.$$

The low-frequency gain is  $-R_f/R_i$ . Therefore, since from the Bode diagram it is also -20 dB,  $-R_f/R_i = -0.1$  and  $R_i = 10R_f = 100,000 \Omega$ .



2. A continuous-time system has a transfer function  $H(s) = \frac{s+1}{s^2(s+4)}$ .

- (a) At very low frequencies what slope (in dB/decade) does the Bode diagram of the magnitude frequency response approach and what phase angle (in radians) does the phase approach?

At very low frequencies  $H(j\omega) \cong \frac{1}{4(j\omega)^2}$  and the system is approximately a double integrator, the slope is -40 dB/decade and the phase is  $\pm\pi$  radians.

- (b) At very high frequencies what slope (in dB/decade) does the Bode diagram of the magnitude frequency response approach and what phase angle (in radians) does the phase approach?

At very high frequencies  $H(j\omega) \cong \frac{j\omega}{(j\omega)^3} = \frac{1}{(j\omega)^2}$  and the system is again approximately a double integrator, the slope is -40 dB/decade and the phase is  $\pm\pi$  radians.

Change the transfer function to  $H(s) = \frac{s-1}{s^2(s+4)}$  and repeat parts (a) and (b).

(a) repeated

At very low frequencies  $H(j\omega) \cong \frac{-1}{4(j\omega)^2}$  and the system is approximately a double-integrator, the slope is -40 dB/decade and the phase is 0 radians.

(b) repeated

At very high frequencies  $H(j\omega) \cong \frac{j\omega}{(j\omega)^3} = \frac{1}{(j\omega)^2}$  and the system is again approximately a double-integrator, the slope is -40 dB/decade and the phase is  $\pm\pi$  radians.



3. A continuous-time system has a transfer function  $H(s) = \frac{s^2}{s^2 + 3s + 20}$ .

- (a) At very low frequencies what slope (in dB/decade) does the Bode diagram of the magnitude frequency response approach and what phase angle (in radians) does the phase approach?

At very low frequencies  $H(j\omega) \cong \frac{(j\omega)^2}{20}$  and the system is approximately a double differentiator, the slope is +40 dB/decade and the phase is  $\pm\pi$  radians.

- (b) At very high frequencies what slope (in dB/decade) does the Bode diagram of the magnitude frequency response approach and what phase angle (in radians) does the phase approach?

At very high frequencies  $H(j\omega) \cong 1$  and the system is approximately a frequency-independent gain, the slope is 0 dB/decade and the phase is 0 radians.

4. A digital filter has a transfer function  $H(z) = \frac{z}{z - 0.8}$ . Its excitation is  $x[n] = \cos(2\pi n / N)$  and its response can be expressed in the form  $y[n] = A \cos(2\pi n / N - \theta)$ .

- (a) At what numerical radian frequency  $-\pi \leq \Omega < \pi$  is the amplitude of  $y[n]$  a maximum?  
 $(H(e^{j\Omega}) = H(z)|_{z \rightarrow e^{j\Omega}})$ . (Be sure to carefully observe the limits and inequalities in  $-\pi \leq \Omega < \pi$ .)

$$H(e^{j\Omega}) = \frac{e^{j\Omega}}{e^{j\Omega} - 0.8} \Rightarrow |H(e^{j\Omega})| = \frac{1}{|e^{j\Omega} - 0.8|}$$

The maximum magnitude occurs at  $\Omega = 0$  and is  $|H(e^{j0})| = \frac{1}{|1 - 0.8|} = 5$ .

- (b) At what numerical radian frequency  $-\pi \leq \Omega < \pi$  is the amplitude of  $y[n]$  a minimum?

The maximum magnitude occurs at  $\Omega = -\pi$  and is  $|H(e^{-j\pi})| = \frac{1}{|-1 - 0.8|} = 0.5556$ .

- (c) If  $N = 4$ , what is the numerical value of  $\theta$  in radians?

$$\theta = \angle H(e^{j\Omega}), \Omega = 2\pi / N = \pi / 2 \Rightarrow \theta = \angle \left( \frac{e^{j\pi/2}}{e^{j\pi/2} - 0.8} \right) = \pi / 2 - \angle(e^{j\pi/2} - 0.8)$$

$$\theta = \pi / 2 - \angle(j - 0.5) = \pi / 2 - 2.2455 = -0.6747 \text{ radians}$$