

# Solution to ECE Test #7 S08 #1

Refer to the typical feedback system below.

1. Let  $H_1(s) = K/s$  and let  $H_2(s) = s + 4$ . For what range of real values of  $K$  is this system stable?

$$H(s) = \frac{K/s}{1 + K \frac{s+4}{s}} = \frac{K}{(K+1)s + 4K} \text{ Poles are at } s = \frac{-4K}{K+1}. \text{ For stability the}$$

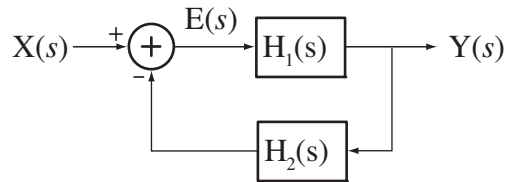
poles must have a negative real part. Since they are guaranteed real in this case they must simply be negative. If  $K$  is positive,  $-4K$  is negative and  $K+1$  is positive, making  $\frac{-4K}{K+1}$  negative. If  $K$  is negative,  $-4K$  is positive and  $K+1$  is positive if  $K$  is also greater than  $-1$ .  $K+1$  is negative if  $K$  is less than  $-1$ . Therefore, overall, for stability  $K$  must be less than  $-1$  or greater than  $0$ . The range is  $K < -1$  or  $K > 0$ .

2. Let  $H_1(s) = \frac{s}{s^2 + 9}$  and let  $H_2(s) = 1/s$ . Where are the poles of  $H(s) = Y(s)/X(s)$ ?

$$H(s) = \frac{s/(s^2 + 9)}{1 + 1/(s^2 + 9)} = \frac{s}{s^2 + 10}, \text{ Poles at } s = \pm j\sqrt{10}.$$

Is this feedback system stable or unstable?    Stable    Unstable  
 If it is unstable is it also marginally stable?    Yes    No    Does Not Apply

System is marginally stable, therefore unstable.



# Solution to ECE Test #7 S08 #1

Refer to the typical feedback system below.

1. Let  $H_1(s) = K/2s$  and let  $H_2(s) = s + 4$ . For what range of real values of  $K$  is this system stable?

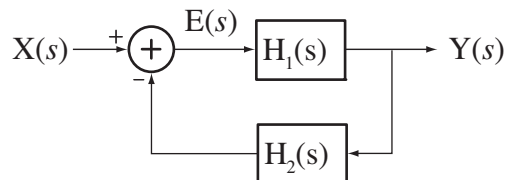
$$H(s) = \frac{K/2s}{1 + K \frac{s+4}{2s}} = \frac{K}{(K+2)s + 4K} \quad \text{Poles are at } s = \frac{-4K}{K+2}.$$

For stability the poles must have a negative real part. Since they are guaranteed real in this case they must simply be negative. If  $K$  is positive,  $-4K$  is negative and  $K+2$  is positive, making  $\frac{-4K}{K+2}$  negative. If  $K$  is negative,  $-4K$  is positive and  $K+2$  is positive if  $K$  is also greater than  $-2$ .  $K+2$  is negative if  $K$  is less than  $-2$ . Therefore, overall, for stability  $K$  must be less than  $-2$  or greater than  $0$ . The range is  $K < -2$  or  $K > 0$ .

2. Let  $H_1(s) = \frac{s}{s^2 - 9}$  and let  $H_2(s) = 1/s$ . Where are the poles of  $H(s) = Y(s)/X(s)$ ?

$$H(s) = \frac{s/(s^2 - 9)}{1 + 1/(s^2 - 9)} = \frac{s}{s^2 - 8}, \quad \text{Poles at } s = \pm\sqrt{8}.$$

Is this feedback system stable or unstable?    Stable    Unstable  
 If it is unstable is it also marginally stable?    Yes    No    Does Not Apply  
 System is unstable and not marginally stable.



# Solution to ECE Test #7 S08 #1

Refer to the typical feedback system below.

1. Let  $H_1(s) = K / (s + 1)$  and let  $H_2(s) = s + 4$ . For what range of real values of  $K$  is this system stable?

$$H(s) = \frac{K / (s + 1)}{1 + K \frac{s + 4}{s + 1}} = \frac{K}{(K + 1)s + 4K + 1} \quad \text{Poles are at } s = \frac{-(4K + 1)}{K + 1}. \quad \text{For}$$

stability the poles must have a negative real part. Since they are guaranteed real in this case they must simply be negative. If  $K$  is positive,  $-(4K + 1)$  is negative and  $K + 1$  is positive, making  $\frac{-(4K + 1)}{K + 1}$  negative. If  $K$  is less than  $-1/4$ ,  $-(4K + 1)$  is positive and  $K + 1$  is positive if  $K$  is also greater than  $-1$ .  $K + 1$  is negative if  $K$  is less than  $-1$  making  $\frac{-(4K + 1)}{K + 1}$  negative. Therefore, overall, for stability  $K$  must be less than  $-1$  or greater than  $-1/4$ . The range is  $K < -1$  or  $K > -1/4$ .

2. Let  $H_1(s) = \frac{s}{s^2 + 4}$  and let  $H_2(s) = 1/s$ . Where are the poles of  $H(s) = Y(s) / X(s)$ ?

$$H(s) = \frac{s / (s^2 + 4)}{1 + 1 / (s^2 + 4)} = \frac{s}{s^2 + 5}, \quad \text{Poles at } s = \pm j\sqrt{5}.$$

Is this feedback system stable or unstable?    Stable    Unstable  
 If it is unstable is it also marginally stable?    Yes    No    Does Not Apply

System is marginally stable, therefore unstable.

