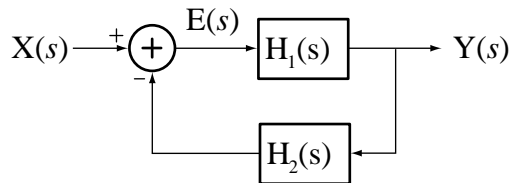


Solution of ECE 316 Test 6 S06

1. In the feedback system below $H_1(s) = \frac{s-3}{s-2}$ and $H_2(s) = K$. What range of real values of K makes this system stable?

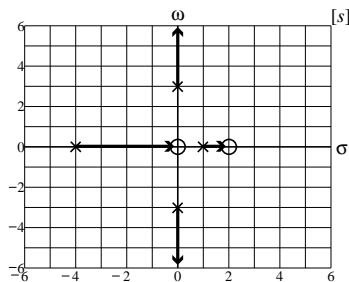
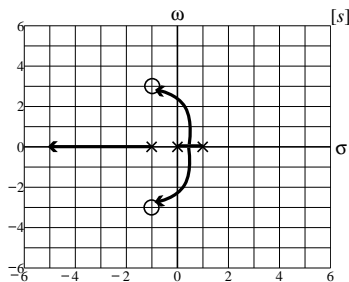
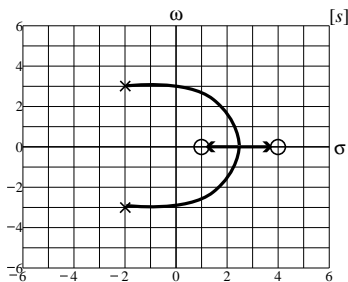


$$H(s) = \frac{\frac{s-3}{s-2}}{1 + K \frac{s-3}{s-2}} = \frac{s-3}{s-2 + K(s-3)} = \frac{s-3}{s(K+1) - 2 - 3K}$$

Poles at $s = \frac{2+3K}{K+1}$. For stability the real part of s must be negative. So we want

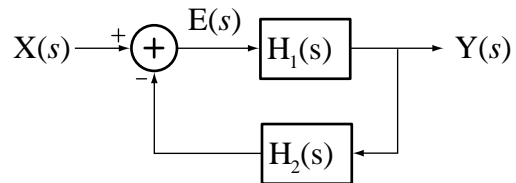
$\frac{2+3K}{K+1} < 0$. For $K > -1$, that implies that $2+3K < 0$ and that $K < -2/3$. For $K < -1$, that implies that $2+3K > 0$ and that $K > -2/3$. But $K < -1$ and $K > -2/3$ are mutually exclusive. So the only range that works is $-1 < K < -2/3$.

2. Sketch a root locus for each set of zeros and poles of the loop transfer function of a feedback system below.



Solution of ECE 316 Test 6 S06

1. In the feedback system below $H_1(s) = \frac{s-5}{s-3}$ and $H_2(s) = K$. What range of real values of K makes this system stable?



$$H(s) = \frac{\frac{s-5}{s-3}}{1 + K \frac{s-5}{s-3}} = \frac{s-5}{s-3 + K(s-5)} = \frac{s-5}{s(K+1) - 3 - 5K}$$

Poles at $s = \frac{3+5K}{K+1}$. For stability the real part of s must be negative. So we want

$\frac{3+5K}{K+1} < 0$. For $K > -1$, that implies that $3+5K < 0$ and that $K < -3/5$. For $K < -1$, that implies that $3+5K > 0$ and that $K > -3/5$. But $K < -1$ and $K > -3/5$ are mutually exclusive. So the only range that works is $-1 < K < -3/5$.

2. Sketch a root locus for each set of zeros and poles of the loop transfer function of a feedback system below.

