

# Solution of ECE 316 Test 4 Su07

1. A stable digital filter has a transfer function with one real zero and one real pole

$$H(z) = \frac{z-a}{z-b}, \quad -1 < a < 1, \quad -1 < b < 1.$$

Its frequency response  $H(e^{j\Omega})$  has the following magnitudes at two discrete-time radian frequencies  $\Omega$ .

$\Omega$	0	$\pi$
$ H(e^{j\Omega}) $	0.3889	6.5

What are the numerical values of  $a$  and  $b$ ?

$a =$  \_\_\_\_\_  $b =$  \_\_\_\_\_

$$H(z) = \frac{z-a}{z-b}$$
$$|H(e^{j0})| = \left| \frac{1-a}{1-b} \right| = 0.3889$$

Since both  $1-a$  and  $1-b$  must be positive,

$$|H(e^{j0})| = \frac{1-a}{1-b} = 0.3889 \Rightarrow (1-a) = 0.3889(1-b)$$
$$a = 1 - 0.3889(1-b) = 0.6111 + 0.3889b$$

$$|H(e^{j\pi})| = \left| \frac{-1-a}{-1-b} \right| = 6.5$$

Since both  $-1-a$  and  $-1-b$  must be negative,

$$|H(e^{j\pi})| = \frac{-1-a}{-1-b} = 6.5 \Rightarrow (1+a) = 6.5(1+b) \Rightarrow 1.6111 + 0.3889b = 6.5 + 6.5b$$

$$6.111b = -4.889 \Rightarrow b = -0.8 \Rightarrow a = 0.3$$

$a = 0.3$  and  $b = -0.8$ .

2. A discrete-time feedback system has a forward-path transfer function  $H_1(z) = K$  and a feedback-path transfer function  $H_2(z) = 3(1 + 2z^{-1})$ . For what range of real values of  $K$  is this system stable?

$$H(z) = \frac{K}{1 + 3K(1 + 2z^{-1})} = \frac{Kz}{z + 3Kz + 6K} = \frac{Kz}{z(1 + 3K) + 6K}$$

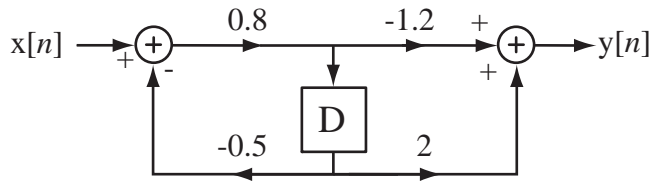
The poles are at

$$z(1 + 3K) + 6K = 0 \Rightarrow z = \frac{-6K}{1 + 3K}$$

For stability  $\left| \frac{-6K}{1 + 3K} \right| < 1$ . The transition values for  $K$  between stability

and instability are at  $\frac{-6K}{1 + 3K} = 1$  and at  $\frac{-6K}{1 + 3K} = -1$  which produce  $K$  values of  $K = 1/3$  and  $-1/9$ . So the  $K$  range for stability is  $-1/9 < K < 1/3$ .

3. If the system below is excited by a unit impulse, what are the numerical values of  $y[0]$ ,  $y[1]$ ,  $y[2]$  and  $y[7]$ ?



Let  $y_1[n]$  be the output signal of the delay element. Then

$$z Y_1(z) / 0.8 = X(z) + 0.5 Y_1(z)$$

and

$$-1.2z Y_1(z) + 2 Y_1(z) = Y(z)$$

Then

$$\frac{-1.2z + 2}{1.25z - 0.5} X(z) = Y(z) \Rightarrow H(z) = \frac{-1.2z + 2}{1.25z - 0.5} = -0.96 \frac{z - 1.67}{z - 0.4}$$

$$h[n] = -0.96 \left\{ (0.4)^n u[n] - 1.67 (0.4)^{n-1} u[n-1] \right\}$$

$$y[0] = \underline{\hspace{2cm}} \quad y[1] = \underline{\hspace{2cm}}$$

$$y[2] = \underline{\hspace{2cm}} \quad y[7] = \underline{\hspace{2cm}}$$

$$y[0] = -0.96 \quad y[1] = 1.2192$$

$$y[2] = 0.4877 \quad y[7] = 0.004994$$

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Its frequency response  $H(e^{j\Omega})$  has the following magnitudes at two discrete-time radian frequencies  $\Omega$ .

$\Omega$	$0$	$\pi$
$ H(e^{j\Omega}) $	$2$	$0.3333$

What are the numerical values of  $a$  and  $b$ ?

$a =$  \_\_\_\_\_  $b =$  \_\_\_\_\_

$$H(z) = \frac{z-a}{z-b}$$

$$|H(e^{j0})| = \left| \frac{1-a}{1-b} \right| = 2$$

Since both  $1-a$  and  $1-b$  must be positive,

$$\left| \frac{1-a}{1-b} \right| = \frac{1-a}{1-b} = 2 \Rightarrow (1-a) = 2(1-b)$$

$$a = 1 - 2(1-b) = -1 + 2b$$

$$\left| H(e^{j\pi}) \right| = \left| \frac{-1-a}{-1-b} \right| = 0.3333$$

Since both  $-1-a$  and  $-1-b$  must be negative,

$$\left| H(e^{j\pi}) \right| = \frac{-1-a}{-1-b} = 0.3333 \Rightarrow (1+a) = 0.3333(1+b) \Rightarrow 2b = 0.3333 + 0.3333b$$

$$1.6667b = 0.3333 \Rightarrow b = 0.2 \Rightarrow a = -0.6$$

$a = -0.6$  and  $b = 0.2$ .

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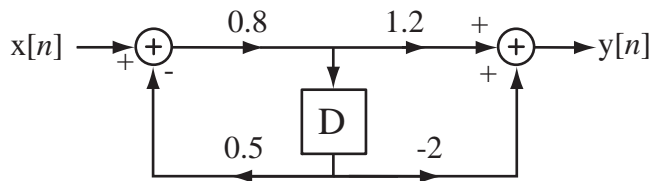
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and instability are at  $\frac{-6K}{1 + 2K} = 1$  and at  $\frac{-6K}{1 + 2K} = -1$  which produce  $K$  values of  $K = 1/4$  and  $-1/8$ . So the  $K$  range for stability is  $-1/8 < K < 1/4$ .

3. If the system below is excited by a unit impulse, what are the numerical values of  $y[0]$ ,  $y[1]$ ,  $y[2]$  and  $y[7]$ ?



Let  $y_1[n]$  be the output signal of the delay element. Then

$$z Y_1(z) / 0.8 = X(z) - 0.5 Y_1(z)$$

and

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Then

$$\frac{1.2z - 2}{1.25z + 0.5} X(z) = Y(z) \Rightarrow H(z) = \frac{1.2z - 2}{1.25z + 0.5} = 0.96 \frac{z - 1.67}{z + 0.4}$$

$$h[n] = 0.96 \left\{ (-0.4)^n u[n] - 1.67 (-0.4)^{n-1} u[n-1] \right\}$$

$$y[0] = \underline{\hspace{2cm}} \quad y[1] = \underline{\hspace{2cm}}$$

$$y[2] = \underline{\hspace{2cm}} \quad y[7] = \underline{\hspace{2cm}}$$

$$y[0] = 0.96 \quad y[1] = -1.9872$$

$$y[2] = 0.79488 \quad y[7] = -0.0081396$$