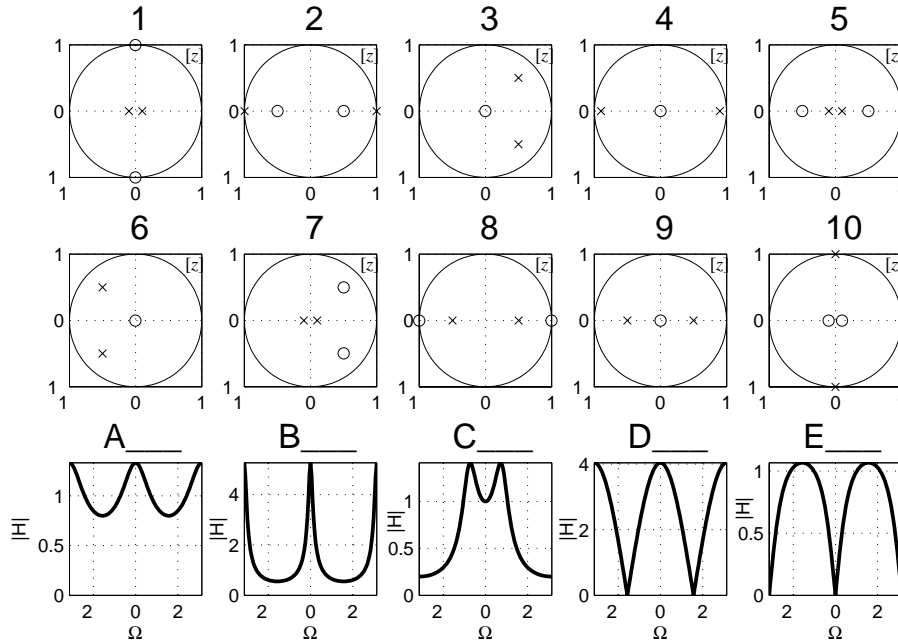


# Solution to ECE Test #11 S09

1. Write in the space provided the number of the pole-zero plot which matches each magnitude frequency response graph.



A-9, B-4, C-3, D-1, E-8

2. A DT feedback system has a forward path transfer function  $H_1(z) = \frac{Kz}{z-0.5}$  and a feedback path transfer function  $H_2(z) = 4z^{-1}$ . For what range of values of  $K$  is the system stable?

$$H(z) = \frac{\frac{Kz}{z-0.5}}{1 + \frac{Kz}{z-0.5} \cdot \frac{4}{z}} = \frac{Kz^2}{z^2 - 0.5z + 4Kz} = \frac{Kz}{z + 4K - 0.5}$$

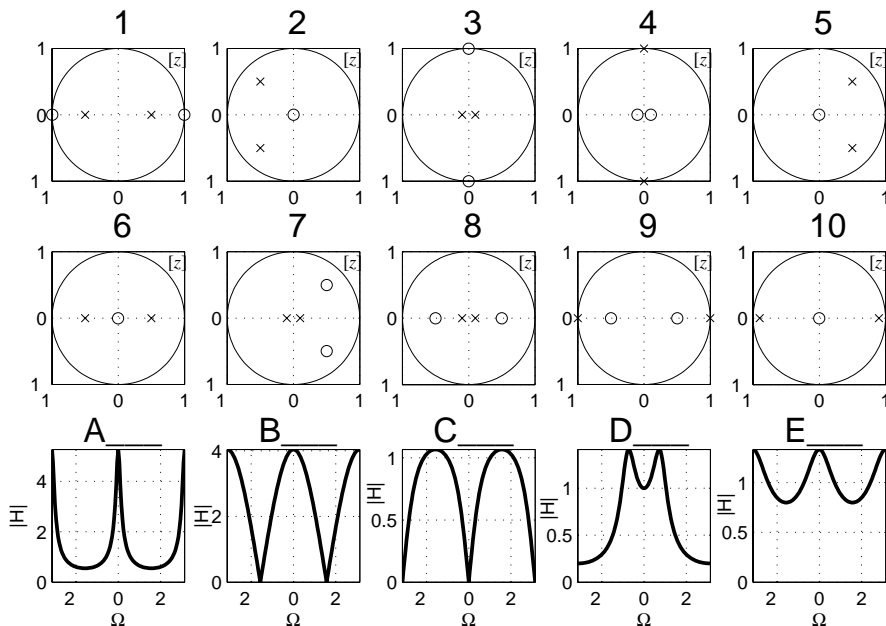
$$z + 4K - 0.5 = 0 \Rightarrow z = 0.5 - 4K$$

For stability,

$$|0.5 - 4K| < 1 \Rightarrow -1/8 < K < 3/8$$

# Solution to ECE Test #11 S09

1. Write in the space provided the number of the pole-zero plot which matches each magnitude frequency response graph.



A-10, B-3, C-1, D-5, E-6

2. A DT feedback system has a forward path transfer function  $H_1(z) = \frac{Kz}{z+0.5}$  and a feedback path transfer function  $H_2(z) = 2z^{-1}$ . For what range of values of  $K$  is the system stable?

$$H(z) = \frac{Kz}{z+0.5} \cdot \frac{2}{z} = \frac{2Kz}{z^2 + 0.5z + 2Kz} = \frac{2Kz}{z^2 + 0.5z + 2Kz}$$

$$z + 2K + 0.5 = 0 \Rightarrow z = 0, -0.5 - 2K$$

For stability,

$$|-0.5 - 2K| < 1 \Rightarrow -3/4 < K < 1/4$$